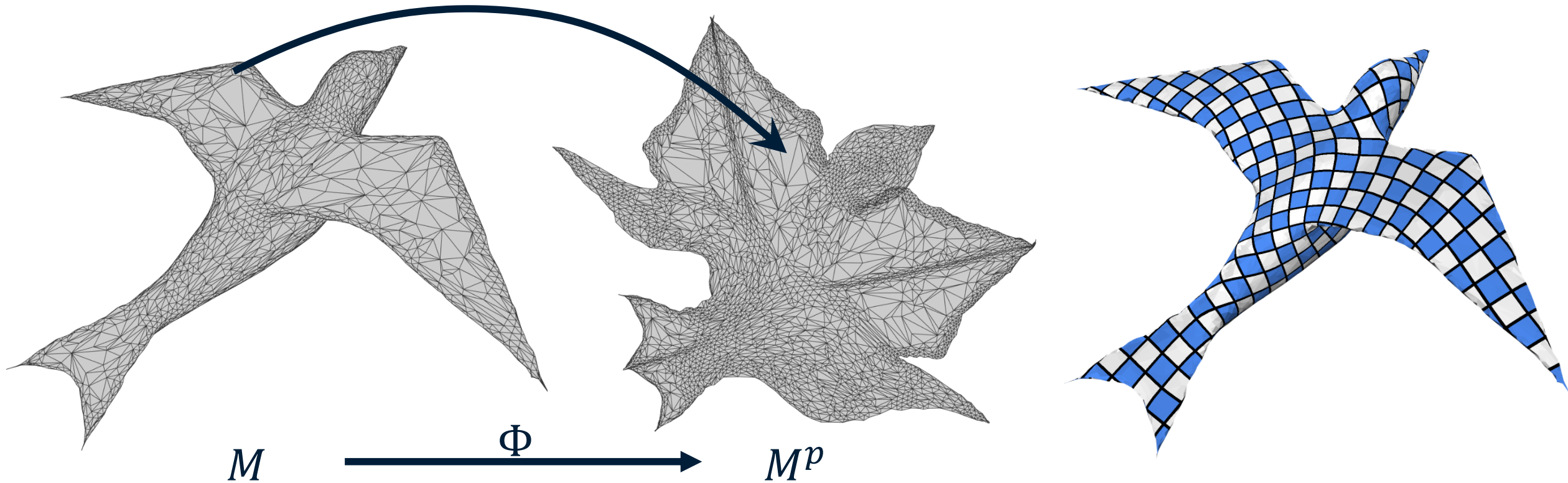


# Progressive Parameterizations

Ligang Liu, Chunyang Ye, **Ruiqi Ni**, Xiao-Ming Fu

University of Science and Technology of China

# Parameterizations

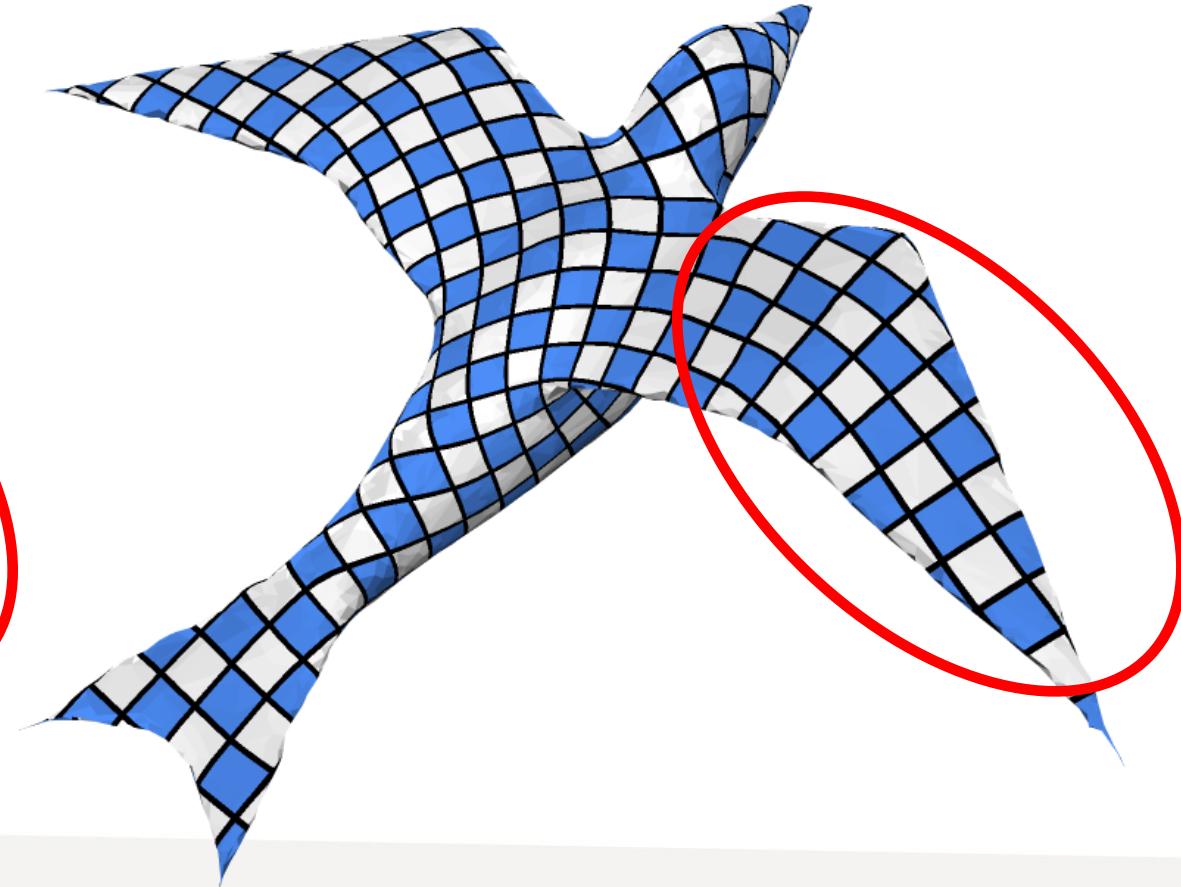
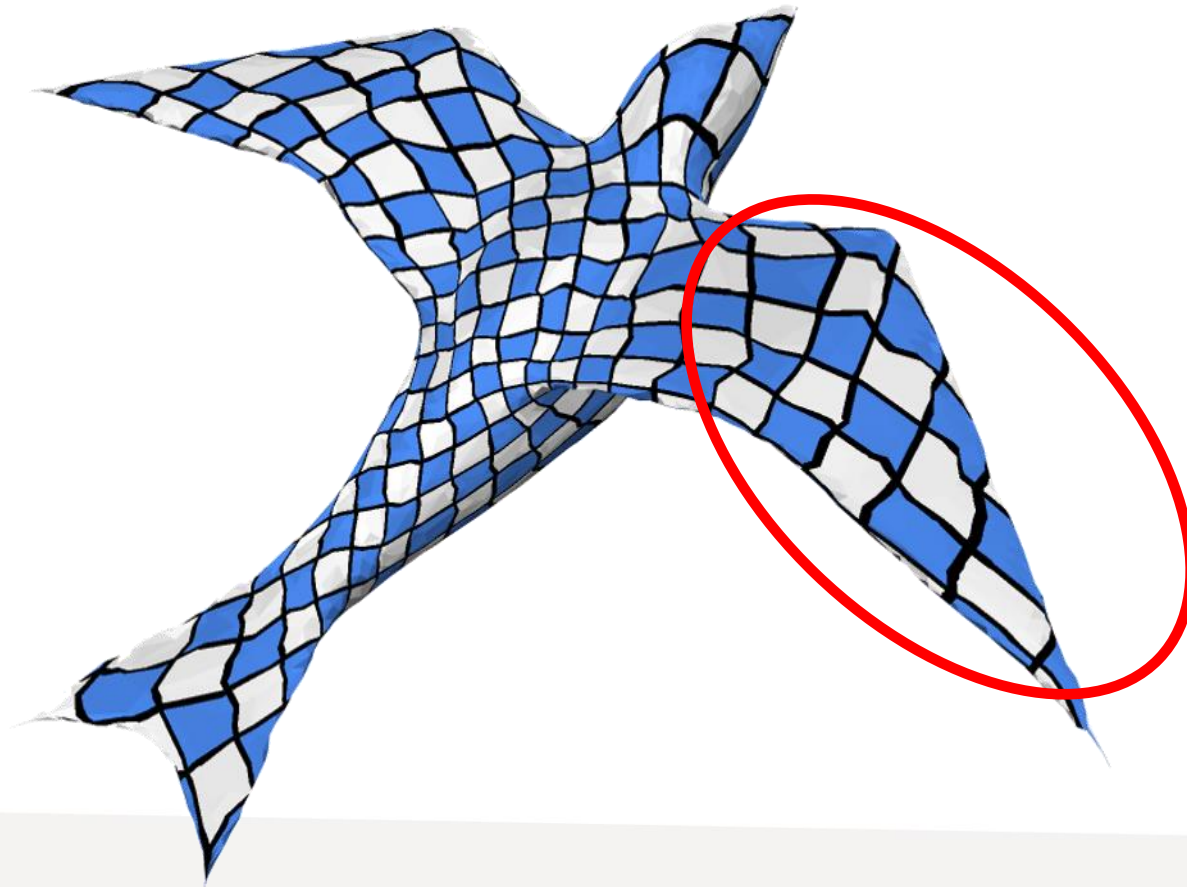


## Applications

Texture mapping, remeshing, inter-surface mapping, and shape analysis

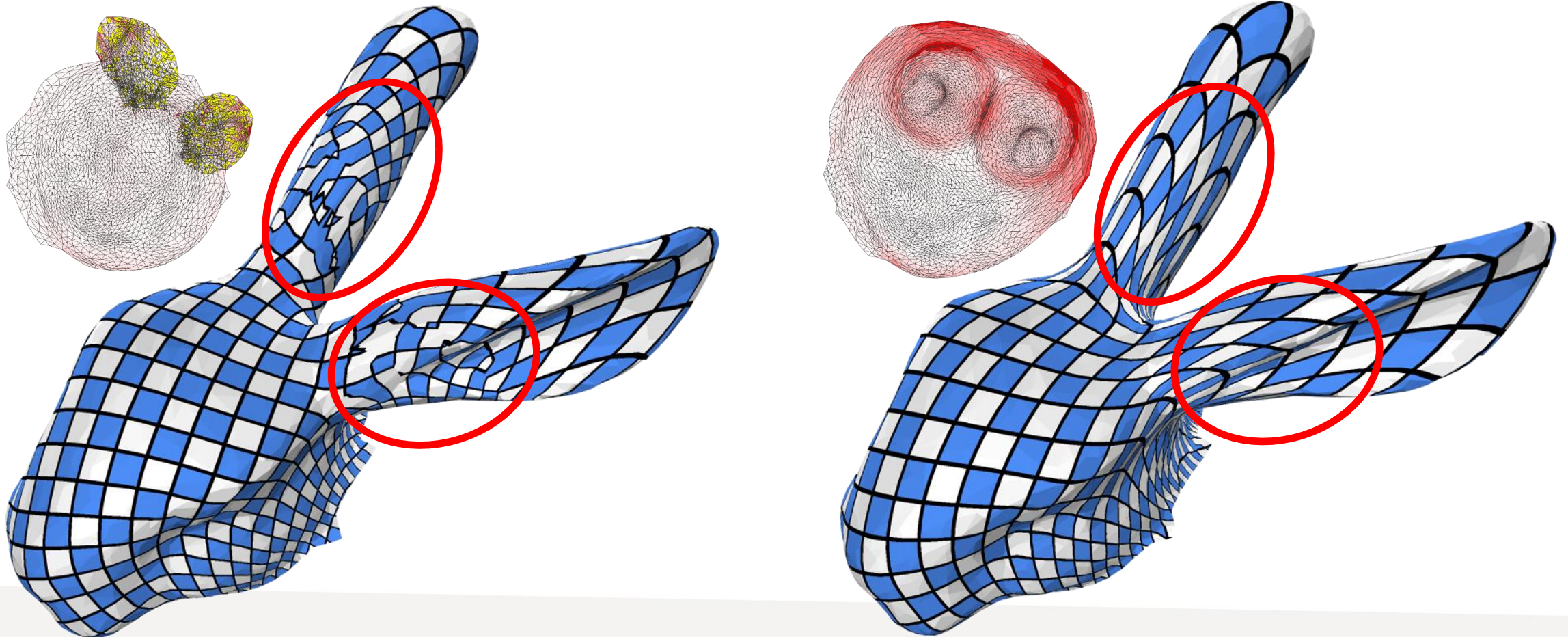
# Two Basic Requirements

- Low distortion



# Two Basic Requirements

- Foldover-free



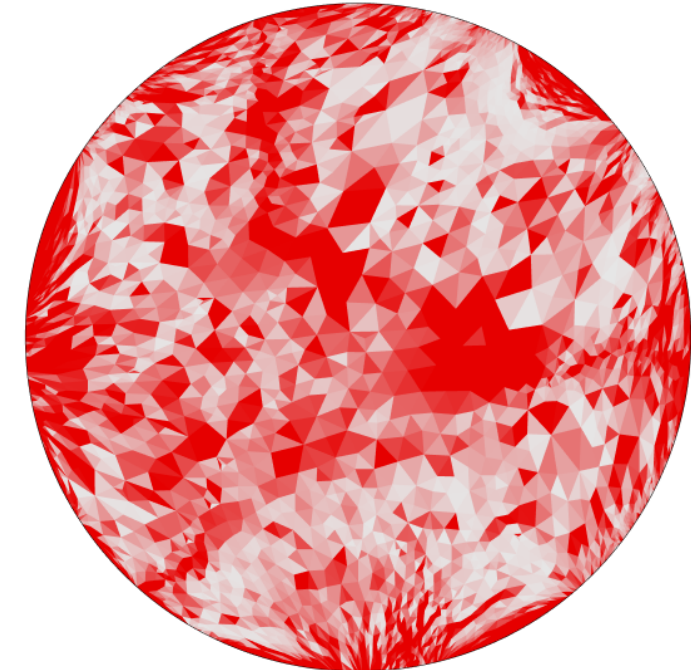
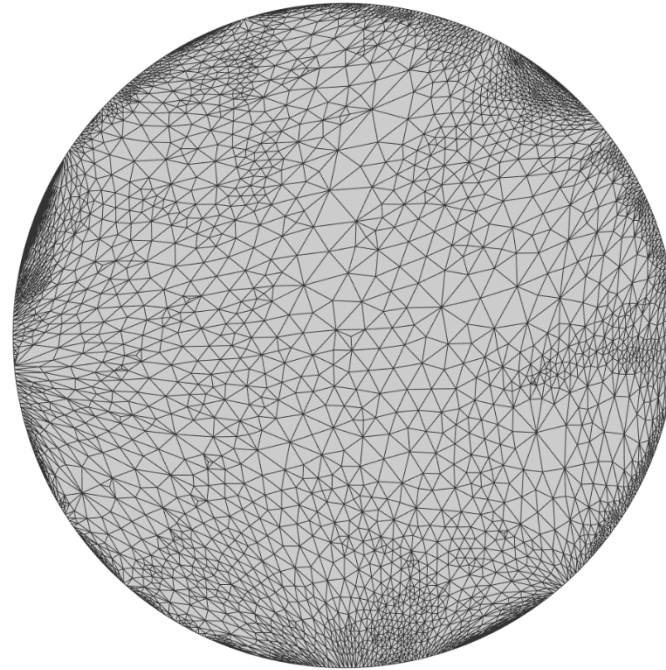
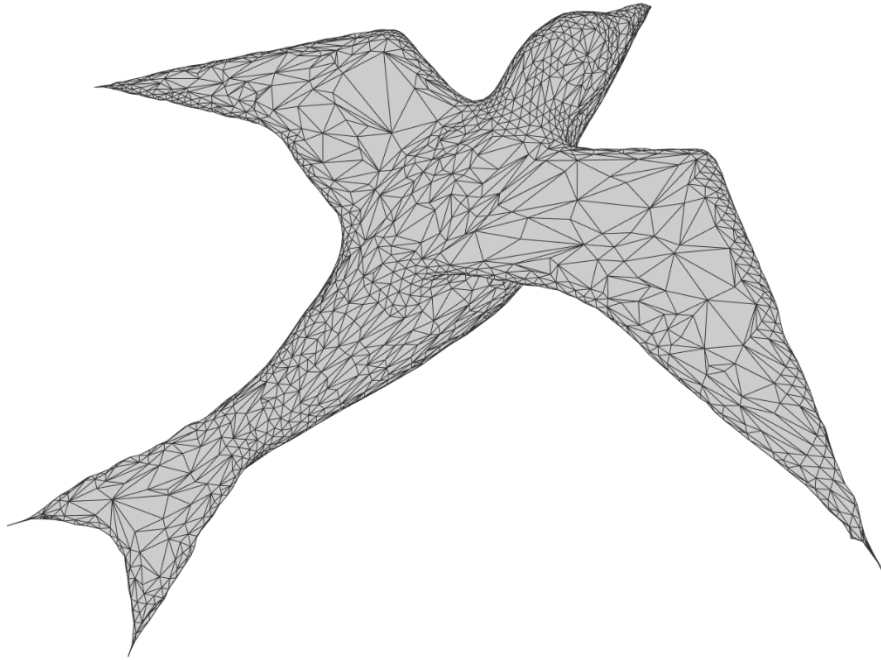
# Existing Work

## Geometric Standpoint

- Local/global methods [Liu et al. 2008; Sorkine and Alex 2007]
- Bounded distortion methods [Aigerman et al. 2014; Kovalsky et al. 2015; Lipman 2012]
- Representation based methods [Chien et al. 2016b; Fu and Liu 2016; Sheffer et al. 2005]

**They cannot guarantee foldover-free!**

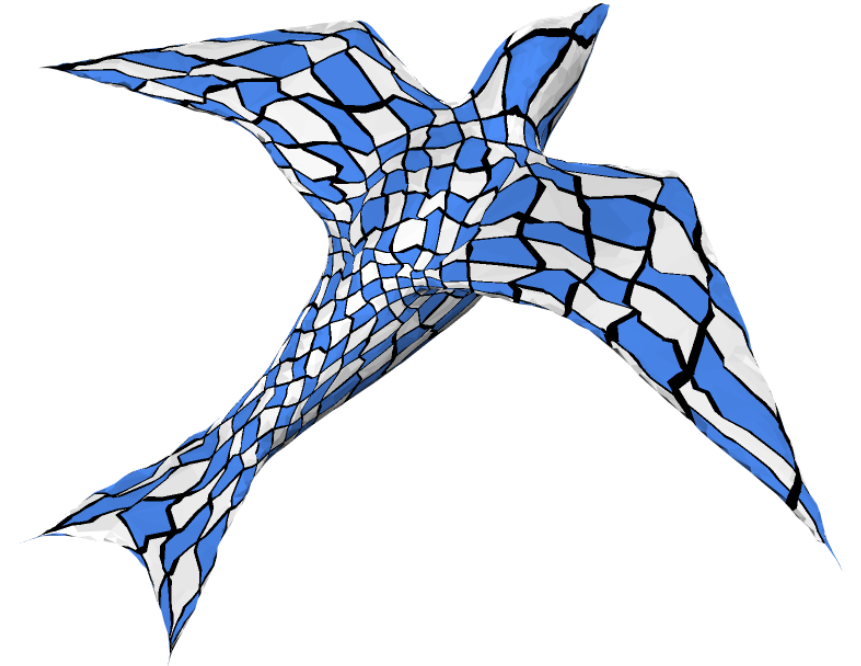
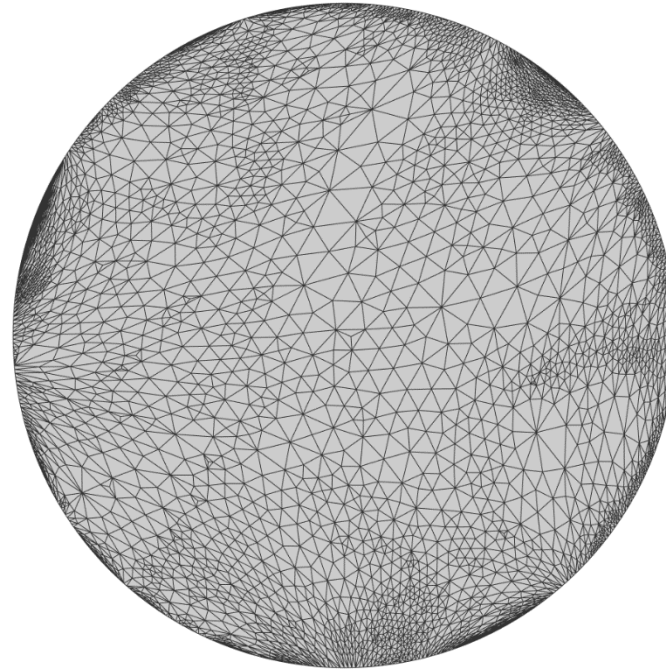
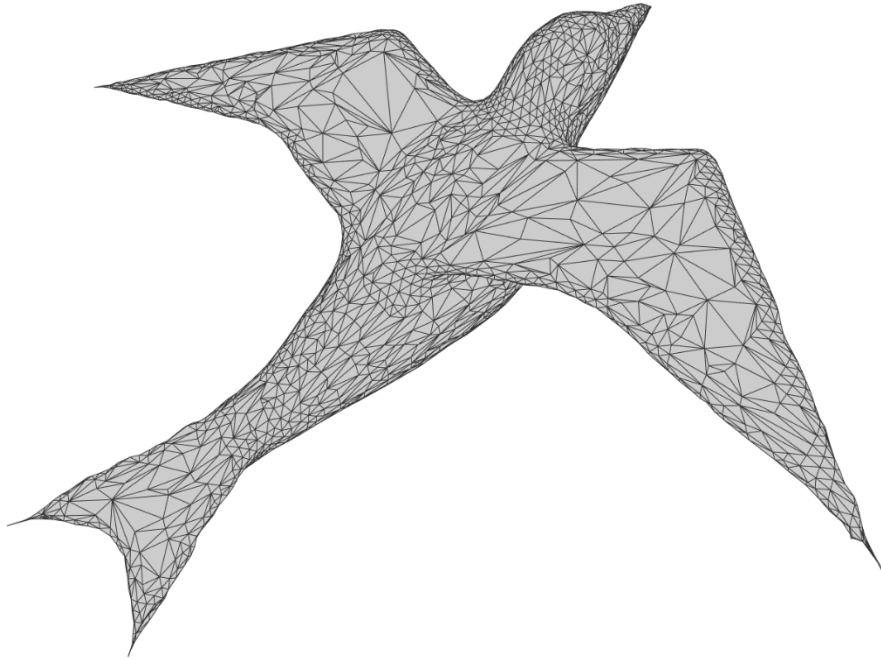
# Tutte's Embedding Method



Convex boundary  
Bijection guarantee

High distortion

# Tutte's Embedding Method



Convex boundary  
Bijection guarantee

High distortion

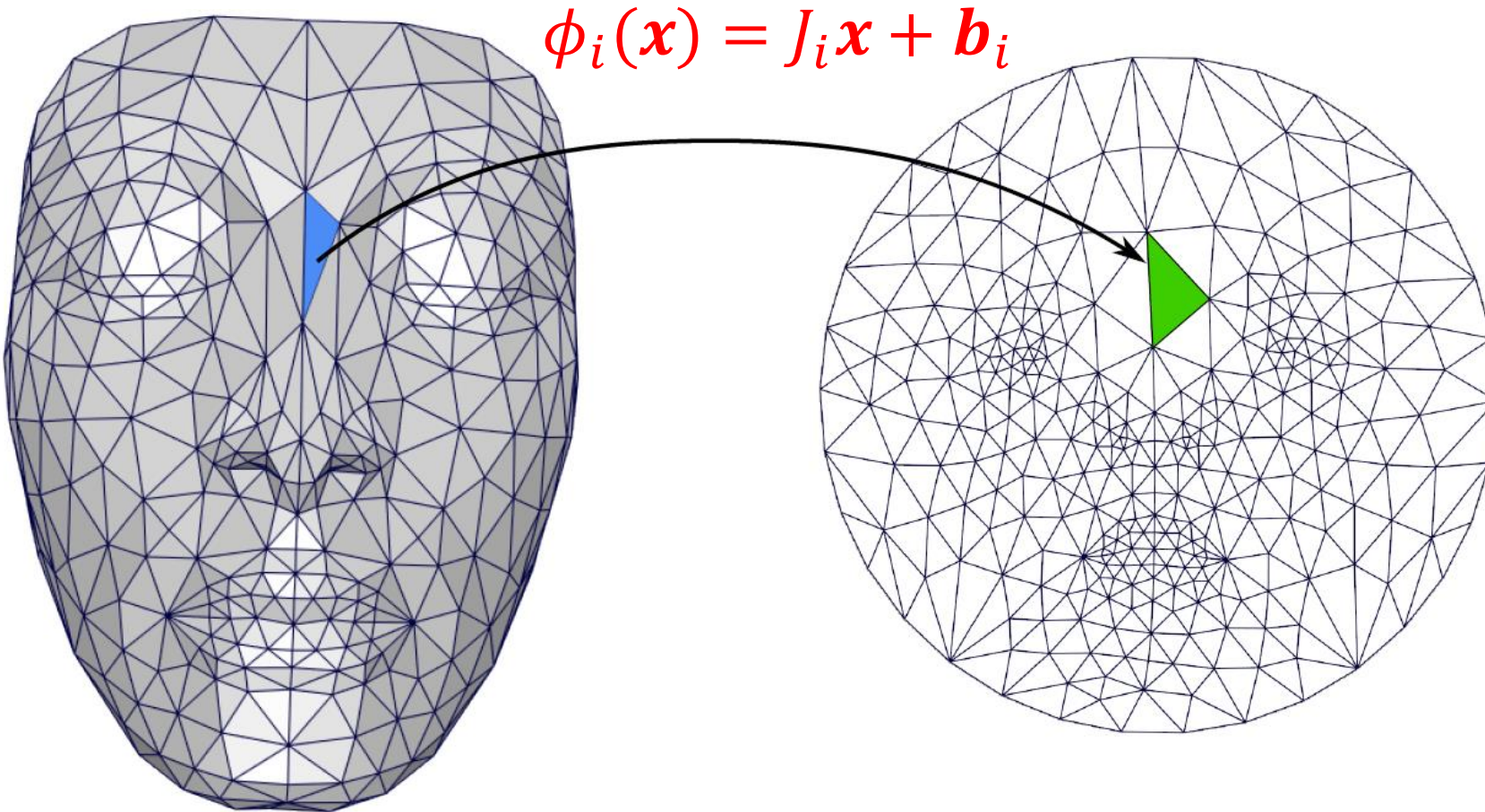
# Maintenance-based Methods

- Not violate the foldover-free constraints.

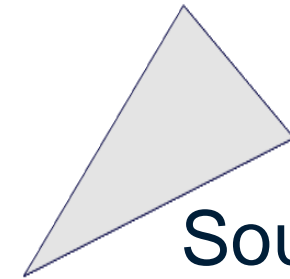




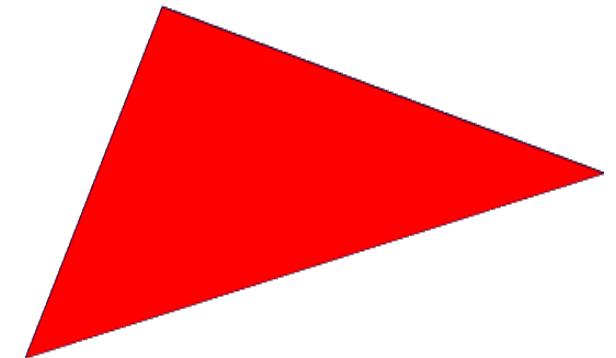
# Distortion Measures



High distortion



Source



High distortion

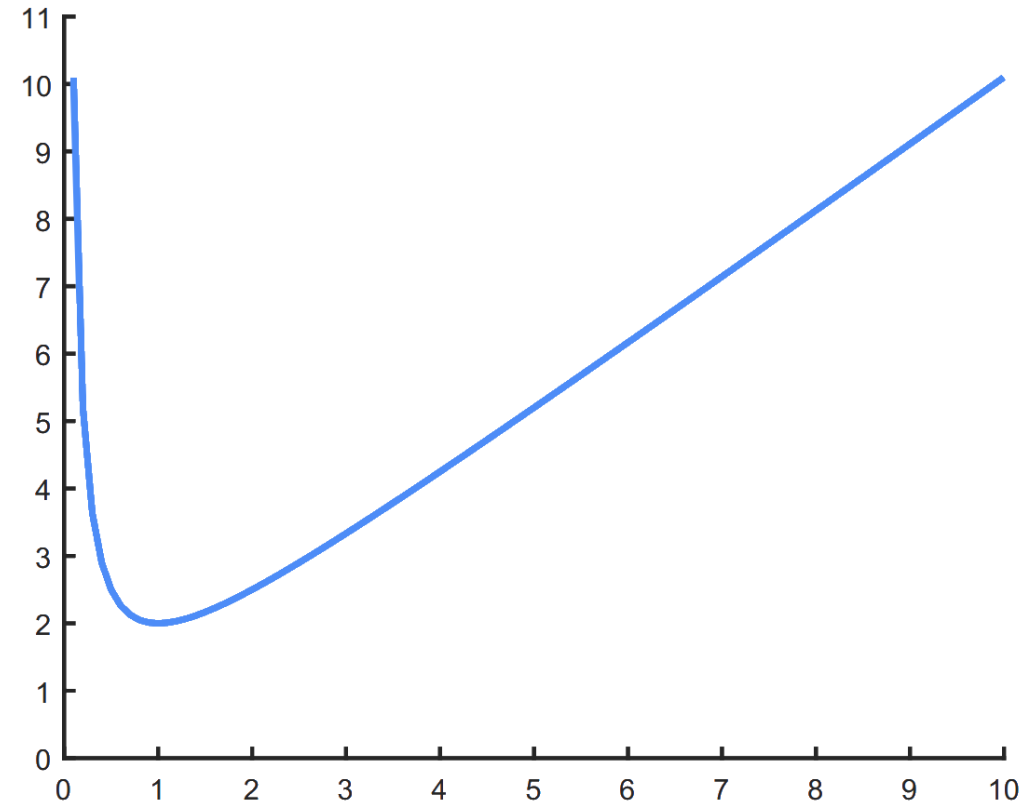
# Distortion Measures

- Symmetric Dirichlet metric: [Smith and Schaefer 2015]

$$D(J_i) = \frac{1}{4} \left( \|J_i\|_F^2 + \|J_i^{-1}\|_F^2 \right)$$
$$= \frac{1}{4} \left( \sigma_i^2 + \sigma_i^{-2} + \tau_i^2 + \tau_i^{-2} \right)$$

$\sigma_i, \tau_i$ : singular values of  $J_i$

Opt value = 1 when  $\sigma_i = \tau_i = 1$



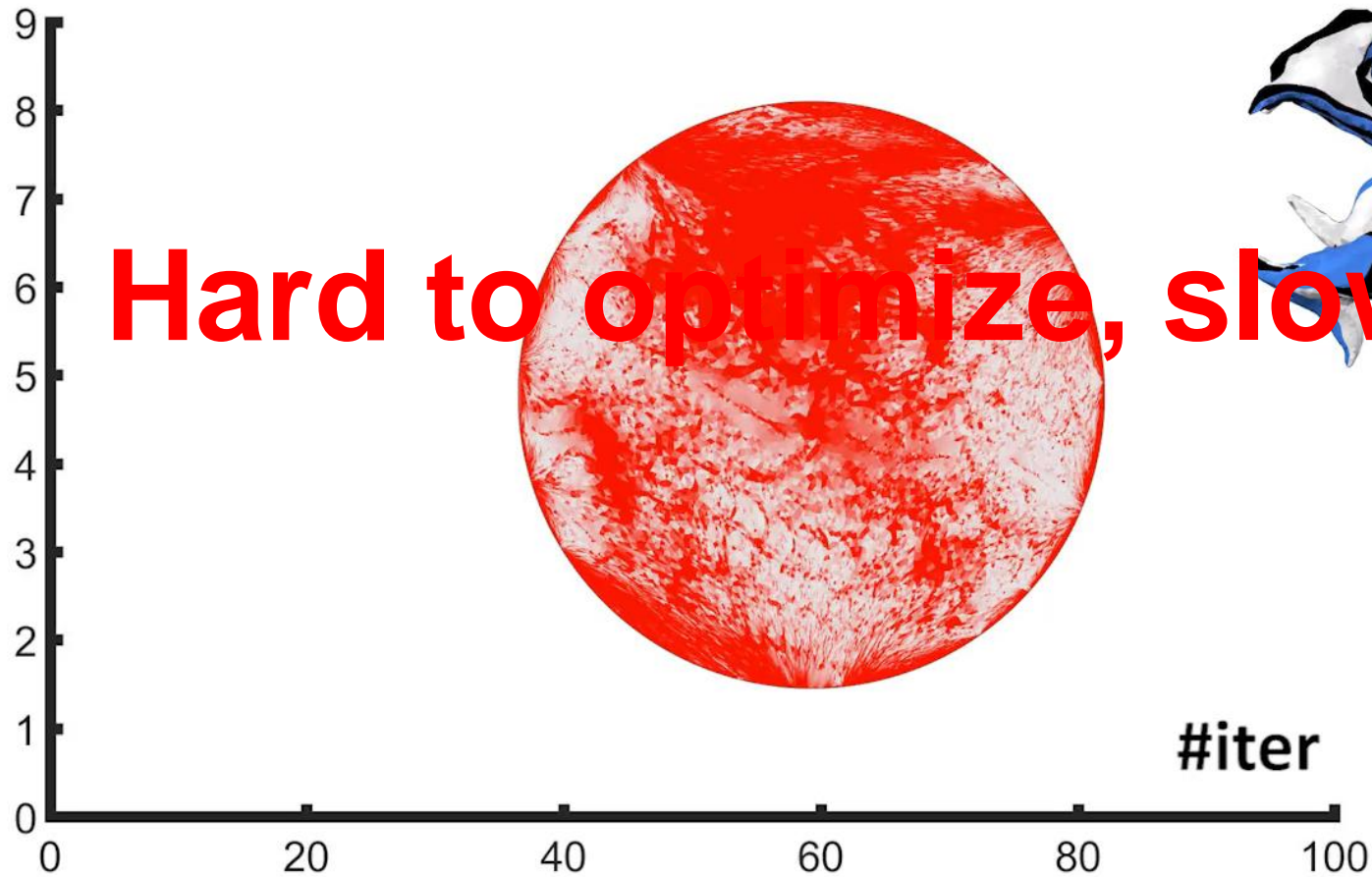
# Challenge

- Highly non-convex and non-linear
- Extremely large distortion on initializations



# Challenge

log(energy)



# Existing Work

## Optimization Standpoint

- Block coordinate descent methods [Fu et al. 2015; Hormann and Greiner 2000]
- Quasi-Newton method [Smith and Schaefer 2015]
- Preconditioning methods [Claici et al. 2017; Kovalsky et al. 2016]
- Reweighting descent method [Rabinovich et al. 2017]
- Composite majorization method [Shtengel et al. 2017]

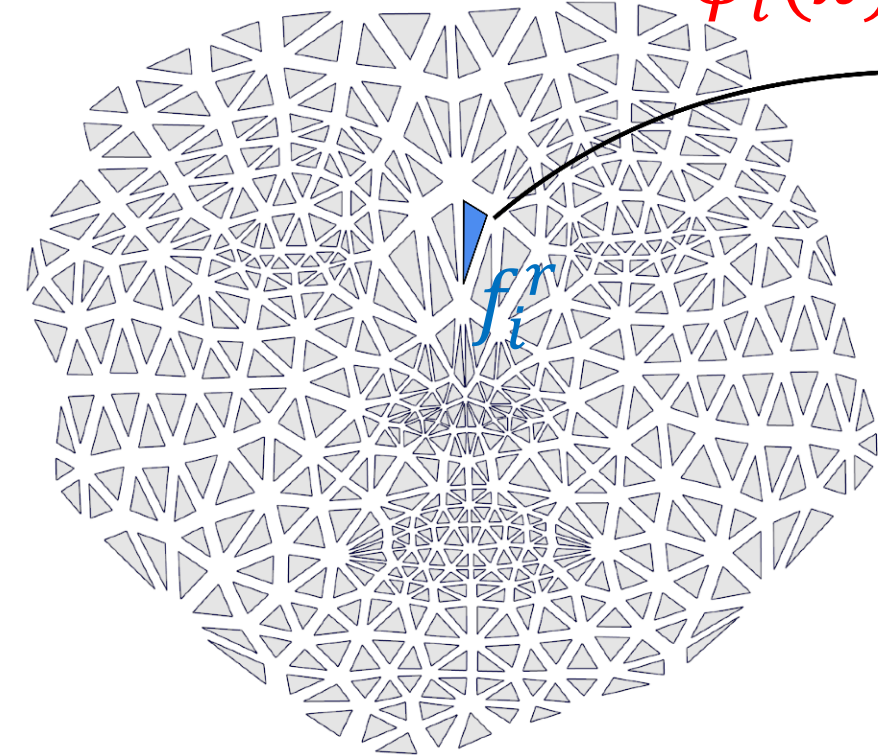
**Only thinking from the view of solver!**

## Our Approach

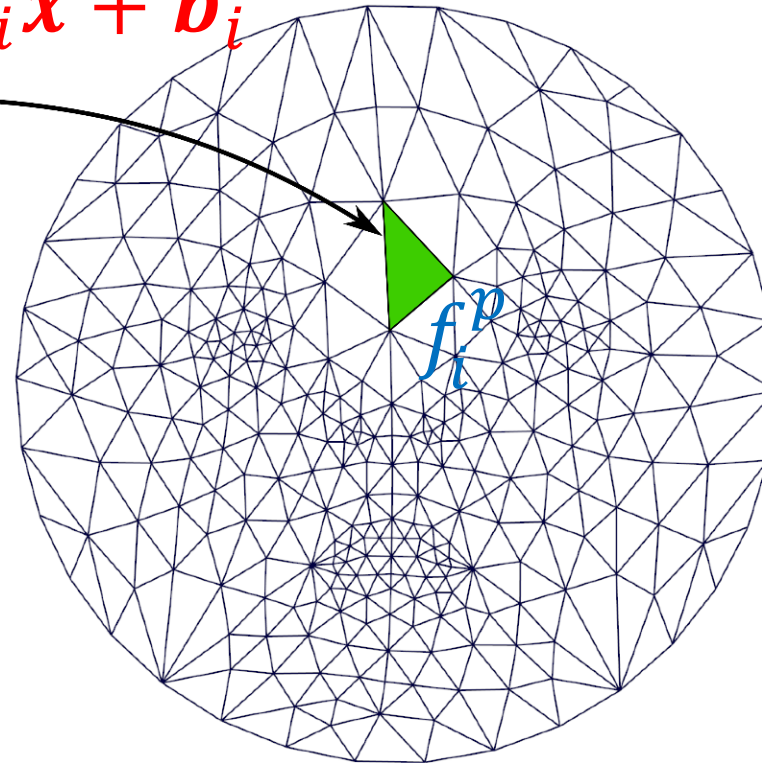
# Progressive Parameterizations

# Reference-guided Distortion Metric

$$\phi_i(\mathbf{x}) = J_i \mathbf{x} + \mathbf{b}_i$$



Reference  $M^r$ : A set of individual triangles

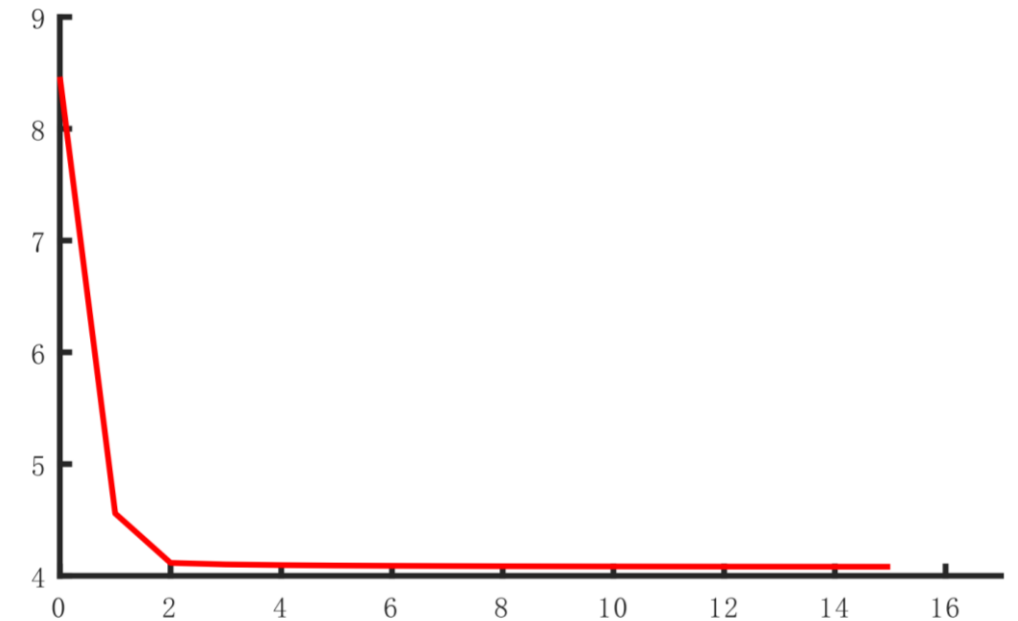
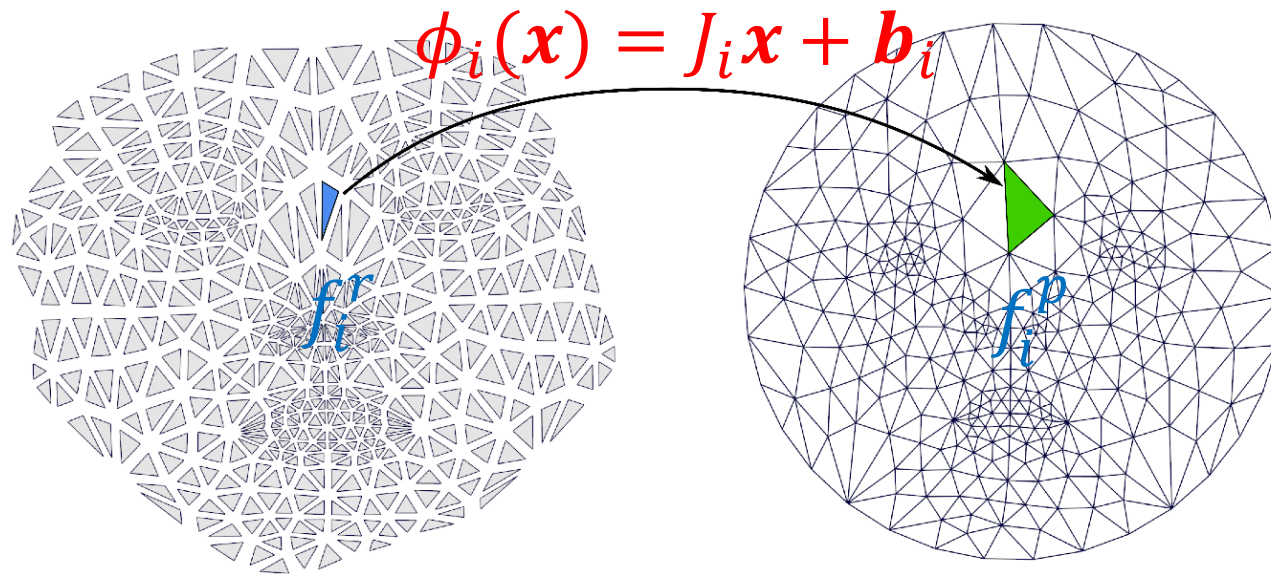


Parameterized mesh  $M^p$

Distortion Metric:  
 $D(f_i^r, f_i^p) = D(J_i)$

Input Mesh:  
Ideal Reference

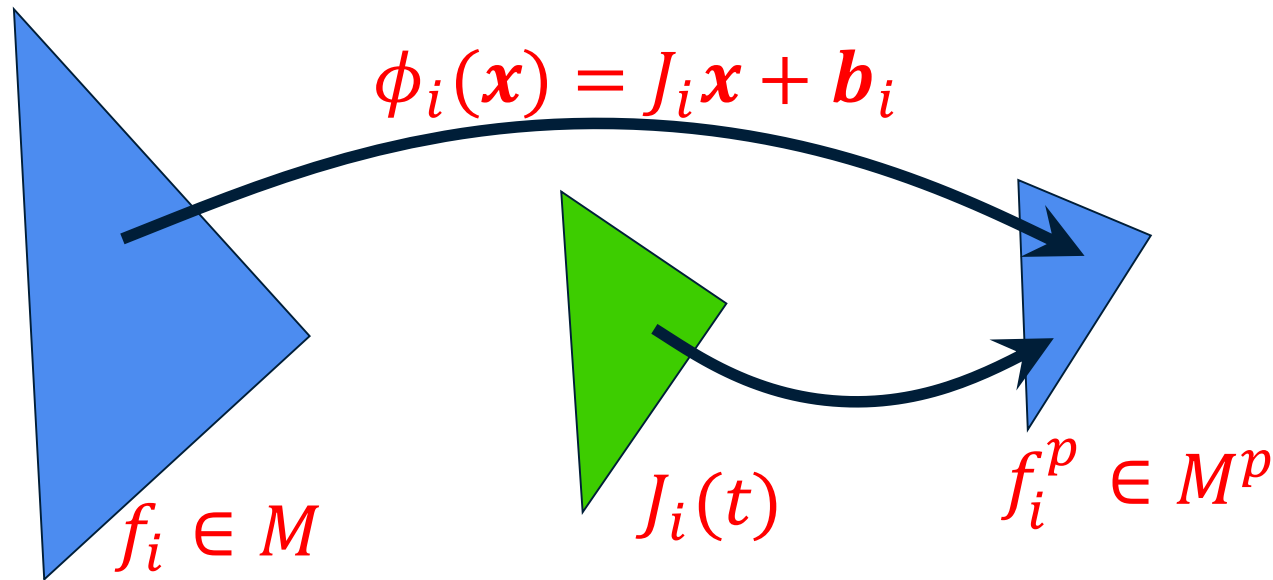
# Key Observation



If all  $D(f_i^r, f_i^p) \leq K, \forall i$ , only a few iterations in the optimization of  $E(M^r, M^p)$  are necessary.



# Change The Reference



Goal: find a triangle between  $f_i$  and  $f_i^p$  as the reference  $f_i^r$  that satisfies  $D(f_i^r, f_i^p) \leq K$ .

$$f_i^r \in M^r$$

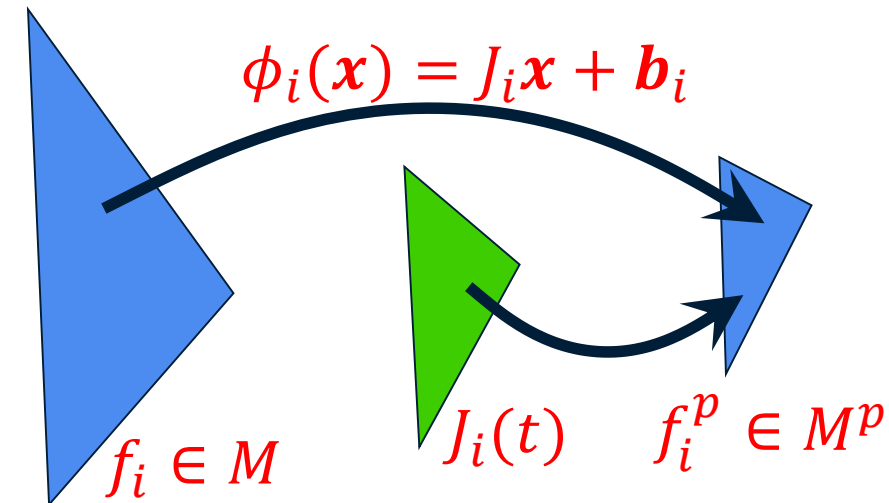
$$D(f_i^r, f_i^p) \leq K$$

# Choose The Reference

- Exponential function [Alexa 2002; Grassia 1998; Rossignac and Vinacua 2011]:

$$J_i(t) = U_i \text{diag}(\sigma_i^t, \tau_i^t) V_i^T$$

where  $J_i = U_i \text{diag}(\sigma_i, \tau_i) V_i^T$



# Construction of new reference

# Optimization Of The New Reference

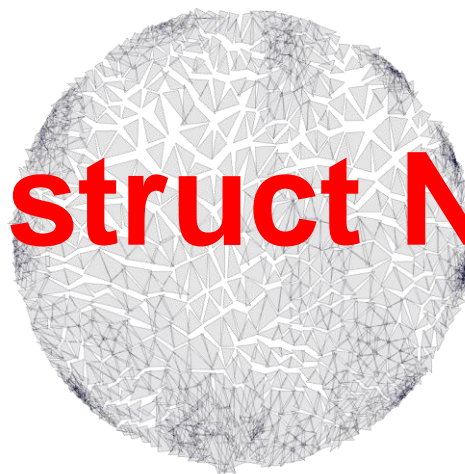
## Progressively Construct New Reference!



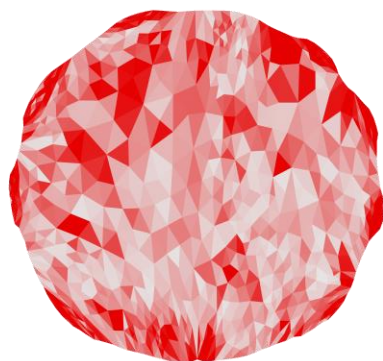
Tutte's  
Initialization



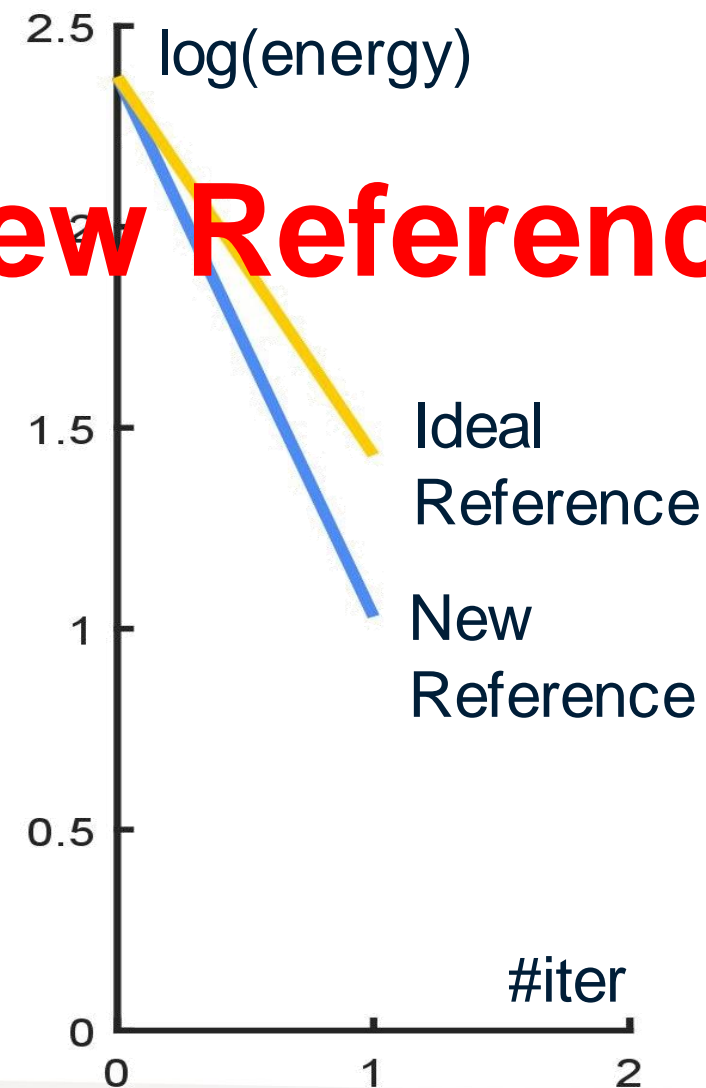
Ideal Reference



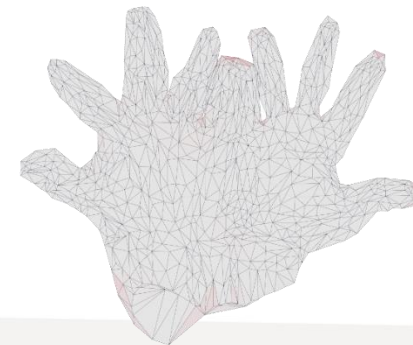
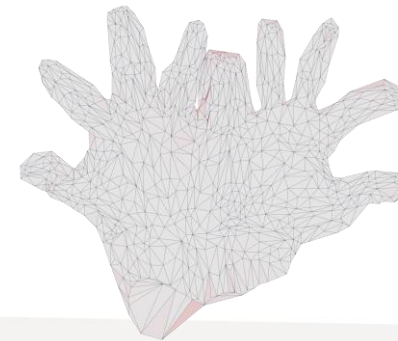
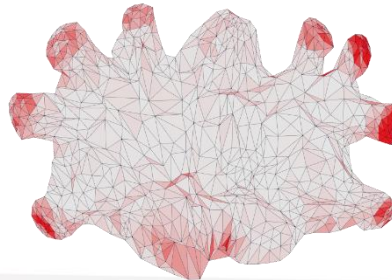
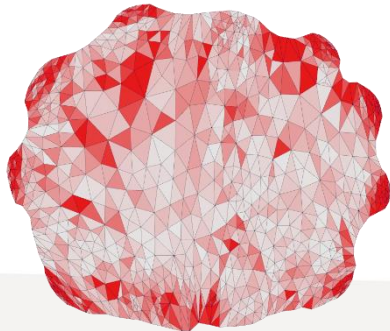
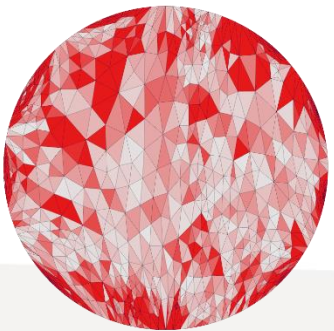
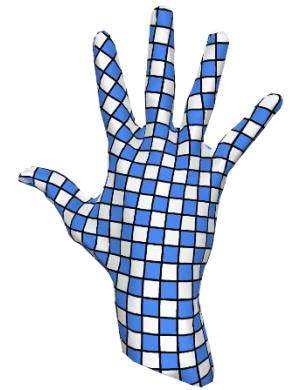
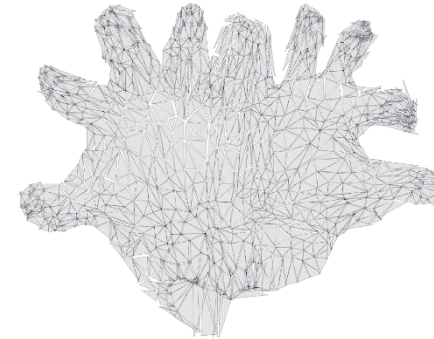
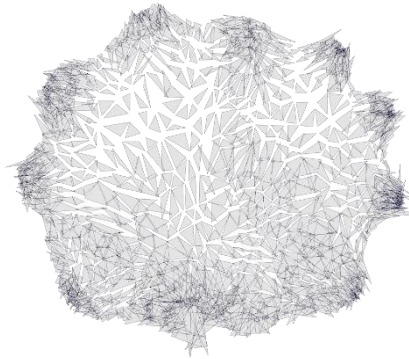
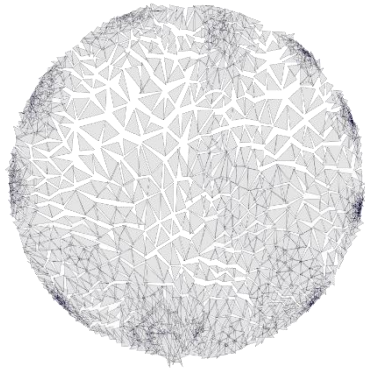
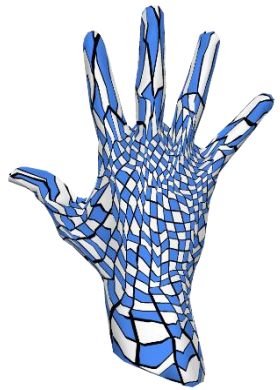
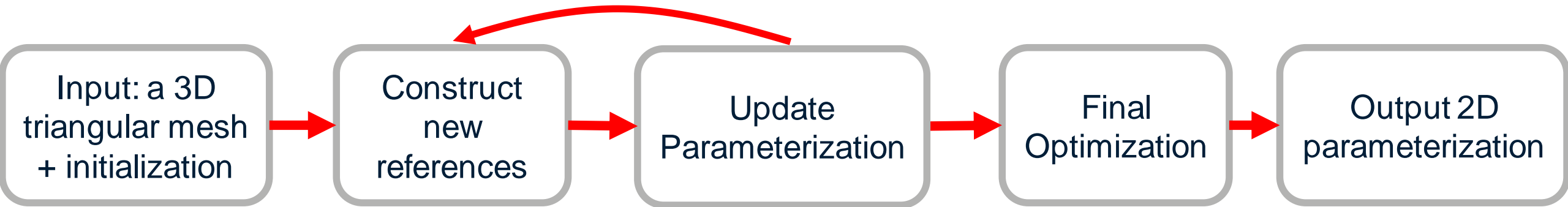
New Reference



SLIM [Rabinovich et al. 2017]



# Progressive Parameterization

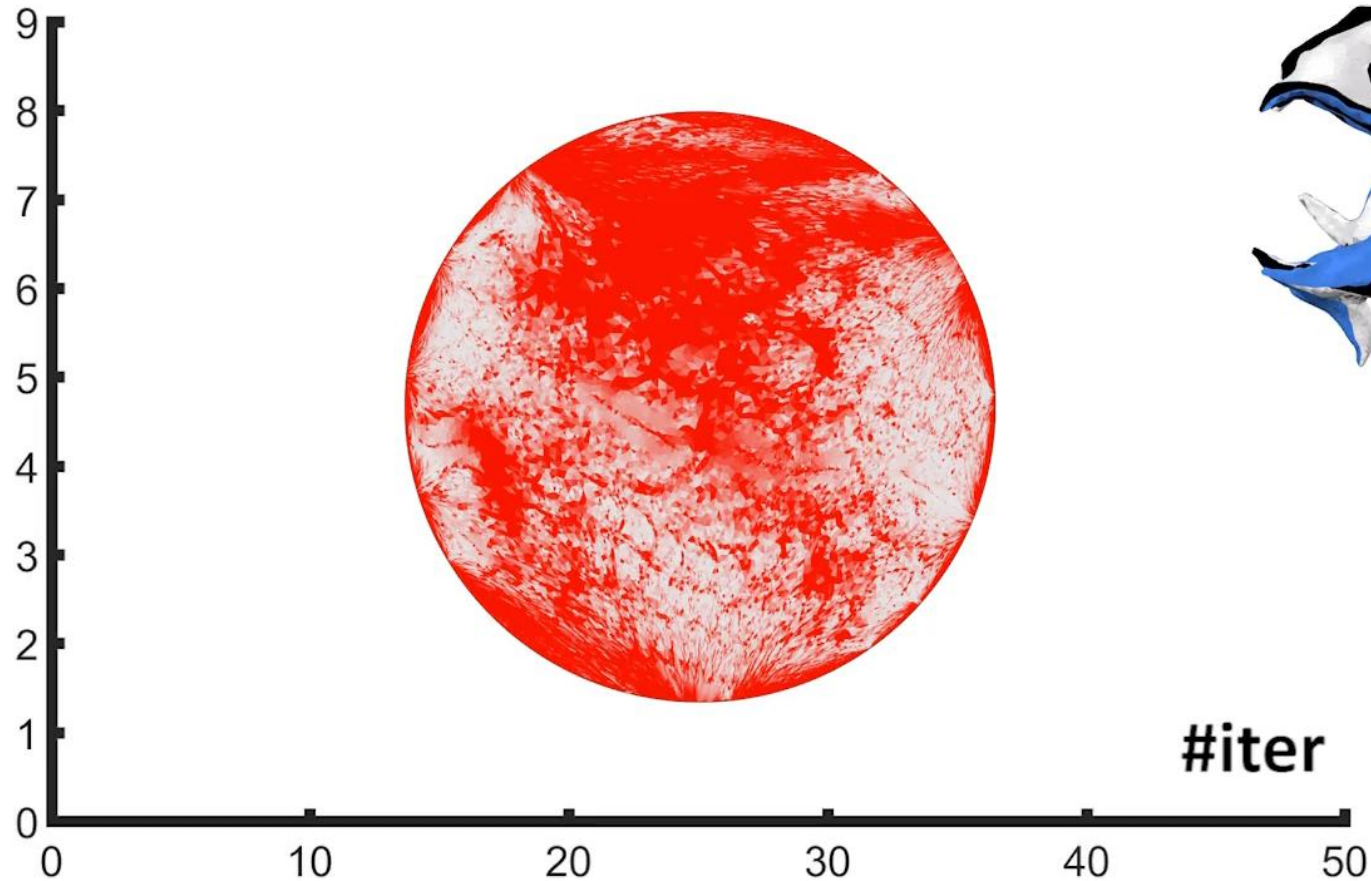


# Hybrid Solver

- SLIM [Rabinovich et al. 2017]
  - Pros: effectively penalize the maximum distortion
  - Cons: a poor convergence rate
- CM [Shtengel et al. 2017]
  - Pros: converge quickly
  - Cons: cannot reduce large distortion quickly
- Hybrid
  - First perform SLIM solver
  - Then use the CM solver

# The Former Dragon Example

log(energy)



# Experiments



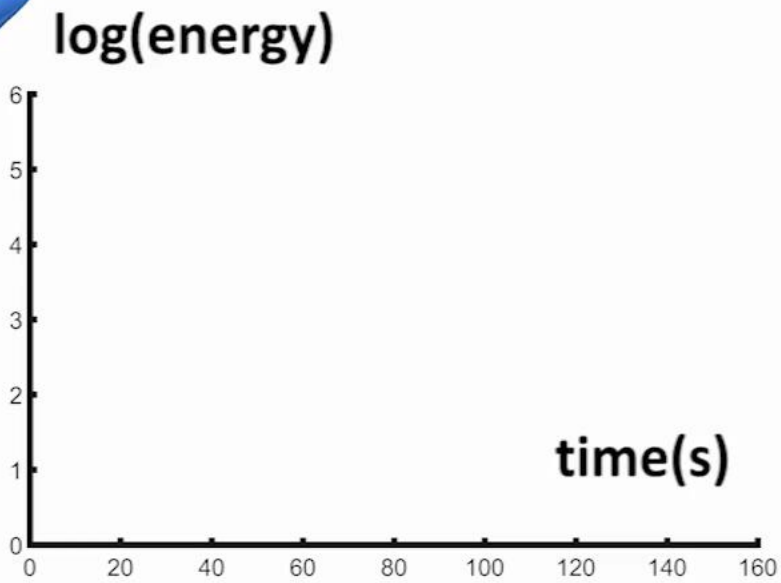
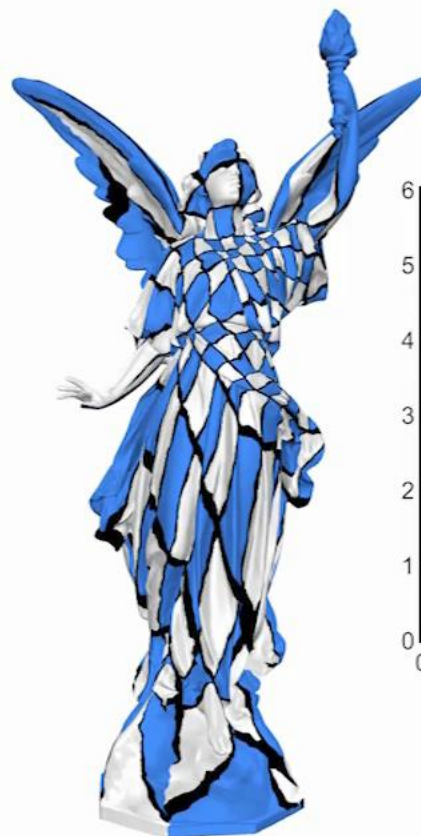
**AKVF** [Claici et al. 17]

**CM** [Shtengel et al. 17]

**SLIM** [Rabinovich et al. 17]

**Ours**

**2x playback**



**#V: 900k, #F: 1792k**

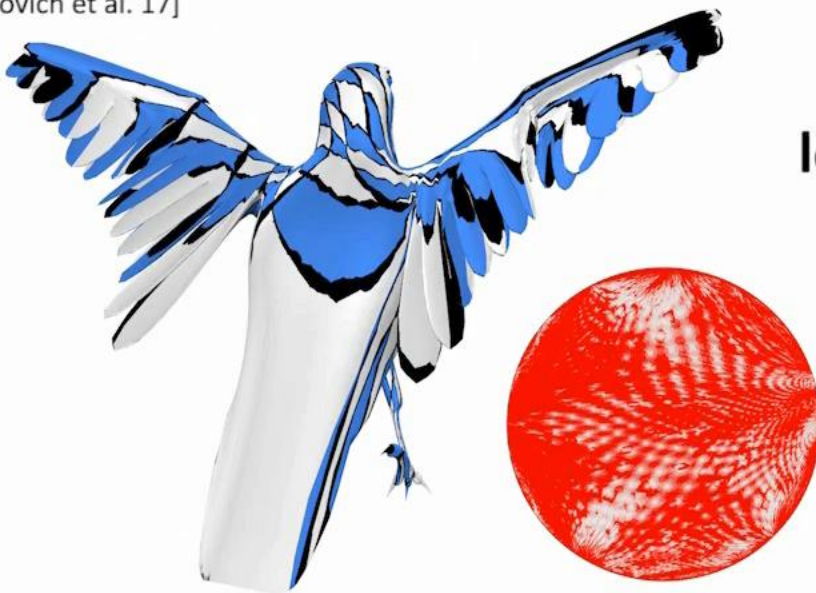
# AKVF

[Claici et al. 17]



# SLIM

[Rabinovich et al. 17]



# CM

[Shtengel et al. 17]

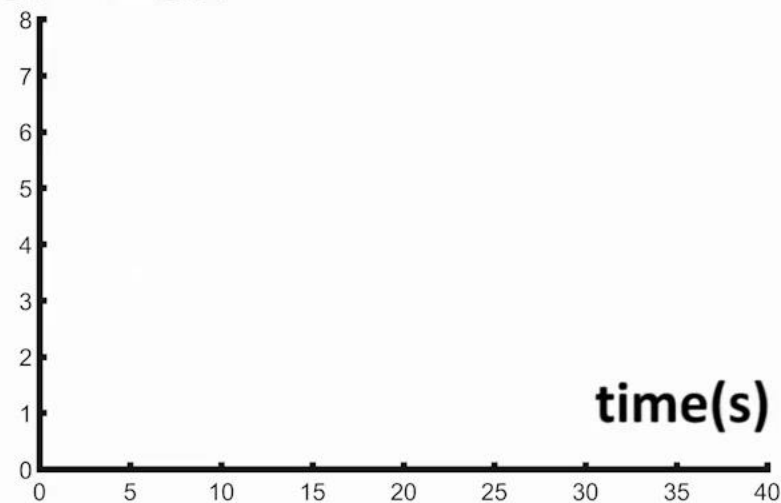


# Ours

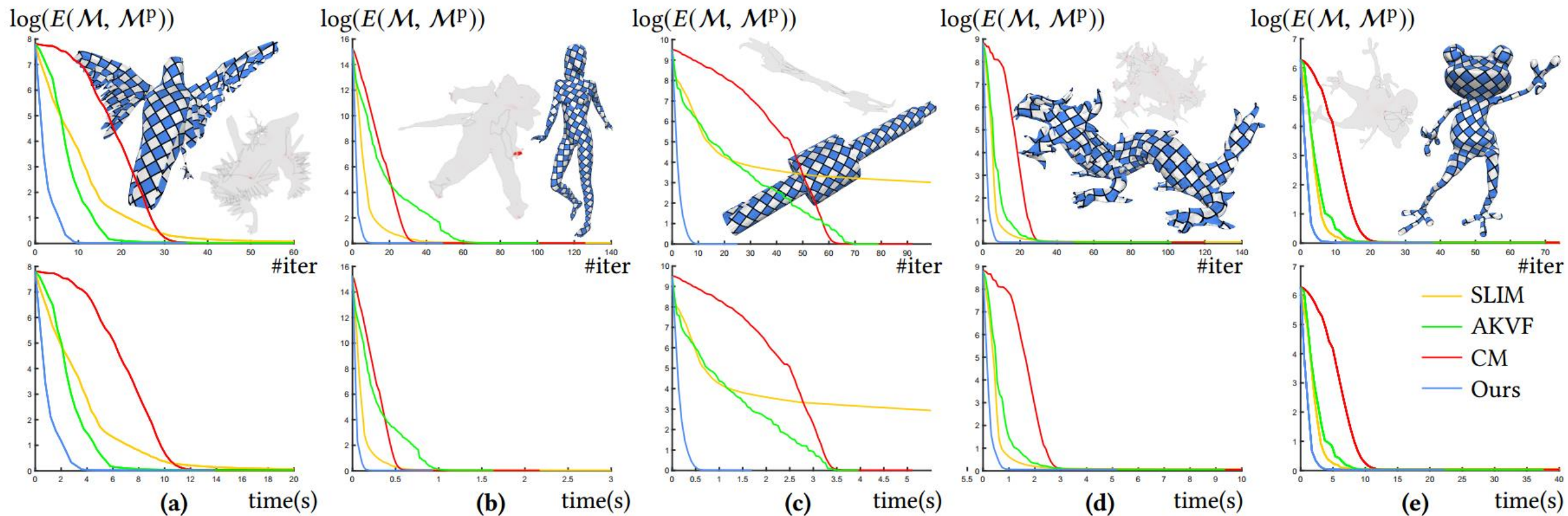


# playback

log(energy)



#V: 195k, #F: 382k

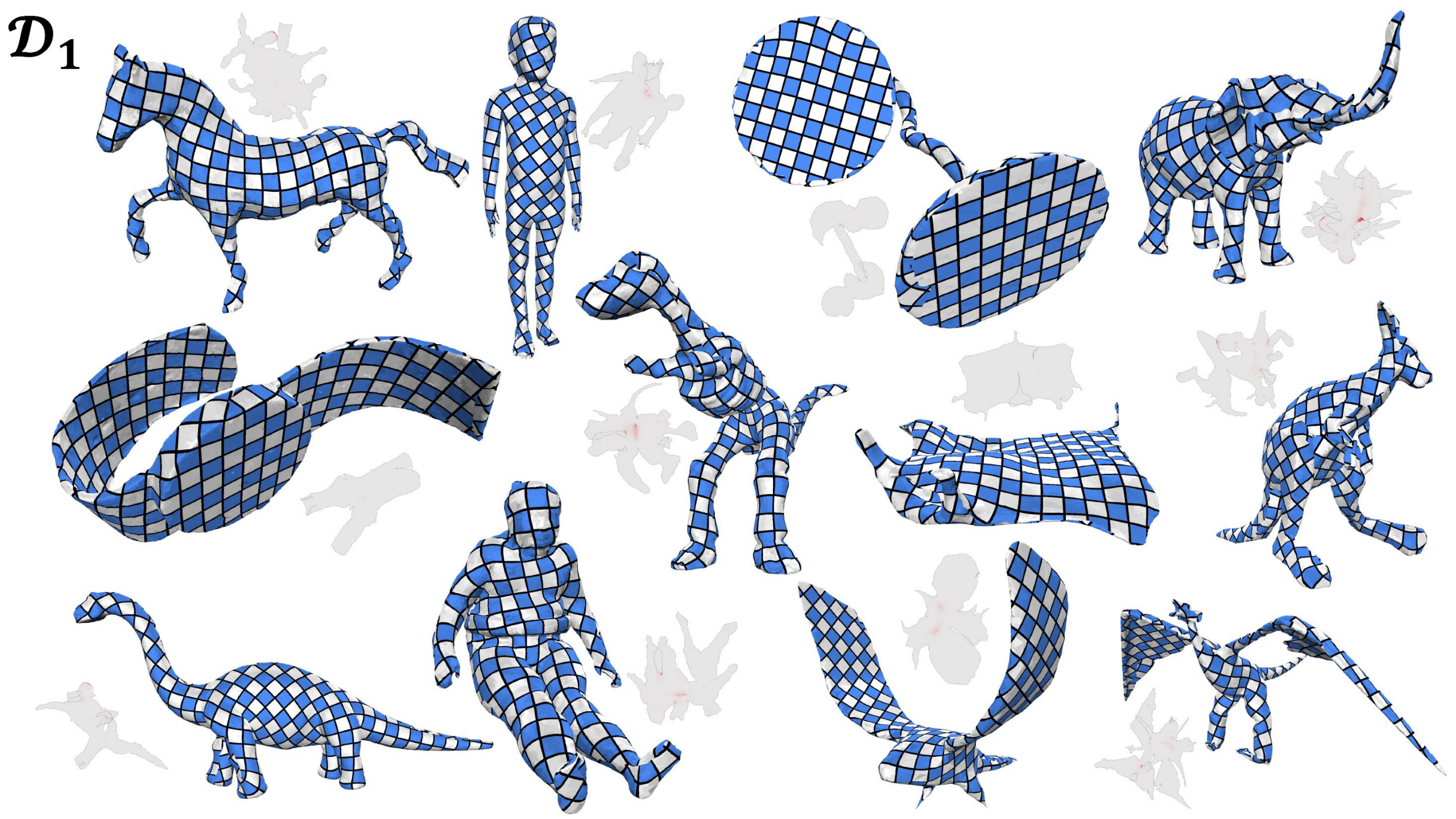


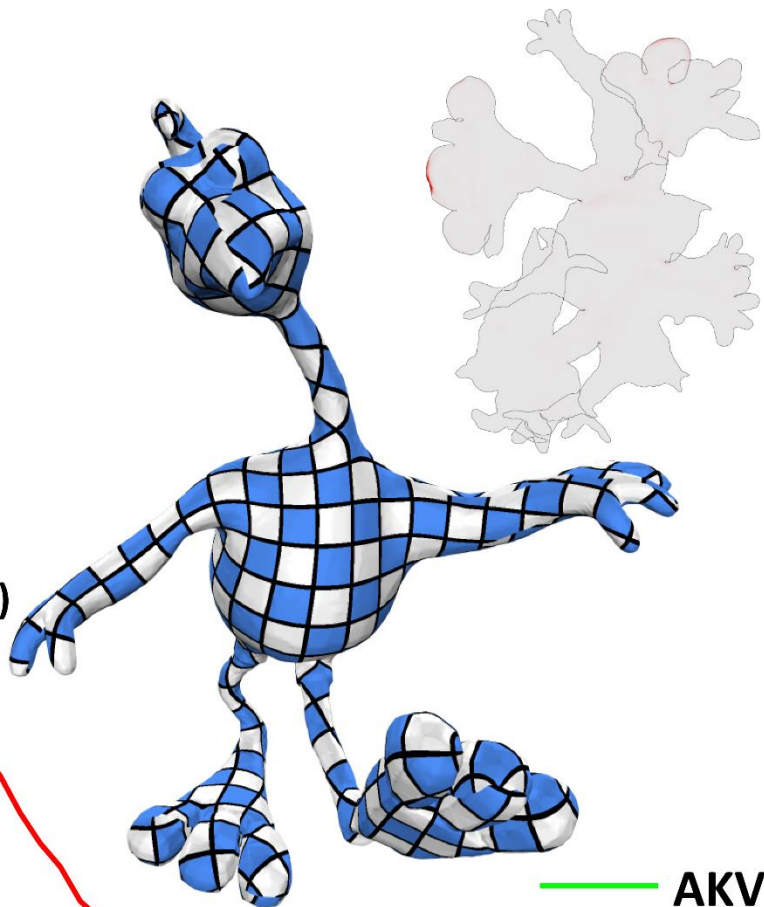
# Benchmark

$\mathcal{D}_1$ : **10273** well cut meshes

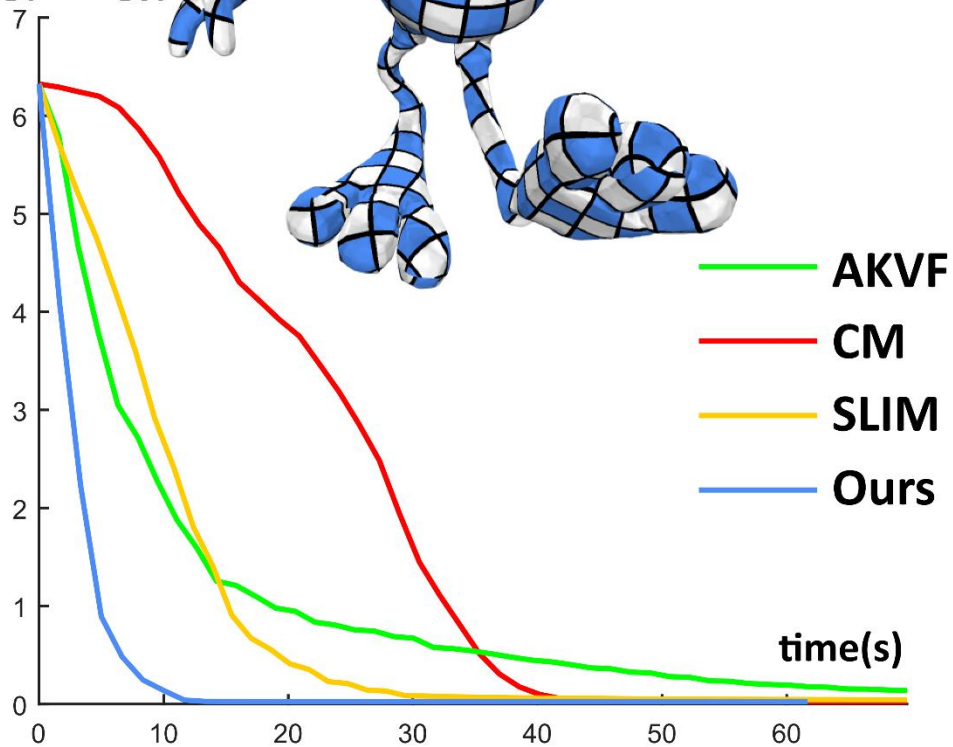
$\mathcal{D}_2$ : **6189** moderately bad cut meshes

$\mathcal{D}_3$ : **4250** extremely challenging examples

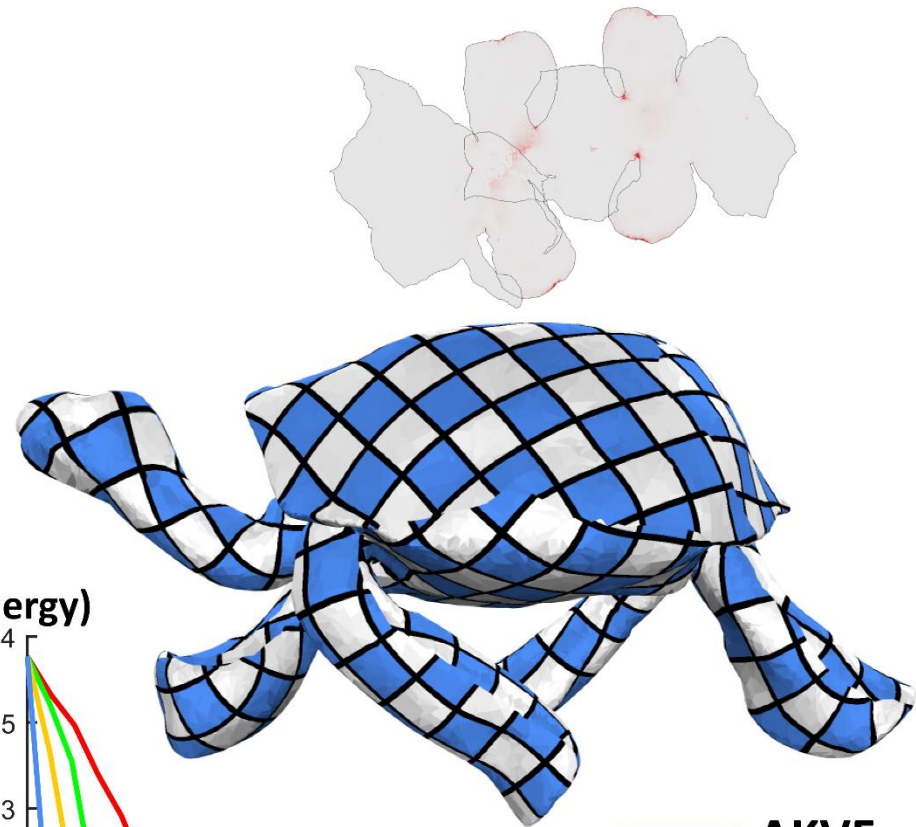


$\mathcal{D}_1$ 

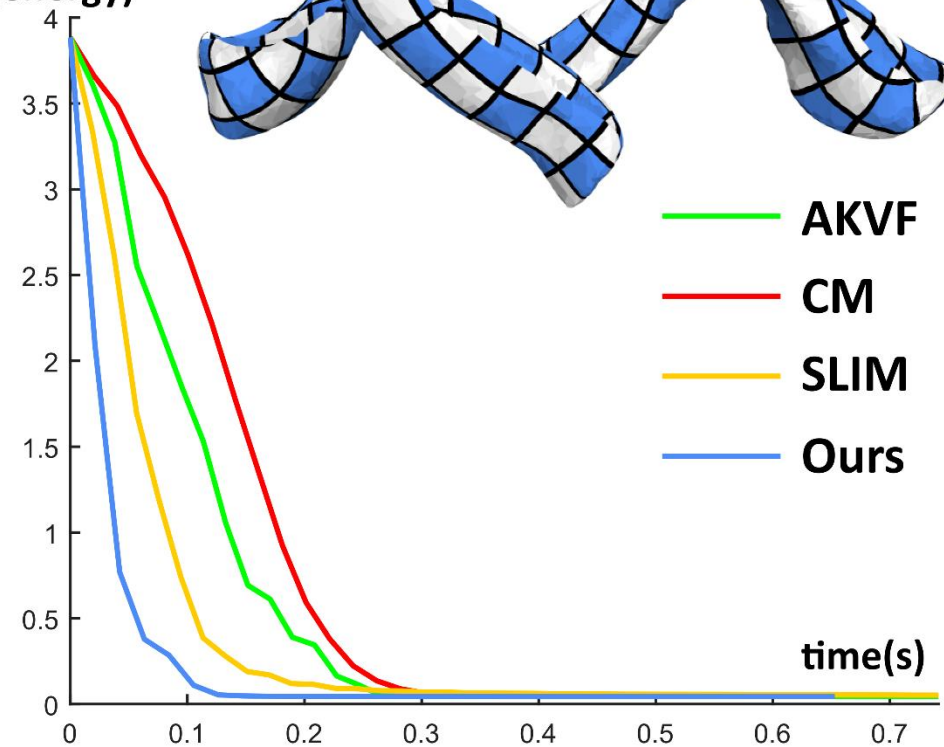
Log(energy)



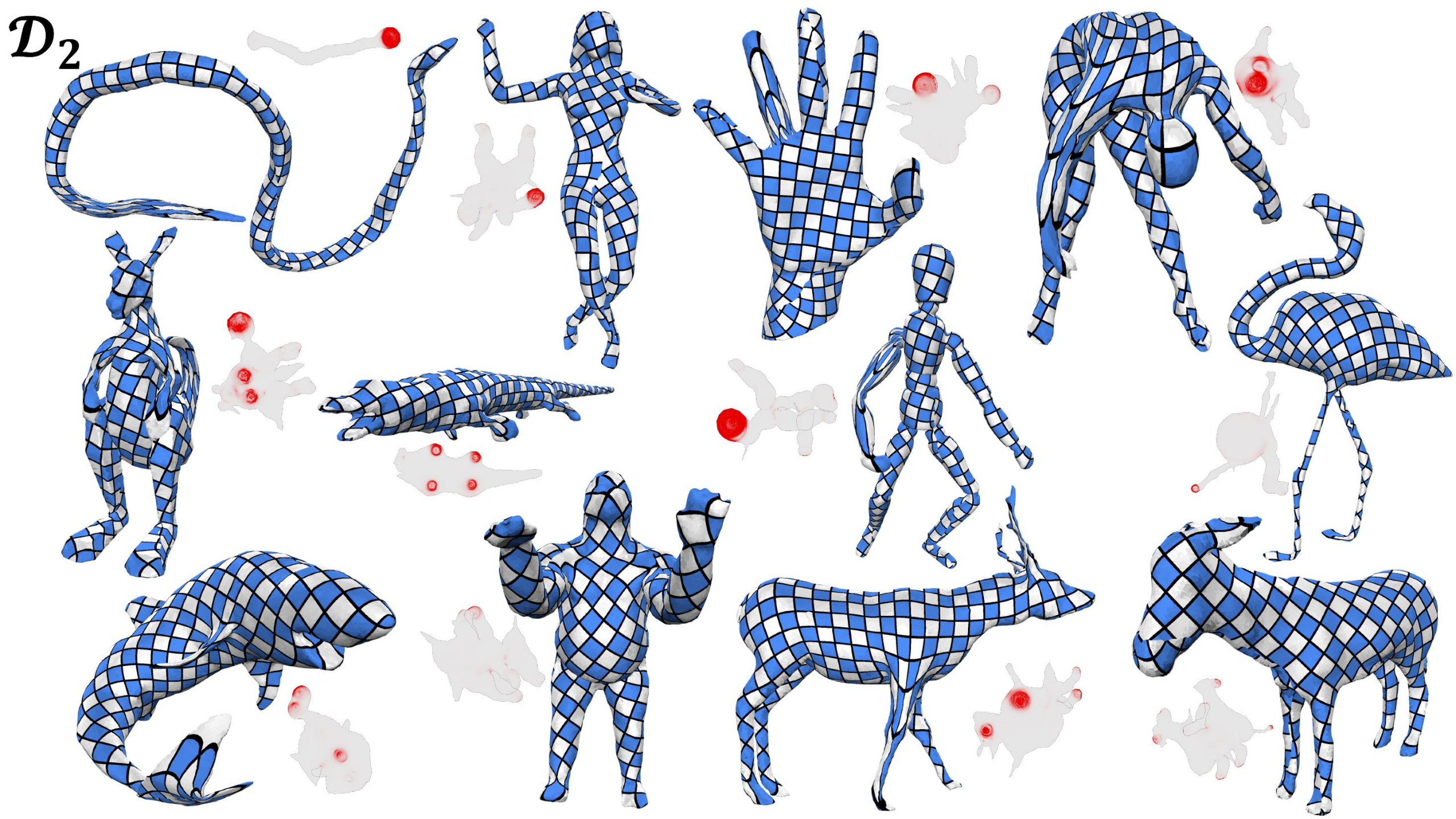
time(s)



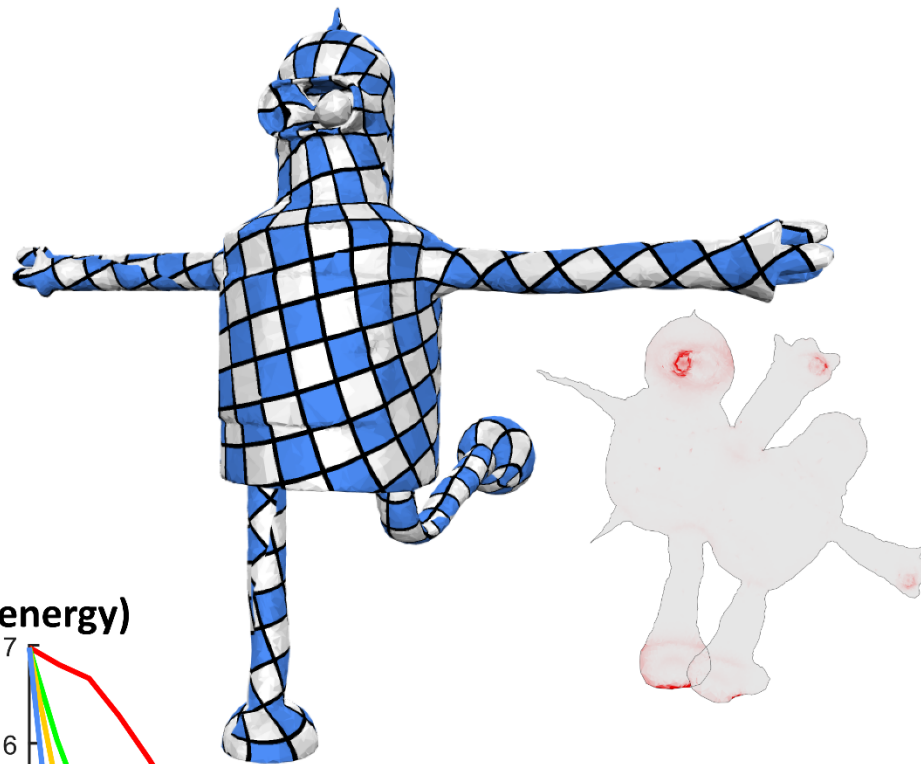
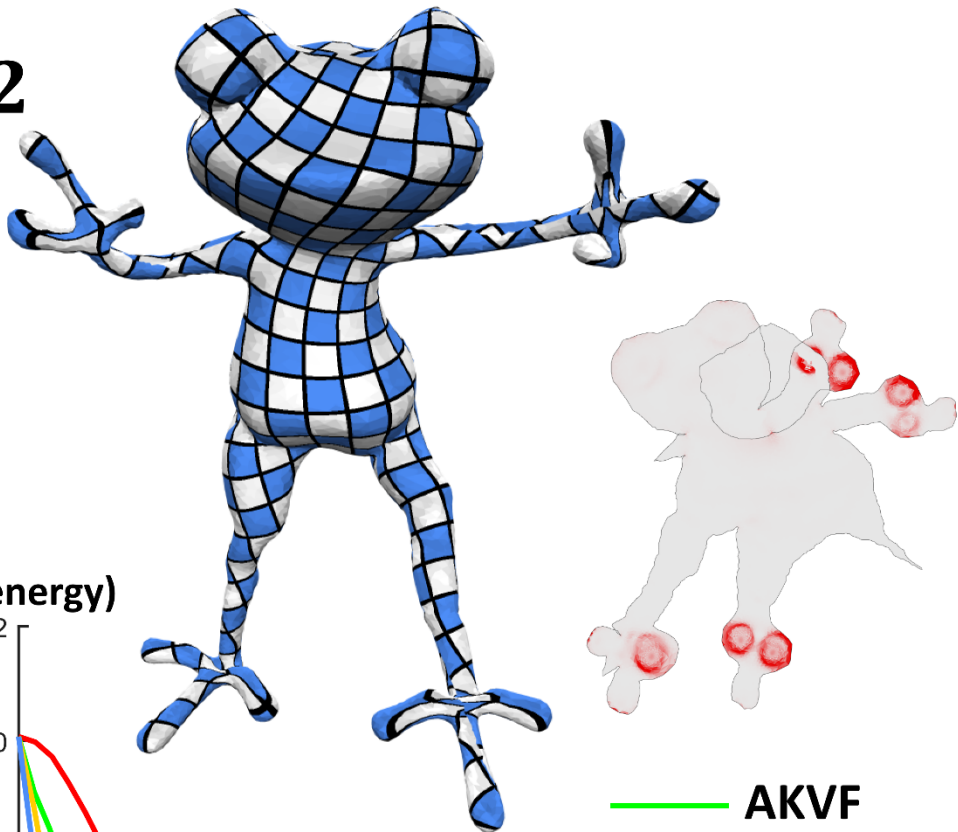
Log(energy)



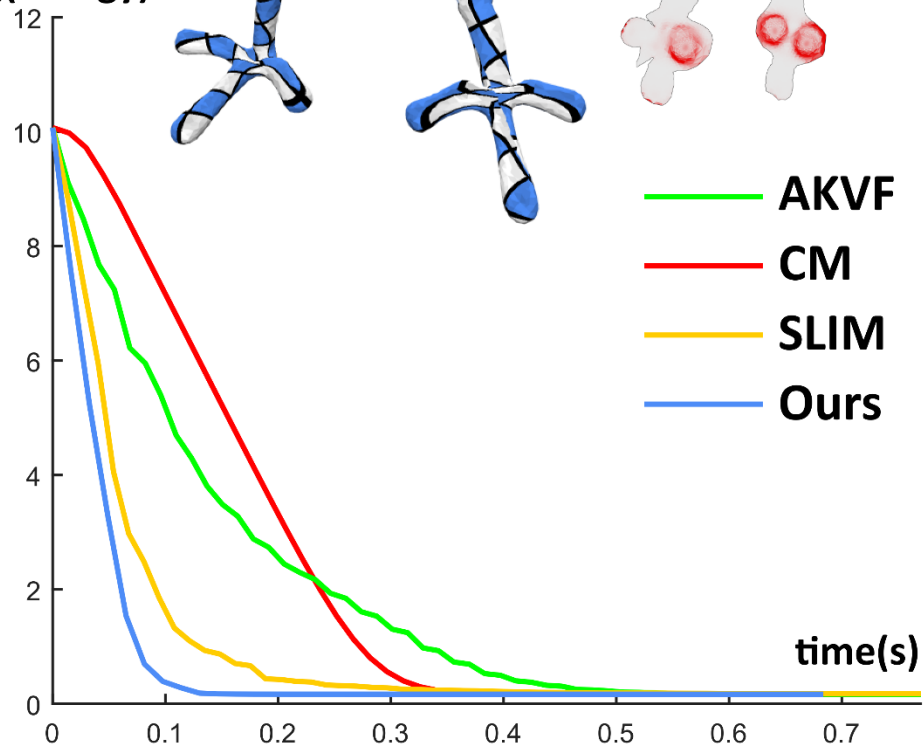
time(s)



$\mathcal{D}_2$

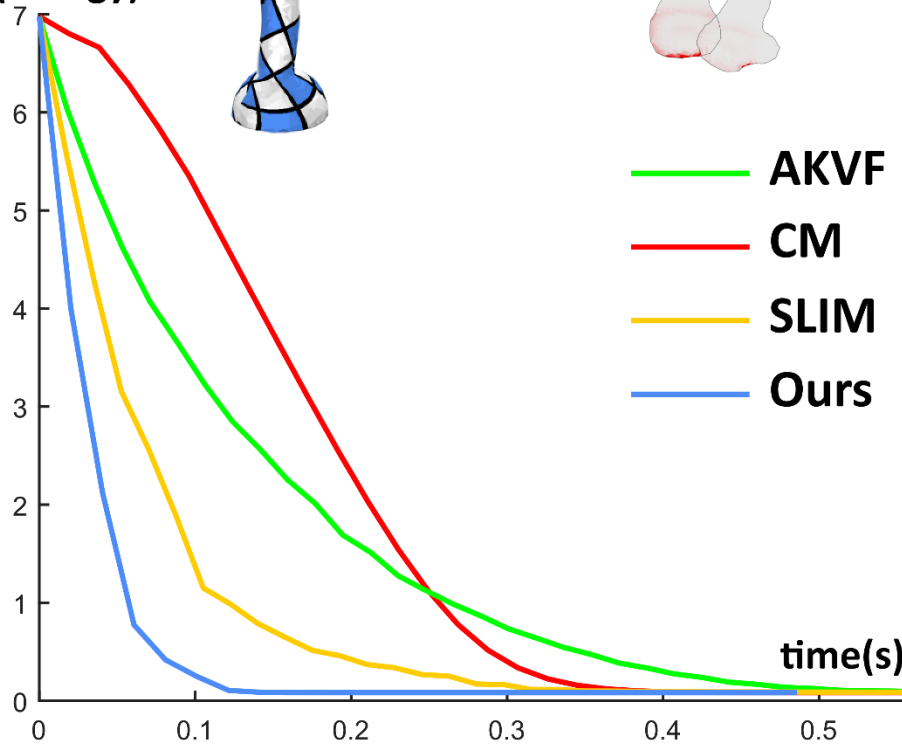


Log(energy)



- AKVF
- CM
- SLIM
- Ours

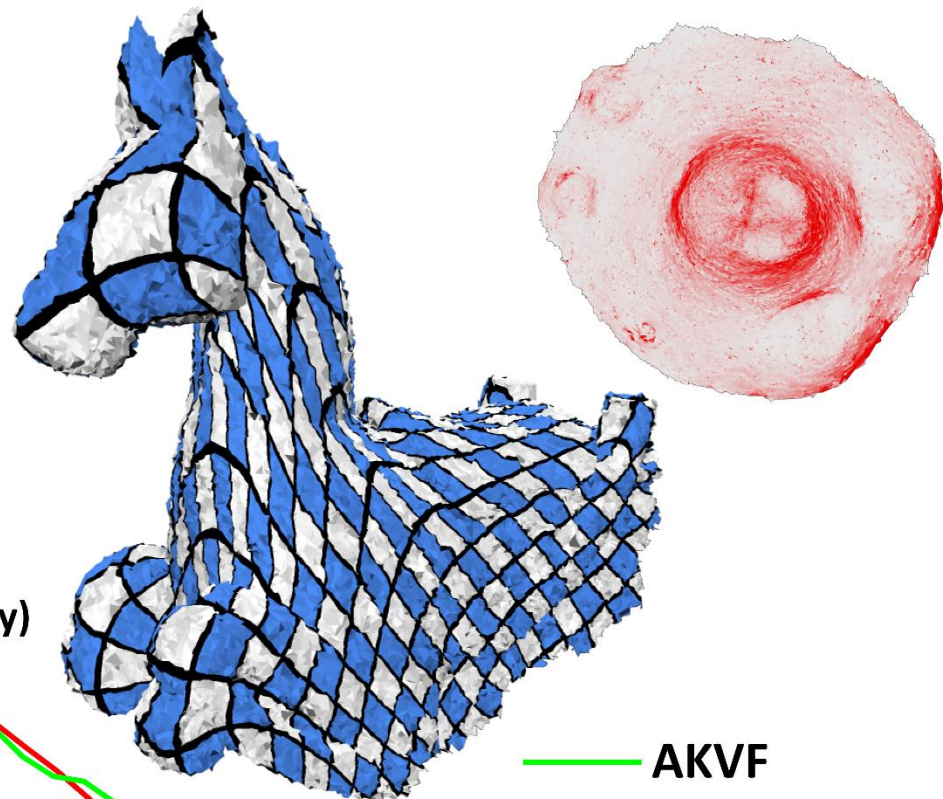
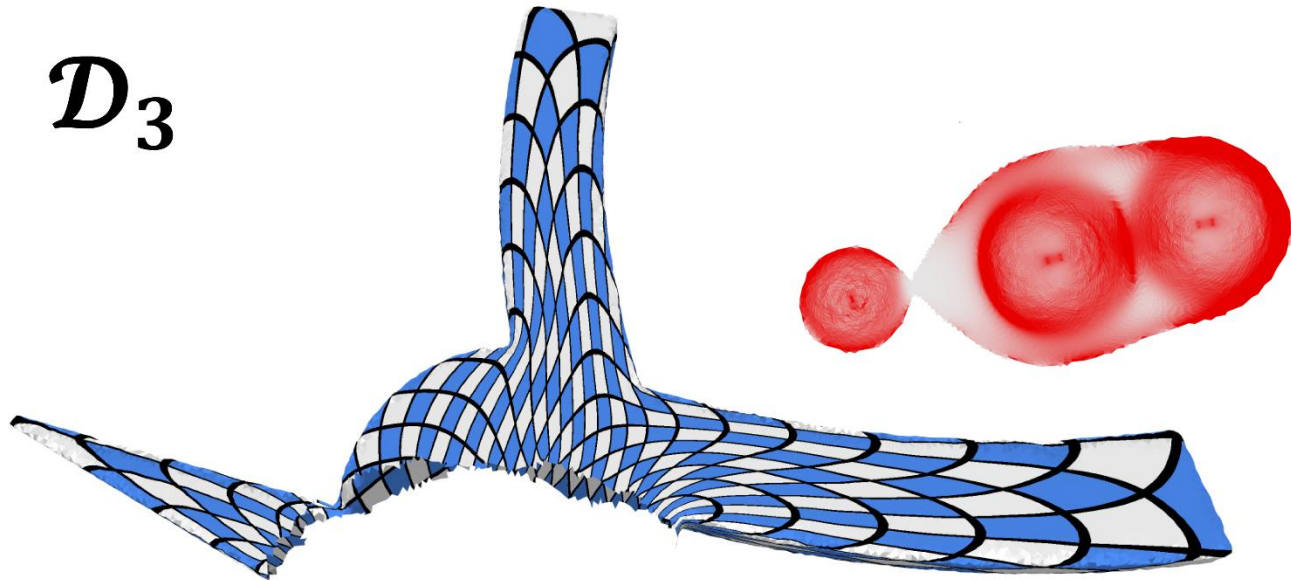
Log(energy)



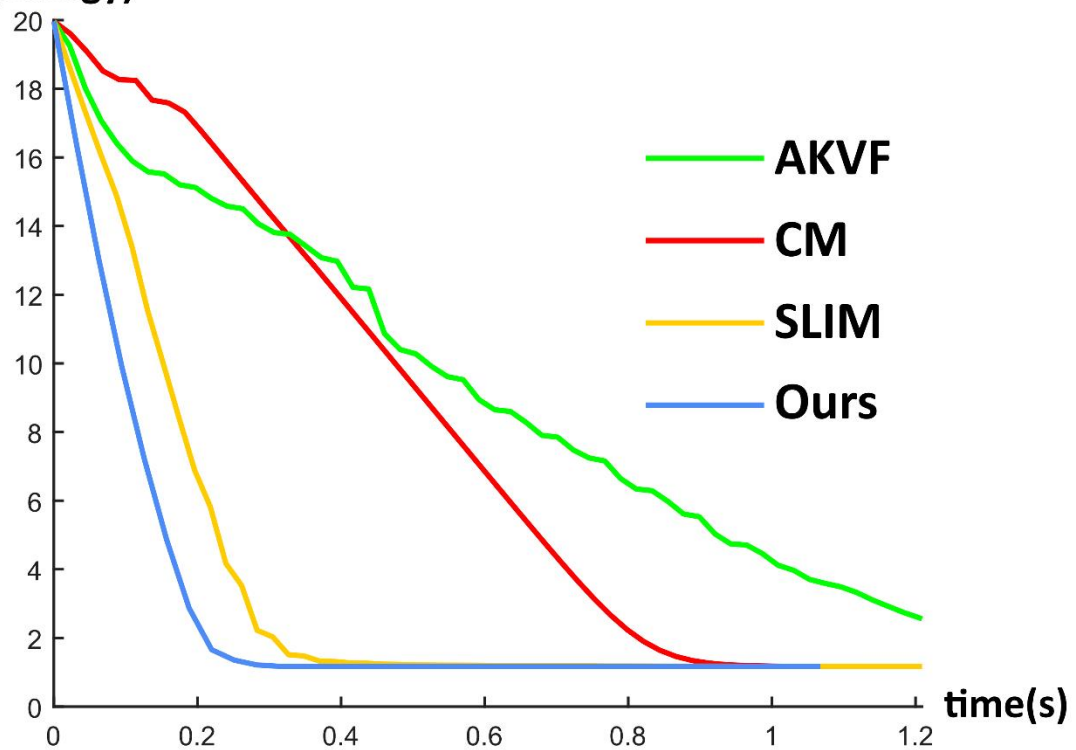
- AKVF
- CM
- SLIM
- Ours



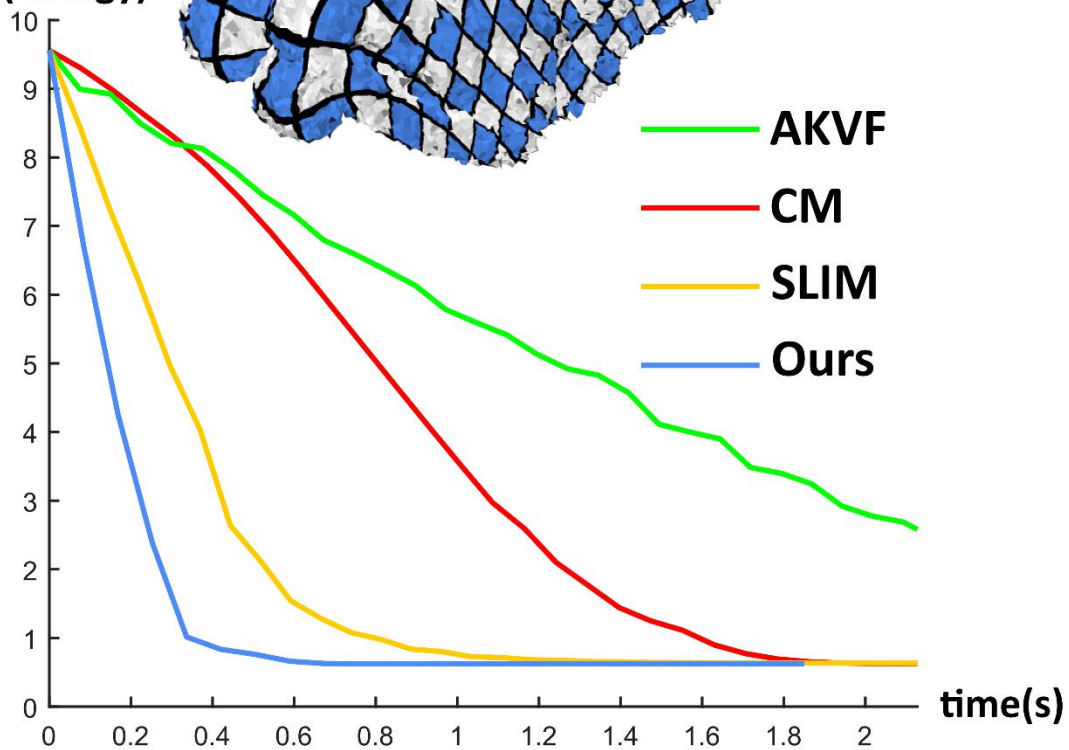


$\mathcal{D}_3$ 

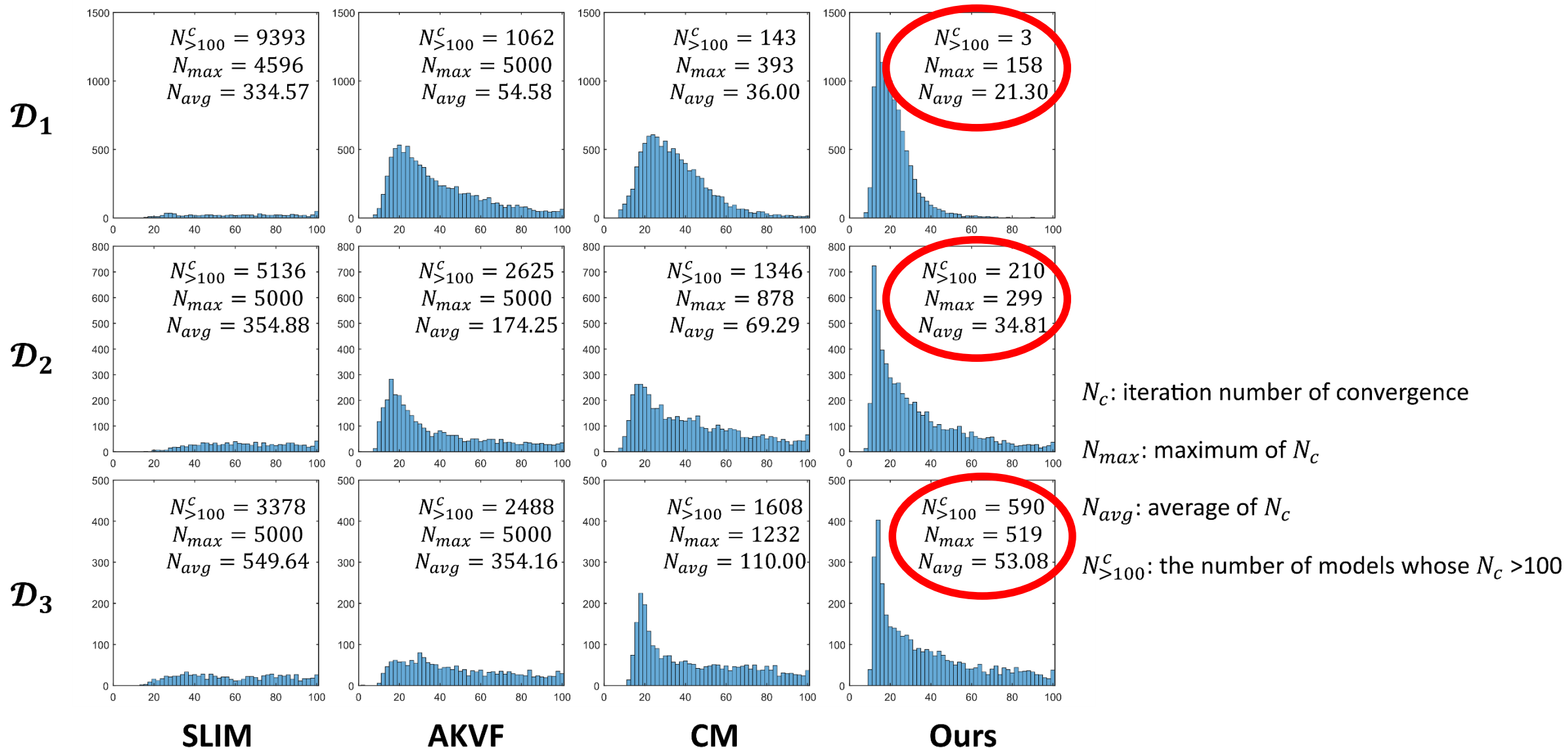
Log(energy)



Log(energy)



# Distributions of iteration number

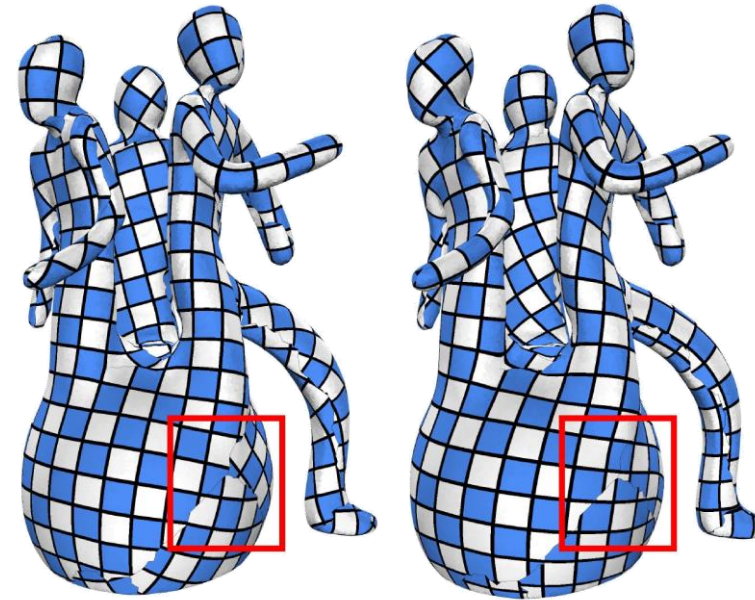


# Conclusions

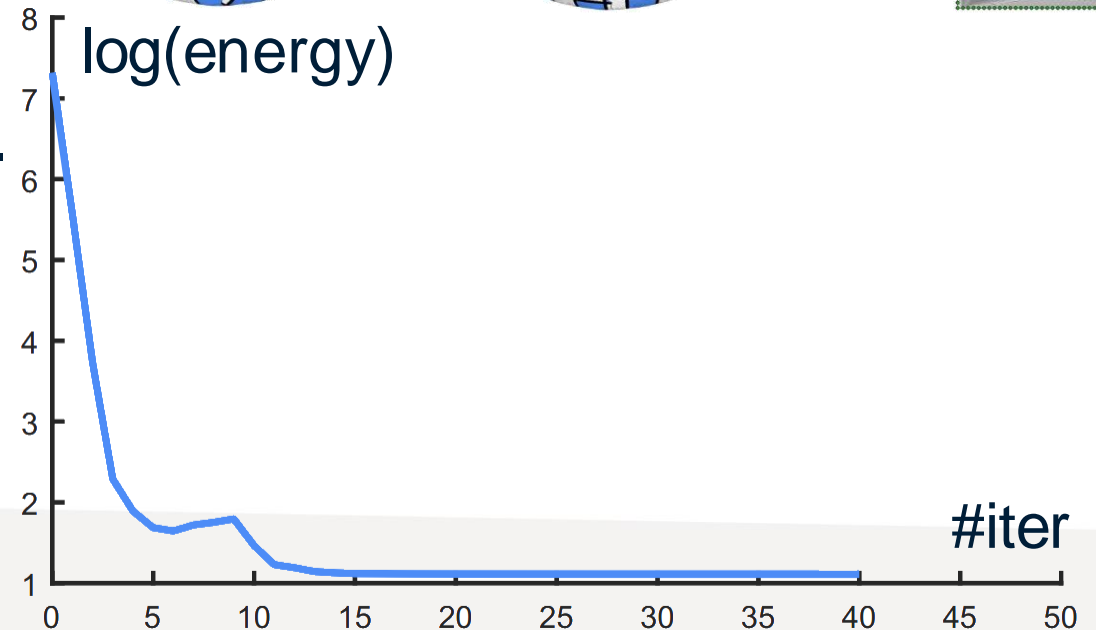
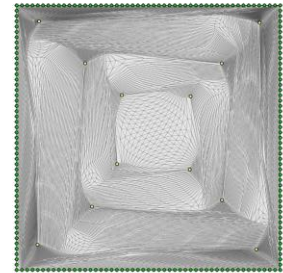
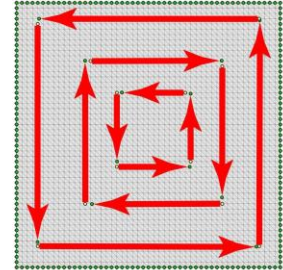
- Progressive parameterizations: a novel and simple method to generate low isometric distortion parameterizations with no foldovers.
- ✓ Thinks from the view of reference triangle.
- ✓ Exhibits strong practical reliability and high efficiency.
- ✓ Demonstrates the practical robustness on a large data set containing 20712 models

# Limitations

- Cannot fit constraint condition well.
- No theoretical guarantee to reduce  $E(M, M^p)$  monotonously.



GENERATIONS / VANCOUVER  
12-16 AUGUST  
SIGGRAPH2018





GENERATIONS / VANCOUVER  
12-16 AUGUST  
SIGGRAPH2018

# Thank you!



<http://staff.ustc.edu.cn/~fuxm/projects/ProgressivePara/>