



# Mesh Data Structures

Ligang Liu

Graphics&Geometric Computing Lab

USTC

<http://staff.ustc.edu.cn/~lgliu>

# Uses of Mesh Data

- Rendering
  - Triangle trip
- Geometry queries
  - What are the vertices of face  $\#k$ ?
  - Are vertices  $\#i$  and  $\#j$  adjacent?
  - Which faces are adjacent face  $\#k$ ?
- Geometry operations
  - Remove/add a vertex/face
  - Mesh simplification
  - Vertex split, edge collapse

# Storing Mesh Data (1)

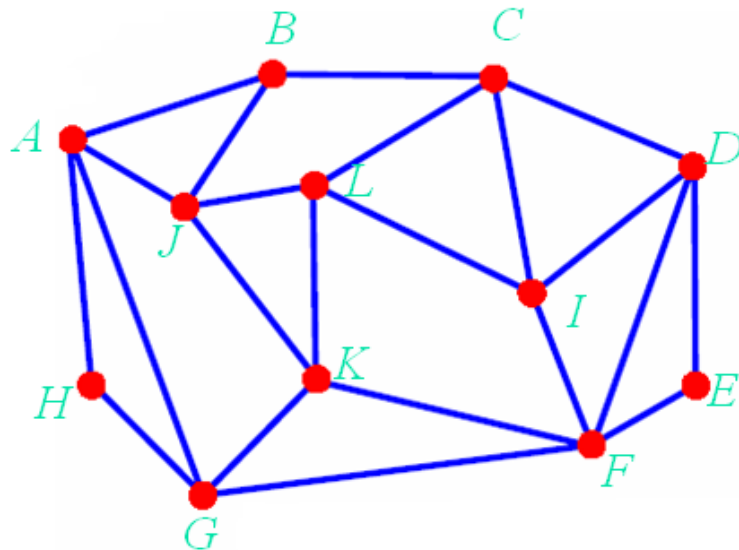
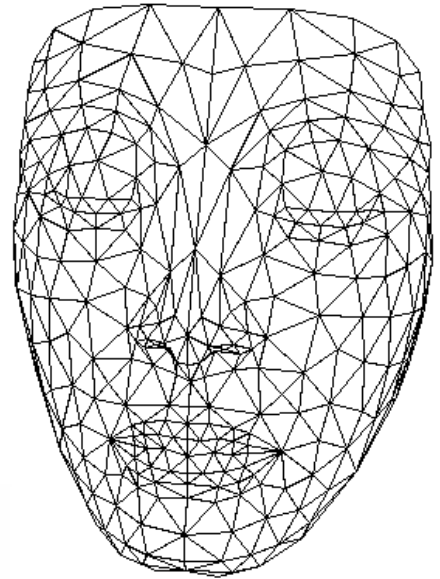
- Storage of generic meshes
  - Hard to implement efficiently
- Assume
  - Triangular
  - Orientable
  - Manifold

# Storing Mesh Data (2)

- How “good” is a data structure?
  - Space complexity
  - Time
    - Time to construct - preprocessing
    - Time to answer a query
    - Time to perform an operation (update the data structure)
  - Trade-off between time and space
  - Redundancy

# Define a Mesh (1)

- Geometry
  - Vertex coordinates
- Connectivity
  - How do vertices connected?



# Define a Mesh (2)

- List of Edge
- Vertex-Edge
- Vertex-Face
- Combined

# 3D Mesh Surface

- Surface & material properties
  - Material color
  - Ambient, highlight coefficients
  - Texture coordinates
  - BRDF, BTF
- Rendering properties
  - Lighting
  - Normals
  - Rendering modes

# General Used Mesh Files

- General used mesh files
  - Wavefront OBJ (\*.obj)
  - 3D Max (\*.max, \*.3ds)
  - VRML(\*.vrl)
  - Inventor (\*.iv)
  - PLY (\*.ply, \*.ply2)
  - User-defined(\*.m, \*.liu)
- Storage
  - Text – (Recommended)
  - Binary



# Wavefront OBJ File Format

- Vertices
  - Start with char 'v'
  - (x,y,z) coordinates
- Faces
  - Start with char 'f'
  - Indices of its vertices in the file
- Other properties
  - Normal, texture coordinates, material, etc.

```
v 1.0 0.0 0.0  
v 0.0 1.0 0.0  
v 0.0 -1.0 0.0  
v 0.0 0.0 1.0  
f 1 2 3  
f 1 4 2  
f 3 2 4  
f 1 3 4
```

# Mesh Viewer Tools

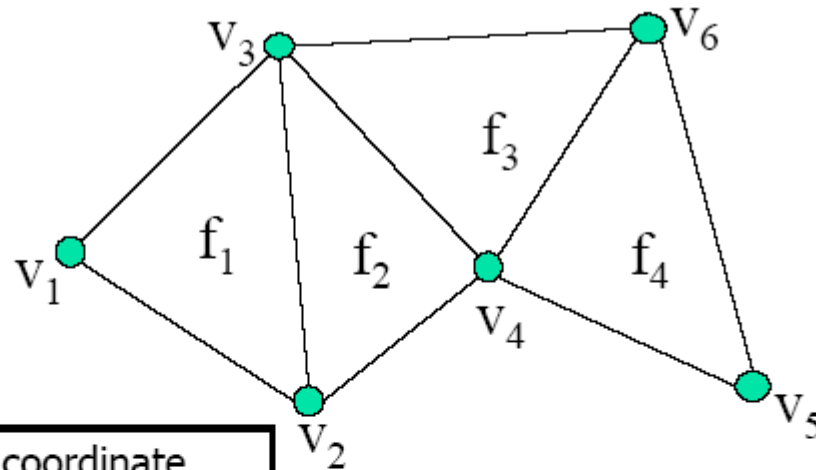
- Commercial tools
  - 3D Exploration
    - <http://www.xdsoft.com/explorer/>
  - 3D Win
    - <http://www.3d-win.com/>
- User Written Viewers
  - Too many on the internet

# List of Faces

# List of Faces

- List of vertices
  - Position coordinates
- List of faces
  - Triplets of pointers to face vertices (c1,c2,c3)
- Queries:
  - What are the vertices of face #3?
    - Answered in  $O(1)$  - checking third triplet
  - Are vertices  $i$  and  $j$  adjacent?
    - A pass over all faces is necessary – NOT GOOD

# List of Faces – Example



vertex	coordinate
$v_1$	$(x_1, y_1, z_1)$
$v_2$	$(x_2, y_2, z_2)$
$v_3$	$(x_3, y_3, z_3)$
$v_4$	$(x_4, y_4, z_4)$
$v_5$	$(x_5, y_5, z_5)$
$v_6$	$(x_6, y_6, z_6)$

face	vertices (ccw)
$f_1$	$(v_1, v_2, v_3)$
$f_2$	$(v_2, v_4, v_3)$
$f_3$	$(v_3, v_4, v_6)$
$f_4$	$(v_4, v_5, v_6)$

# List of Faces – Analysis

- Pros:
  - Convenient and efficient (memory wise)
  - Can represent non-manifold meshes
- Cons:
  - Too simple - not enough information on relations between vertices & faces

# Adjacency Matrix

# Adjacency Matrix – Definition

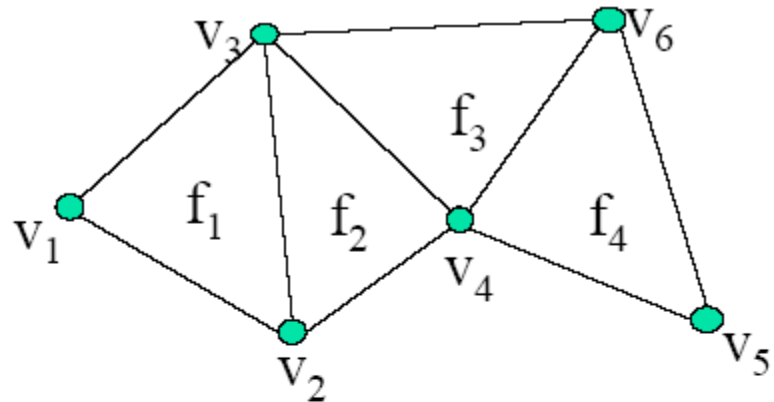
- View mesh as connected graph
- Given  $n$  vertices build  $n \times n$  matrix of adjacency information
  - Entry  $(i,j)$  is TRUE value if vertices  $i$  and  $j$  are adjacent
- Geometric info
  - list of vertex coordinates
- Add faces
  - list of triplets of vertex indices  $(v_1, v_2, v_3)$



# Adjacency Matrix – Example

vertex	coordinate
$v_1$	$(x_1, y_1, z_1)$
$v_2$	$(x_2, y_2, z_2)$
$v_3$	$(x_3, y_3, z_3)$
$v_4$	$(x_4, y_4, z_4)$
$v_5$	$(x_5, y_5, z_5)$
$v_6$	$(x_6, y_6, z_6)$

face	vertices (ccw)
$f_1$	$(v_1, v_2, v_3)$
$f_2$	$(v_2, v_4, v_3)$
$f_3$	$(v_3, v_4, v_6)$
$f_4$	$(v_4, v_5, v_6)$



	$v_1$	$v_2$	$v_3$	$v_4$	$v_5$	$v_6$
$v_1$		1	1			
$v_2$	1		1	1		
$v_3$	1	1		1		1
$v_4$		1	1		1	1
$v_5$				1		1
$v_6$			1	1	1	

# Adjacency Matrix – Queries

- What are the vertices of face #3?
  - $O(1)$  – checking third triplet of faces
- Are vertices  $i$  and  $j$  adjacent?
  - $O(1)$  - checking adjacency matrix at location  $(i,j)$ .
- Which faces are adjacent to vertex  $j$ ?
  - Full pass on all faces is necessary

# Adjacency Matrix – Analysis

- Pros:
  - Information on vertices adjacency
  - Stores non-manifold meshes
- Cons:
  - Connects faces to their vertices, BUT NO connection between vertex and its face

# Doubly-Connected Edge List (DCEL)

# DCEL

- Record for each face, edge and vertex:
  - Geometric information
  - Topological information
  - Attribute information
- Half-Edge Structure

# DCEL (cont.)

- Vertex record:

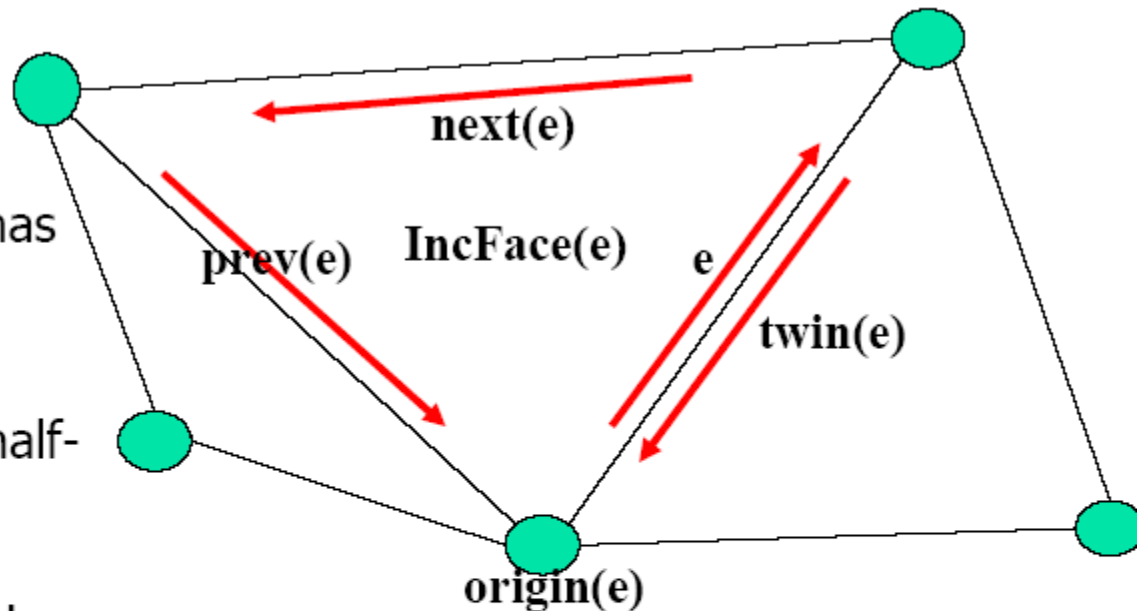
- Coordinates
- Pointer to one half-edge that has  $v$  as its origin

- Face record:

- Pointer to one half-edge on its boundary

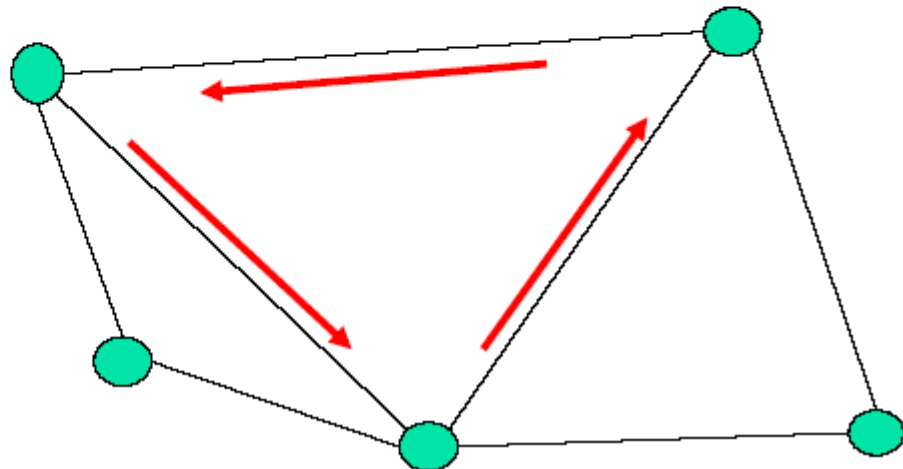
- Half-edge record:

- Pointer to its origin,  $\text{origin}(e)$
- Pointer to its twin half-edge,  $\text{twin}(e)$
- Pointer to the face it bounds,  $\text{IncidentFace}(e)$  (face lies to left of  $e$  when traversed from origin to destination)
- Next and previous edge on boundary of  $\text{IncidentFace}(e)$

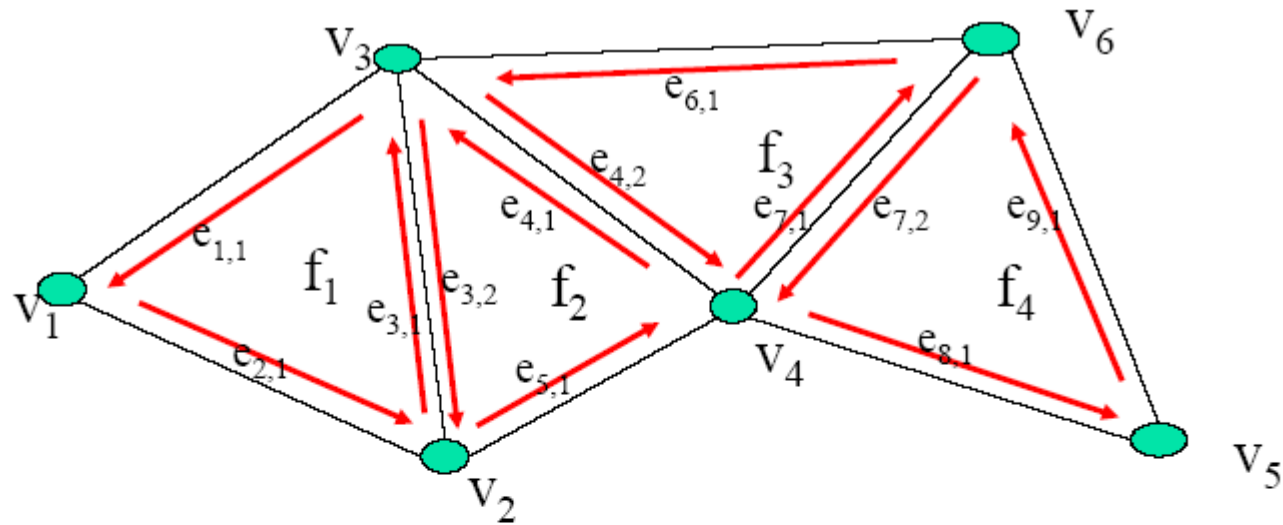


# DCEL(cont.)

- Operations supported:
  - Walk around boundary of given face
  - Visit all edges incident to vertex  $v$
- Queries:
  - Most queries are  $O(1)$



# DCEL – Example

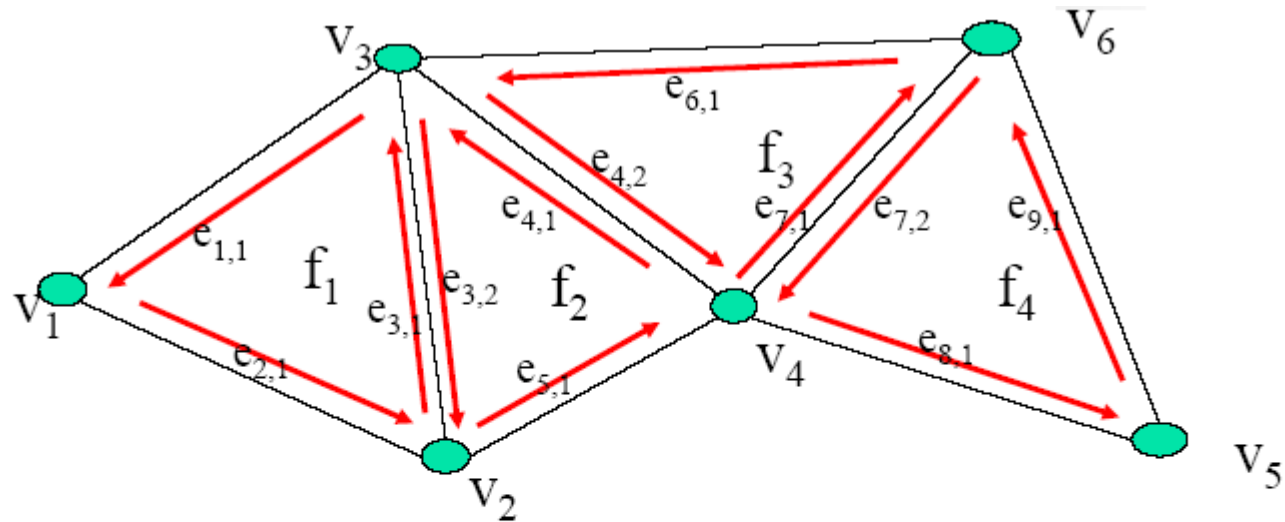


Vertex	coordinate	IncidentEdge
$V_1$	$(x_1, y_1, z_1)$	$e_{2,1}$
$v_2$	$(x_2, y_2, z_2)$	$e_{5,1}$
$v_3$	$(x_3, y_3, z_3)$	$e_{1,1}$
$v_4$	$(x_4, y_4, z_4)$	$e_{7,1}$
$v_5$	$(x_5, y_5, z_5)$	$e_{9,1}$
$v_6$	$(x_6, y_6, z_6)$	$e_{7,2}$

face	edge
$f_1$	$e_{1,1}$
$f_2$	$e_{5,1}$
$f_3$	$e_{4,2}$
$f_4$	$e_{8,1}$



# DCEL – Example (cont.)



Half-edge	origin	twinn	IncidentFace	next	prev
$e_{3,1}$	$v_2$	$e_{3,2}$	$f_1$	$e_{1,1}$	$e_{2,1}$
$e_{3,2}$	$v_3$	$e_{3,1}$	$f_2$	$e_{5,1}$	$e_{4,1}$
$e_{4,1}$	$v_4$	$e_{4,2}$	$f_2$	$e_{3,2}$	$e_{5,1}$
$e_{4,2}$	$v_3$	$e_{4,1}$	$f_3$	$e_{7,1}$	$e_{6,1}$

# DCEL – Analysis

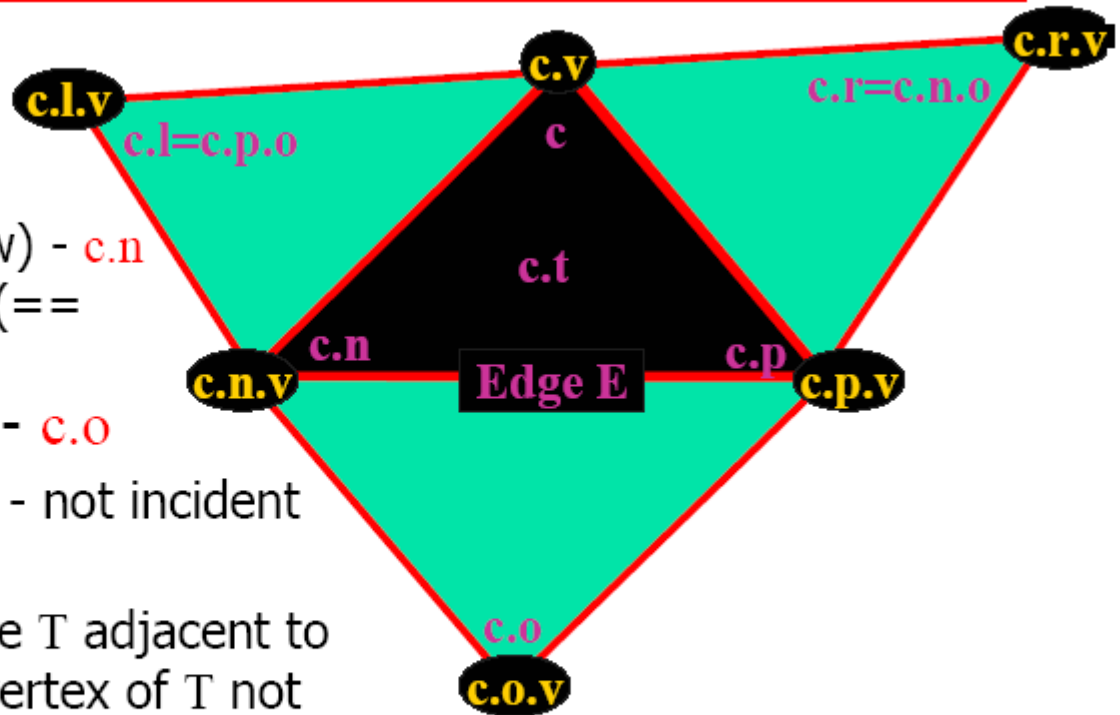
- Pros
  - All queries in  $O(1)$  time
  - All operations are  $O(1)$  (usually)
- Cons
  - Represents only manifold meshes

# Corner Table

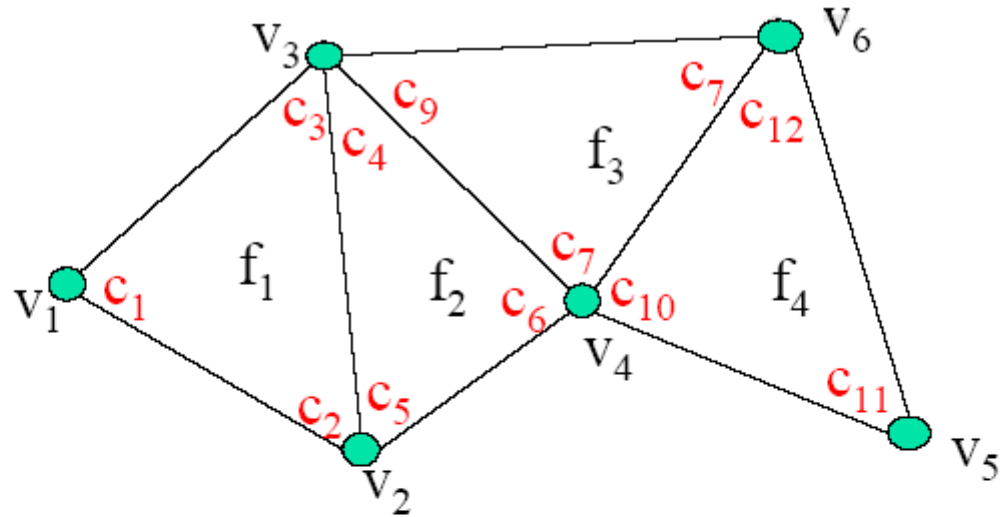
**Corner : Coupling of vertex with one of its incident triangles**

Corner  $c$  contains:

- Triangle –  $c.t$
- Vertex –  $c.v$
- Next corner in  $c.t$  (ccw) -  $c.n$
- Previous corner -  $c.p$  ( $== c.n.n$ )
- Corner opposite  $c$  -  $c.o$ 
  - E edge opposite  $c$  - not incident on  $c.v$
  - $c.o$  couples triangle  $T$  adjacent to  $c.t$  across  $E$  with vertex of  $T$  not incident on  $E$ 
    - Right corner -  $c.r$  - corner opposite  $c.n$  ( $== c.n.o$ ).
    - Left corner -  $c.l$  ( $== c.p.o == c.n.n.o$ )



# Corner Table – Example



corner	c.v	c.t	c.n	c.p	c.o	c.r	c.l
$c_1$	$v_1$	$f_1$	$c_2$	$c_3$	$c_6$	NULL	NULL
$c_2$	$v_2$	$f_1$	$c_3$	$c_1$	NULL	NULL	$c_6$
$c_3$	$v_3$	$f_1$	$c_1$	$c_2$	NULL	$c_6$	NULL
$c_4$	$v_3$	$f_2$	$c_5$	$c_6$	NULL	$c_7$	$c_1$
$c_5$	$v_2$	$f_2$	$c_6$	$c_4$	$c_7$	$c_1$	NULL
$c_6$	$v_4$	$f_2$	$c_4$	$c_5$	$c_1$	NULL	$c_7$

# Example Queries

- What are the vertices of face #3?
  - Check **c.v** of corners 9, 10, 11
- Are vertices  $i$  and  $j$  adjacent?
  - Scan all corners of vertex  $i$ , check if **c.p.v** or **c.n.v** are  $j$
- Which faces are adjacent to vertex  $j$ ?
  - Check **c.t** of all corners of vertex  $j$

# Corner Table – Analysis

- Pros
  - All queries in  $O(1)$  time
  - All operations are  $O(1)$  (usually)
- Cons
  - Represents only manifold meshes
  - High redundancy (but not too high ...)

# Mesh Programming

- Use a good mesh library
  - CGAL
  - OpenMesh
  - MeshMaker
  - My own lib
- Practice, practice, practice
  - If you never try, you never know.
- Enjoying coding 😊



# Q&A