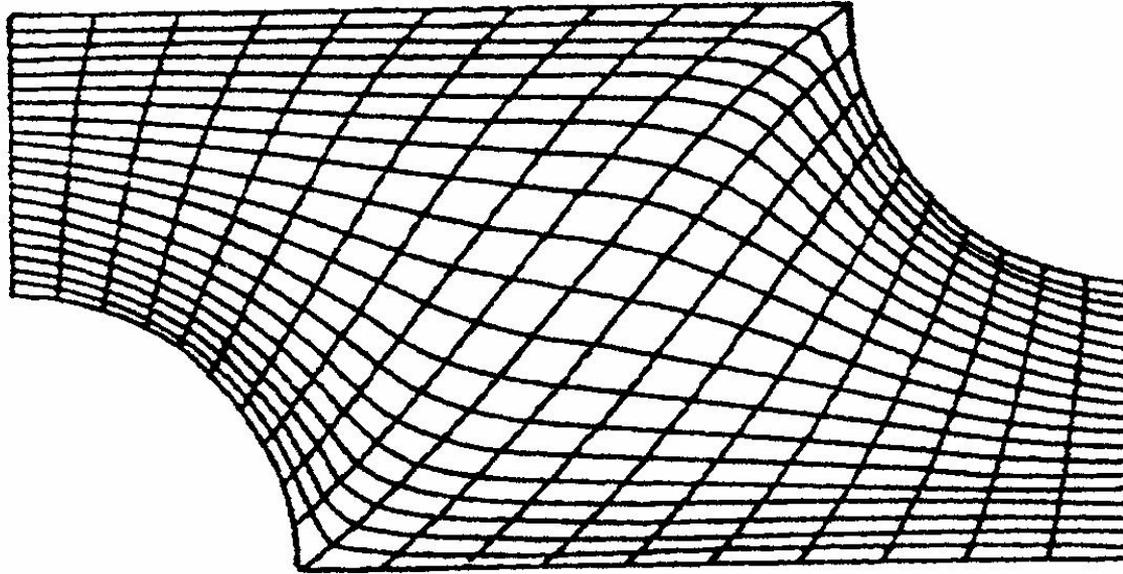


9.2 贴体坐标和贴体坐标转换



胡茂彬

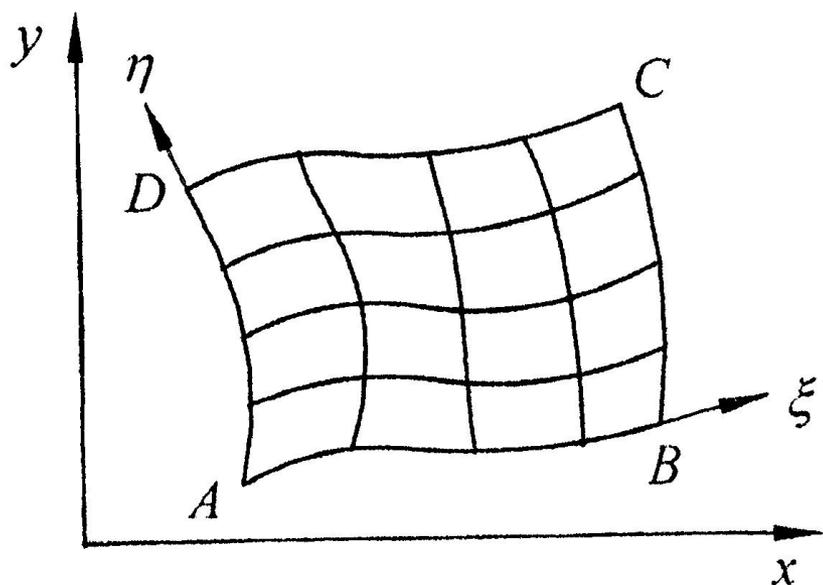
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1 贴体坐标

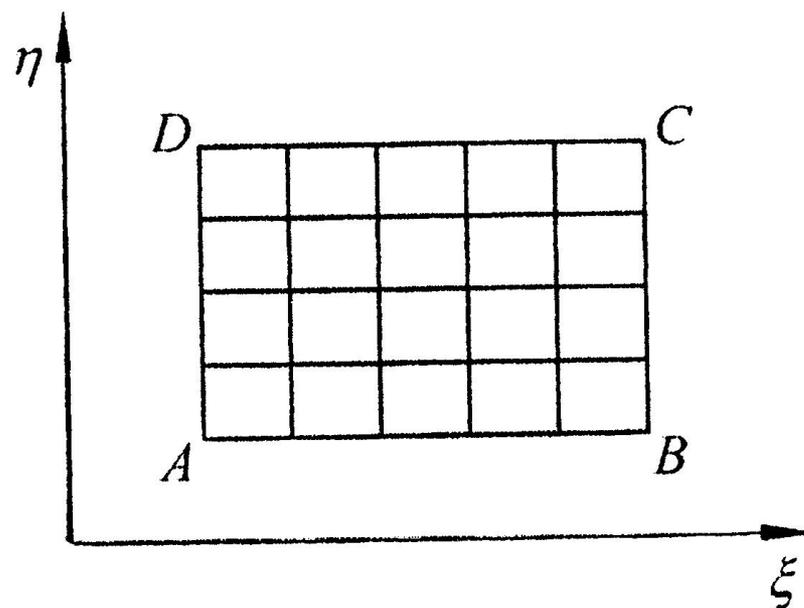
- 理想的坐标系：求解区域边界与坐标系的坐标轴一一相符合。
- 直角坐标系 - 矩形区域
- 极坐标 - 圆形区域
- 球坐标 - 球形区域
- 称为贴体坐标 (或适体坐标)。在贴体坐标下所建立的计算网格，就叫贴体网格。

2 贴体坐标转换

- 对于一般的复杂求解区域，需要采用坐标转换，构造与之相适应的贴体坐标系



(a) x - y 物理平面



(b) ξ - η 计算平面

坐标转换

正变换:

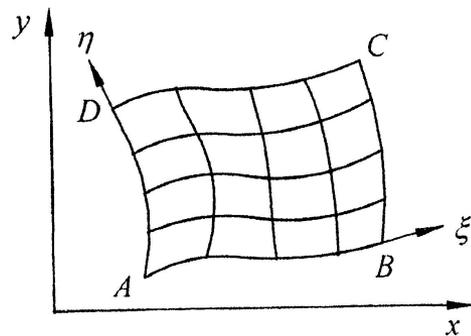
$$\xi = \xi(x, y)$$

$$\eta = \eta(x, y)$$

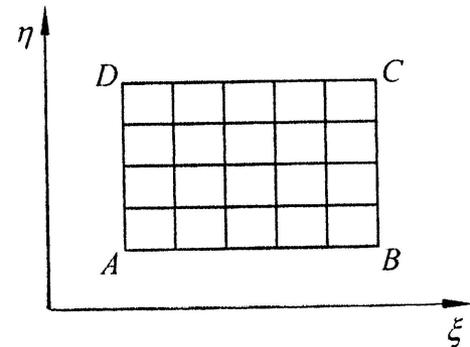
反变换:

$$x = x(\xi, \eta)$$

$$y = y(\xi, \eta)$$



(a) x - y 物理平面



(b) ξ - η 计算平面

贴体网格生成: 找到**计算平面**网格节点坐标 (ξ, η)
对应的**物理平面**网格节点坐标 (x, y)

贴体坐标转换的基本要求

- 1 转换函数单值，转换节点一一对应
- 2 物理平面的网格线光滑，提供连续的转换导数
- 3 物理平面上的网格疏密程度易于控制
- 4 网格线尽可能避免过于倾斜，以减小截断误差
- 5 网格线尽可能与边界垂直，以利处理边界条件

3 适体坐标系下的导数变换

正变换:

$$\xi = \xi(x, y)$$
$$\eta = \eta(x, y)$$

反变换:

$$x = x(\xi, \eta)$$
$$y = y(\xi, \eta)$$



$$d\xi = \xi_x dx + \xi_y dy$$
$$d\eta = \eta_x dx + \eta_y dy$$

$$dx = x_\xi d\xi + x_\eta d\eta$$
$$dy = y_\xi d\xi + y_\eta d\eta$$

矩阵形式:

$$\begin{pmatrix} d\xi \\ d\eta \end{pmatrix} = \begin{pmatrix} \xi_x & \xi_y \\ \eta_x & \eta_y \end{pmatrix} \begin{pmatrix} dx \\ dy \end{pmatrix}$$

$$\begin{pmatrix} dx \\ dy \end{pmatrix} = \begin{pmatrix} x_\xi & x_\eta \\ y_\xi & y_\eta \end{pmatrix} \begin{pmatrix} d\xi \\ d\eta \end{pmatrix}$$

坐标转换的Jacobi行列式 (Jacobi因子)

$$\begin{pmatrix} \xi_x & \xi_y \\ \eta_x & \eta_y \end{pmatrix} = \begin{pmatrix} x_\xi & x_\eta \\ y_\xi & y_\eta \end{pmatrix}^{-1} = \frac{1}{J} \begin{pmatrix} y_\eta & -x_\eta \\ -y_\xi & x_\xi \end{pmatrix}$$

其中

$$J = \begin{vmatrix} x_\xi & x_\eta \\ y_\xi & y_\eta \end{vmatrix} = x_\xi y_\eta - x_\eta y_\xi = \begin{vmatrix} \xi_x & \xi_y \\ \eta_x & \eta_y \end{vmatrix}^{-1}$$

转换坐标变量之间的微分关系

$$\xi_x = \frac{y_\eta}{J}, \quad \xi_y = \frac{-x_\eta}{J}, \quad \eta_x = \frac{-y_\xi}{J}, \quad \eta_y = \frac{x_\xi}{J}$$

坐标变换式的度量系数

度量系数

- **度量系数**：应当用有限差分方法确定，而不应按变换的分析式计算
- **度量系数**：不应采用插值方法确定，而应直接按各节点的坐标值用差分式计算，节点的坐标值如果需要则可以采用插值方法确定

导数变换关系

一阶偏导数

$$\frac{\partial}{\partial x} = \frac{y_\eta}{J} \frac{\partial}{\partial \xi} - \frac{y_\xi}{J} \frac{\partial}{\partial \eta}, \quad \frac{\partial}{\partial y} = -\frac{x_\eta}{J} \frac{\partial}{\partial \xi} + \frac{x_\xi}{J} \frac{\partial}{\partial \eta}$$

二阶偏导数

$$\begin{aligned} \frac{\partial^2}{\partial x^2} &= \frac{\partial}{\partial x} \left(\frac{y_\eta}{J} \frac{\partial}{\partial \xi} - \frac{y_\xi}{J} \frac{\partial}{\partial \eta} \right) = \frac{y_\eta}{J} \frac{\partial}{\partial \xi} \left(\frac{y_\eta}{J} \frac{\partial}{\partial \xi} \right) - \frac{y_\xi}{J} \frac{\partial}{\partial \eta} \left(\frac{y_\eta}{J} \frac{\partial}{\partial \xi} \right) \\ &+ \frac{y_\eta}{J} \frac{\partial}{\partial \xi} \left(-\frac{y_\xi}{J} \frac{\partial}{\partial \eta} \right) - \frac{y_\xi}{J} \frac{\partial}{\partial \eta} \left(-\frac{y_\xi}{J} \frac{\partial}{\partial \eta} \right) \end{aligned}$$

二阶偏导数:

$$\begin{aligned}\frac{\partial^2}{\partial y^2} &= \frac{\partial}{\partial y} \left(-\frac{x_\eta}{J} \frac{\partial}{\partial \xi} + \frac{x_\xi}{J} \frac{\partial}{\partial \eta} \right) = -\frac{x_\eta}{J} \frac{\partial}{\partial \xi} \left(-\frac{x_\eta}{J} \frac{\partial}{\partial \xi} \right) \\ &+ \frac{x_\xi}{J} \frac{\partial}{\partial \eta} \left(-\frac{x_\eta}{J} \frac{\partial}{\partial \xi} \right) - \frac{x_\eta}{J} \frac{\partial}{\partial \xi} \left(\frac{x_\xi}{J} \frac{\partial}{\partial \eta} \right) + \frac{x_\xi}{J} \frac{\partial}{\partial \eta} \left(\frac{x_\xi}{J} \frac{\partial}{\partial \eta} \right)\end{aligned}$$

交叉偏导数:

$$\begin{aligned}\frac{\partial^2}{\partial x \partial y} &= \frac{\partial}{\partial y} \left(\frac{y_\eta}{J} \frac{\partial}{\partial \xi} - \frac{y_\xi}{J} \frac{\partial}{\partial \eta} \right) = \frac{-x_\eta}{J} \frac{\partial}{\partial \xi} \left(\frac{y_\eta}{J} \frac{\partial}{\partial \xi} \right) + \frac{x_\xi}{J} \frac{\partial}{\partial \eta} \left(\frac{y_\eta}{J} \frac{\partial}{\partial \xi} \right) \\ &- \frac{x_\eta}{J} \frac{\partial}{\partial \xi} \left(-\frac{y_\xi}{J} \frac{\partial}{\partial \eta} \right) + \frac{x_\xi}{J} \frac{\partial}{\partial \eta} \left(-\frac{y_\xi}{J} \frac{\partial}{\partial \eta} \right)\end{aligned}$$

Laplace 算子转换到 计算平面

$$\begin{aligned} \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} = & \frac{1}{J^2} \left\{ (x_\eta^2 + y_\eta^2) \frac{\partial^2}{\partial \xi^2} + (x_\xi^2 + y_\xi^2) \frac{\partial^2}{\partial \eta^2} \right. \\ & - 2(x_\xi x_\eta + y_\xi y_\eta) \frac{\partial^2}{\partial \eta \partial \xi} + (x_\eta x_{\xi\eta} + y_\eta y_{\xi\eta} - x_\xi x_{\eta\eta} - y_\xi y_{\eta\eta}) \frac{\partial}{\partial \xi} \\ & + (x_\xi x_{\xi\eta} + y_\xi y_{\xi\eta} - x_\eta x_{\xi\xi} - y_\eta y_{\xi\xi}) \frac{\partial}{\partial \eta} - (x_\eta^2 + y_\eta^2) \frac{J_\xi}{J} \frac{\partial}{\partial \xi} \\ & \left. - (x_\xi^2 + y_\xi^2) \frac{J_\eta}{J} \frac{\partial}{\partial \eta} + (x_\xi x_\eta + y_\xi y_\eta) \frac{J_\eta}{J} \frac{\partial}{\partial \xi} + (x_\xi x_\eta + y_\xi y_\eta) \frac{J_\xi}{J} \frac{\partial}{\partial \eta} \right\} \end{aligned}$$

Laplace 算子表达式简化形式

$$\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} = \frac{1}{J^2} \left[\alpha \frac{\partial^2}{\partial \xi^2} - 2\beta \frac{\partial^2}{\partial \xi \partial \eta} + \gamma \frac{\partial^2}{\partial \eta^2} + \tau \frac{\partial}{\partial \xi} + \sigma \frac{\partial}{\partial \eta} \right]$$

其中

$$\alpha = x_\eta^2 + y_\eta^2, \quad \beta = x_\xi x_\eta + y_\xi y_\eta, \quad \gamma = x_\xi^2 + y_\xi^2$$

$$\tau = (x_\eta D_y - y_\eta D_x) / J, \quad \sigma = (y_\xi D_x - x_\xi D_y) / J$$

$$D_x = \alpha x_{\xi\xi} - 2\beta x_{\xi\eta} + \gamma x_{\eta\eta}, \quad D_y = \alpha y_{\xi\xi} - 2\beta y_{\xi\eta} + \gamma y_{\eta\eta}$$

4 应用贴体坐标解题过程

- 1) **生成贴体网格**：在**计算平面**上选定与**物理平面**上复杂求解域相对应的求解区域，给定边界条件，求出两平面内节点的对应关系
- 2) 将控制方程和定解条件在贴体坐标下写出并离散
- 3) 在**计算平面求解**离散代数方程，并将**解传递回**物理平面