

## Physics

Special Topic: Active Matter

## Effective diffusion of a tracer in active bath: A path-integral approach

Mengkai Feng\* &amp; Zhonghuai Hou\*

Hefei National Research Center for Physical Sciences at the Microscale & Key Laboratory of Precision and Intelligent Chemistry, University of Science and Technology of China, Hefei 230026, China

\*Corresponding authors (emails: [fengmk@ustc.edu.cn](mailto:fengmk@ustc.edu.cn) (Mengkai Feng); [hzhlj@ustc.edu.cn](mailto:hzhlj@ustc.edu.cn) (Zhonghuai Hou))

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**Abstract:** We investigate the effective diffusion of a tracer immersed in an active particle bath consisting of self-propelled particles. Utilising the Dean's method developed for the equilibrium bath and extending it to the nonequilibrium situation, we derive a generalized Langevin equation (GLE) for the tracer particle. The complex interactions between the tracer and bath particles are shown as a memory kernel term and two colored noise terms. To obtain the effective diffusivity of the tracer, we use path integral technique to calculate all necessary correlation functions. Calculations show the effective diffusion decreases with the persistent time of active force, and has rich behavior with the number density of bath particles, depending on different activities. All theoretical results regarding the dependence of such diffusivity on bath parameters have been confirmed by direct computer simulation.

**Keywords:** active matter, nonequilibrium statistical mechanics, active bath, mean-field theory, path integral, tracer diffusivity

### INTRODUCTION

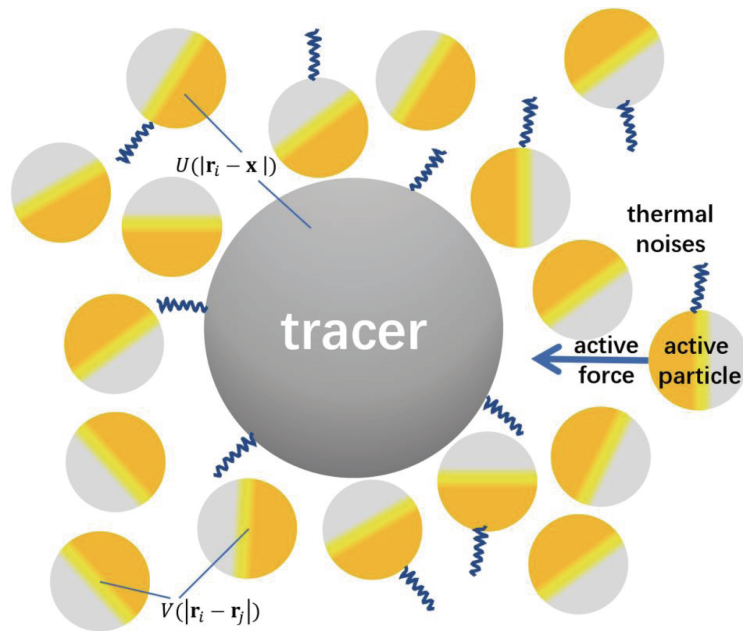
Active matter systems, consisting of self-propelled units that are able to convert stored or surrounding energy into their persistent motion, provide a fresh opportunity for applications of nonequilibrium statistical mechanics [1–4]. In particular, active colloidal suspension can serve as an active bath that can significantly influence the motion and dynamics of passive objects submerged within them [5–12]. Understanding the behavior of tracer particles in the active bath is a fundamental pursuit in statistical physics and plays a crucial role in various biological [10, 13–16], chemical [17, 18], and physical phenomena [8, 9, 12, 19–32]. Notably, the tracer particle immersed in the active bath exhibits a distinct diffusion profile compared to its equilibrium counterpart [26, 33–39]. Furthermore, studying the diffusion behavior of such a tracer is essential for unraveling the intricate dynamics that govern systems away from thermal equilibrium, providing a valuable tool to investigate the collective behavior [8, 40–46] and transport properties in such media [47–51]. Because of the importance and wide range of applications, understanding the dynamics of the tracer in such an active bath is desirable.

As one already knows, the classical work by Einstein laid the foundation for understanding Brownian motion, providing a framework for diffusive behavior in passive media. Subsequent advancements, such

as the Langevin equation, have enriched our understanding of stochastic processes, diffusive phenomena, and the fluctuation-dissipation theorem in thermal equilibrium. Nevertheless, the dynamics of particles in active baths introduce additional complexity [37, 45, 51–57]. Several studies have investigated this question, often employing analytical and numerical techniques to model and characterize the motion of tracer particles within nonequilibrium media, including the active bath. For instance, Maes *et al.* established a generalized fluctuation-response relation for thermal systems driven out of equilibrium [58–63], utilized this method to investigate the fluctuation-dissipation relation for nonequilibrium bath [35], and further studied the dynamics of a tracer immersed in such bath, gave the friction and noise properties [53], the Langevin description [64], and correlation functions of the tracer variables to study the fluctuation properties [54]. Speck and Seifert *et al.* formulated a fluctuation-dissipation theorem (FDT) within a nonequilibrium steady state of a sheared colloidal suspension system [65, 66], and subsequently investigated the mobility and diffusivity of a tagged particle within this system, determined the velocity autocorrelation functions and response functions with small shear force, found that a phenomenological effective temperature recovers the Einstein relation in nonequilibrium [67]. Esparza-López *et al.* [68] proposed a stochastic fluid dynamic model to describe analytically and computationally the dynamics of microscopic particles driven by the motion of surface attached bacteria, analytically calculated expressions for the effective diffusion coefficient through a run-and-tumble model, found that the short-time mean squared displacement is proportional to the square of the swimming speed while the long-time one only depends on the size of the particle. Burkholder and Brady [22] studied the diffusion of a tracer in a dilute dispersion of active Brownian particles (ABPs), by employing the Smoluchowski equation and averaging over bath particles and orientation variables, obtained tracers single-particle probability distribution function, found that the active contribution to the diffusivity scales as  $U_0$  (characteristic swim speed of ABP) for strong swimming and  $U_0^2$  for weak swimming. Furthermore, they [69] derived a general relationship between diffusivity and mobility in generic colloidal suspensions, provided a method to quantify deviations from the FDT and express them in terms of an effective SES relation. More recently, Granek *et al.* [51] studied the long-time dynamics of a tracer immersed in a one-dimensional active bath, derived a time-dependent friction and noise correlation with power law long tails that depend on the symmetry of tracers, and found that shape asymmetry of the tracer induces ratchet effects and leads to super-diffusion and friction that grows with time.

Numerous theories based on various starting points have demonstrated the importance and attraction of studying tracer behavior in nonequilibrium baths. In this study, we propose an alternative theoretical method based on path-integral method to investigate the behavior of tracer diffusion in an active particle bath, and subsequent simulation results successfully validate our theory. The starting point of the theory is the generalized Langevin equation (GLE) for the tracer, which utilizes a generalized version of Dean's equation to describe the active bath. The GLE contains a memory kernel function and complex effective noise terms, reflecting the complex interactions between the tracer and bath particles. We then employ the path integral method [70, 71] to calculate the diffusion coefficient. Numerical calculations show that the effective diffusion has a non-trivial dependence on bath parameters such as the number density and the persistent time of the active bath particle. Finally, we perform extensive computer simulations, which show very good agreement with our theoretical predictions.

This work is organized as follows: In Section “Model and theory”, we introduce the model system and derive the GLE of the tracer. Then, we utilize the path integral method to obtain the effective diffusion of



**Figure 1** Schematic diagram of a tracer particle with coordinate  $\mathbf{x}$  in an active particle bath consisting of self-propulsion particles at  $\mathbf{r}_i$ ,  $i = 1, 2, \dots, N$ . The tracer-bath interaction is  $U(|\mathbf{x} - \mathbf{r}_i|)$ , and the bath-bath interaction is  $V(|\mathbf{r}_i - \mathbf{r}_j|)$ . The wave lines label the thermal noises.

the tracer formally. In Section “Simulation results”, we show the numerical solution of such diffusion and compare it with simulation results. The paper ends with conclusion in Section “Conclusion”.

## MODEL AND THEORY

### Active bath model

Considering a system consisting of a tracer particle and  $N$  active Ornstein-Uhlenbeck (OU) particles (Figure 1), the coordinates of the tracer  $\mathbf{x}$  and the active bath particles  $\mathbf{r}_i$  are governed by the overdamped Langevin equations,

$$\dot{\mathbf{x}} = -\mu_t \nabla_x \left[ \sum_{i=1}^N U(|\mathbf{x} - \mathbf{r}_i|) + U_{\text{ext}}(\mathbf{x}) \right] + \sqrt{2\mu_t T} \xi_t, \quad (1a)$$

$$\dot{\mathbf{r}}_i = -\mu_b \left\{ \mathbf{f}_i + \nabla_i \left[ \sum_{j \neq i} V(|\mathbf{r}_i - \mathbf{r}_j|) + U(|\mathbf{r}_i - \mathbf{x}|) \right] \right\} + \sqrt{2\mu_b T} \xi_i, \quad (1b)$$

$$\tau_b \dot{\mathbf{f}}_i = -\mathbf{f}_i + \sqrt{2D_b / \mu_b^2} \eta_i, \quad (1c)$$

wherein  $\mu_t$  and  $\mu_b$  are the mobilities of the tracer and bath particles respectively,  $U_{\text{ext}}$  is an external potential acting on the tracer particle,  $U$  is the interacting potential between tracer and bath particles, and  $V$  is potential between bath particles,  $\xi_t$ ,  $\xi_i$  and  $\eta_i$  are white noises with zero means and unit variances,  $\mathbf{f}_i$  is the self-propulsion force acting on bath particle  $i$  with time correlation function  $\langle \mathbf{f}_i(t) \mathbf{f}_j(t') \rangle = \frac{D_b}{\mu_b^2 \tau_b} \delta_{ij} e^{-|t-t'|/\tau_b} \mathbf{I}$ , where  $\mathbf{I}$  is the unit matrix,  $\tau_b$  is the self-propulsion correlation time and  $D_b$  serves as the amplitude of such force,

with the same dimension as diffusivity. We consider the situation that all potentials ( $U$  and  $V$ ) are square integrable, meaning that they have well defined and limited Fourier transforms:  $U_k = \int U(\mathbf{r})e^{i\mathbf{k}\cdot\mathbf{r}}d\mathbf{r}$ ,  $V_k = \int V(\mathbf{r})e^{i\mathbf{k}\cdot\mathbf{r}}d\mathbf{r}$ .

Inspired by the idea of Dean's studies [72, 73], we derive a self-consistent equation for the density profile of bath particles  $\rho(\mathbf{r}, t) = \sum_{j=1}^N \delta(\mathbf{r} - \mathbf{r}_j(t))$  (See details in Appendix A in Supplementary information),

$$\frac{\partial}{\partial t}\rho(\mathbf{r}, t) = \mu_b \nabla \cdot \left\{ \rho(\mathbf{r}, t) \left[ \int \rho(\mathbf{r}', t) \nabla V(|\mathbf{r} - \mathbf{r}'|) d\mathbf{r}' + \nabla U(|\mathbf{r} - \mathbf{x}|) \right] \right\} + \mu_b T \nabla^2 \rho(\mathbf{r}, t) + \nabla \cdot \left\{ \sqrt{\rho(\mathbf{r}, t)} \left[ \xi^T(\mathbf{r}, t) + \xi^A(\mathbf{r}, t) \right] \right\}, \quad (2)$$

where the noise terms  $\xi^{(T,A)}$  has correlation functions  $\langle \xi^T(\mathbf{r}, t) \xi^T(\mathbf{r}', t') \rangle = 2\mu_b T \delta(\mathbf{r} - \mathbf{r}') \delta(t - t') \mathbf{I}$ ,  $\langle \xi^A(\mathbf{r}, t) \xi^A(\mathbf{r}', t') \rangle = \frac{D_b}{\tau_b} e^{-|t-t'|/\tau_b} \delta(\mathbf{r} - \mathbf{r}') \mathbf{I}$ . In the Fourier space ( $\delta\rho_k(t) = \int e^{i\mathbf{r}\cdot\mathbf{k}} (\rho(\mathbf{r}, t) - \rho_0) d\mathbf{k}$ ), Eq. (2) has a formal solution,

$$\delta\rho_k(t) = \int_{-\infty}^t e^{-(t-s)G_k} \left\{ -\mu_b k^2 \rho_0 U_k e^{i\mathbf{k}\cdot\mathbf{x}_s} + \sqrt{\rho_0} i\mathbf{k} \cdot \left[ \tilde{\xi}_k^T(s) + \tilde{\xi}_k^A(s) \right] \right\} ds, \quad (3)$$

wherein  $G_k = \mu_b k^2 (T + \rho_0 V_k)$  can be considered as a characteristic frequency (a typical illustration of this term is shown in Figure S1A). Noise terms  $\tilde{\xi}_k^{(T,A)}(t)$  are the Fourier transform of  $\xi^{(T,A)}$ , respectively, with correlation functions

$$\langle \tilde{\xi}_k^T(t) \tilde{\xi}_{k'}^T(t') \rangle = 2\mu_b T (2\pi)^3 \delta(\mathbf{k} + \mathbf{k}') \delta(t - t') \mathbf{I}, \quad (4a)$$

$$\langle \tilde{\xi}_k^A(t) \tilde{\xi}_{k'}^A(t') \rangle = \frac{D_b}{\tau_b} (2\pi)^3 \delta(\mathbf{k} + \mathbf{k}') e^{-|t-t'|/\tau_b} \mathbf{I}, \quad (4b)$$

wherein  $\langle \dots \rangle$  means the average over noises.

### Generalized Langevin equation

To achieve an effective equation of motion of the tracer which does not contain any bath particle variables, one can use an identity  $\nabla_x \sum_{i=1}^N U(|\mathbf{r}_i - \mathbf{x}|) = -\frac{1}{(2\pi)^3} \int i\mathbf{k} e^{-i\mathbf{k}\cdot\mathbf{x}} \rho_k U_k d^3\mathbf{k}$ , then has a GLE for  $\mathbf{x}$ ,

$$\begin{aligned} \dot{\mathbf{x}}(t) &= -\mu_t \nabla_x U_{\text{ext}}(\mathbf{x}) + \mu_t \frac{1}{(2\pi)^3} \int i\mathbf{k} e^{-i\mathbf{k}\cdot\mathbf{x}(t)} \delta\rho_k U_k d^3\mathbf{k} + \sqrt{2\mu_t T} \xi_t \\ &= -\mu_t \nabla_x U_{\text{ext}}(\mathbf{x}) - \int_{-\infty}^t \mathbf{K}(s, t) ds + \eta_T(t) + \eta_A(t) \sqrt{2\mu_t T} \xi_t, \end{aligned} \quad (5)$$

where the memory kernel

$$\begin{aligned} \mathbf{K}(s, t) &= \frac{\mu_t \mu_b \rho_0}{(2\pi)^3} \int i\mathbf{k}^2 \mathbf{k} U_k^2 e^{-(t-s)G_k} e^{-i\mathbf{k}\cdot(\mathbf{x}(t) - \mathbf{x}(s))} d^3\mathbf{k} \\ &= \frac{\mu_t \mu_b \rho_0}{(2\pi)^3} \int \text{Im}[e^{i\mathbf{k}\cdot(\mathbf{x}(t) - \mathbf{x}(s))}] \mathbf{k} k^2 U_k^2 e^{-(t-s)G_k} d^3\mathbf{k}, \end{aligned} \quad (6)$$

and the colored noise terms,

$$\eta_T(t) = -\mu_t \frac{1}{(2\pi)^3} \int \mathbf{k} e^{-i\mathbf{k}\cdot\mathbf{x}_t} \sqrt{\rho_0} U_k \int_{-\infty}^t e^{-(t-s)G_k} \mathbf{k} \cdot \tilde{\xi}_k^T(s) ds d^3\mathbf{k}, \quad (7)$$

$$\eta_A(t) = -\mu_t \frac{1}{(2\pi)^3} \int \mathbf{k} e^{-i\mathbf{k}\cdot\mathbf{x}_t} \sqrt{\rho_0} U_k \int_{-\infty}^t e^{-(t-s)G_k} \mathbf{k} \cdot \tilde{\xi}_k^A(s) ds d^3\mathbf{k}, \quad (8)$$

and their correlations are

$$\mathbf{G}_T(t, t') = \langle \boldsymbol{\eta}_T(t) \boldsymbol{\eta}_T(t') \rangle = \frac{\mu_T^2 \rho_0 \mu_b T}{(2\pi)^3} \int e^{-i\mathbf{k} \cdot (\mathbf{x}_t - \mathbf{x}_{t'})} \mathbf{k} \mathbf{k} k^2 U_k^2 \frac{e^{-|t-t'|G_k}}{G_k} d^3\mathbf{k}, \quad (9)$$

$$\mathbf{G}_A(t, t') = \langle \boldsymbol{\eta}_A(t) \boldsymbol{\eta}_A(t') \rangle = \frac{\mu_T^2 \rho_0 D_b}{(2\pi)^3} \int e^{-i\mathbf{k} \cdot (\mathbf{x}_t - \mathbf{x}_{t'})} \mathbf{k} \mathbf{k} k^2 U_k^2 \frac{\tau_b e^{-|t-t'|/\tau_b} - (e^{-|t-t'|G_k}/G_k)}{[(\tau_b G_k)^2 - 1]} d^3\mathbf{k}. \quad (10)$$

### Path integral and effective diffusion

To calculate the transport coefficients, one needs to calculate several correlation functions first. Considering the coupling between the tracer position and the colored noises  $\boldsymbol{\eta}_{A,T}$ , we propose a path integral method to calculate them.

We consider a path of the tracer in the time interval  $[t_i, t_f]$ . The partition function of such trajectory can be written as

$$Z = \int \prod_t \delta\left\{ \dot{\mathbf{x}} + \mu_t \nabla U_{\text{ext}} + \int_{-\infty}^t \mathbf{K}(s, t) ds - \boldsymbol{\eta}_A - \boldsymbol{\eta}_T - \sqrt{2\mu_t T} \boldsymbol{\xi}_t \right\} P[\boldsymbol{\xi}_t] P[\boldsymbol{\eta}_T] P[\boldsymbol{\eta}_A] \mathcal{D}\mathbf{x} \mathcal{D}\boldsymbol{\xi}_t \mathcal{D}\boldsymbol{\eta}_A \mathcal{D}\boldsymbol{\eta}_T. \quad (11)$$

Using the identity of delta function,  $\delta(x) = \frac{1}{(2\pi)} \int e^{ipx} dp$ , we also have

$$Z = \int e^{i \int \mathbf{p} \cdot \left\{ \dot{\mathbf{x}} + \mu_t \nabla U_{\text{ext}} + \int_{-\infty}^t \mathbf{K}(s, t) ds - \boldsymbol{\eta}_A - \boldsymbol{\eta}_T - \sqrt{2\mu_t T} \boldsymbol{\xi}_t \right\}} dt P[\boldsymbol{\xi}_t] P[\boldsymbol{\eta}_T] P[\boldsymbol{\eta}_A] \mathcal{D}\mathbf{x} \mathcal{D}\mathbf{p} \mathcal{D}\boldsymbol{\xi}_t \mathcal{D}\boldsymbol{\eta}_A \mathcal{D}\boldsymbol{\eta}_T, \quad (12)$$

where  $\mathbf{p}$  is an auxiliary real vector field. Next, utilizing  $\langle e^{au} \rangle = e^{\frac{1}{2}a^2 \langle u^2 \rangle}$  for a Gaussian random variable  $u$  with zero mean, we have the partition function as a function of the action,

$$Z = \int e^{-S(\mathbf{x}, \mathbf{p})} \mathcal{D}\mathbf{x} \mathcal{D}\mathbf{p}, \quad S(\mathbf{x}, \mathbf{p}) = S_0(\mathbf{x}, \mathbf{p}) + S_{\text{int}}(\mathbf{x}, \mathbf{p}), \quad (13)$$

where

$$S_0 = -i \int \mathbf{p}(t) \cdot [\dot{\mathbf{x}}(t) + \mu_t \nabla_x U_{\text{ext}}] dt + \mu_t T \int |\mathbf{p}(t)|^2 dt, \quad (14)$$

for a free particle and

$$S_{\text{int}} = -i \int \mathbf{p}(t) \cdot \left[ \int_{-\infty}^t \mathbf{K}(s, t) ds \right] dt + \frac{1}{2} \iint \mathbf{p}(t) \cdot [\mathbf{G}_T(t, s) + \mathbf{G}_A(t, s)] \cdot \mathbf{p}(s) dt ds \quad (15)$$

counts for the tracer-bath interaction. Herein, we have assumed that  $\boldsymbol{\eta}_{A,T}$  are both Gaussian, and their deviations from the Gaussian distribution are only weakly present in regions far from the mean. Since this approximation primarily reflects the properties of the second moments, it is reasonable in this context. In addition, since we have used the perturbative expansion, the interaction between tracer and bath particles should be weak. Therefore, we choose soft harmonic potentials as the inter-particle potentials. The perturbation also demands that the activity is not very large, which constitutes a condition for the application of our theoretical framework.

After introducing the partition function over the trajectory, the average over any operator  $A$  as function of  $\mathbf{x}(t)$ ,  $t \in [t_i, t_j]$  can be defined as

$$\langle A \rangle = \frac{\int A e^{-(S_0 + S_{\text{int}})} \mathcal{D}\mathbf{x} \mathcal{D}\mathbf{p}}{Z} = \frac{\langle A e^{-S_{\text{int}}} \rangle_0}{\langle e^{-S_{\text{int}}} \rangle_0}, \quad (16)$$

where  $\langle \dots \rangle_0 = Z_0^{-1} \int (\dots) e^{-S_0} \mathcal{D}\mathbf{x} \mathcal{D}\mathbf{p}$  corresponds to a tracer particle only affected by external potential, not any particle bath. So far, the  $e^{-S_{\text{int}}}$  term is still too complicated to handle. A common treatment is the linear truncation when  $S_{\text{int}}$  is weak. Herein, we treat the tracer-bath interaction  $U$  as a small perturbative quantity by assigning  $U(r) = \sqrt{\epsilon} u(r)$ , where  $\epsilon$  is a dimensionless factor that scales the interacting strength, and can be used to the following perturbative expansion. The memory kernel  $\mathbf{k}$  and correlators  $G_{A,T}(t)$  are order 1 of  $\epsilon$ . Therefore, Eq. (16) can be expand as

$$\langle A \rangle = \langle A \rangle_0 - \langle AS_{\text{int}} \rangle_0 + \langle A \rangle_0 \langle S_{\text{int}} \rangle_0 + O(\epsilon^2). \quad (17)$$

For studying the diffusion problem, we only need to consider the free particle situation,  $U_{\text{ext}} = 0$ . According to the symmetry, we have  $\langle \mathbf{p}(t) e^{-i\mathbf{k} \cdot [\mathbf{x}(t) - \mathbf{x}(s)]} \rangle_0 = -i \langle \mathbf{p}(t) [\mathbf{x}(t) - \mathbf{x}(s)] \rangle_0 \cdot \mathbf{k} e^{-k^2 \mu_t T(t-s)} = 0$ . Similarly, we also have

$$\langle \mathbf{p}(t) \cdot \mathbf{G}_{A,T}(t, s) \cdot \mathbf{p}(t) \rangle_0 \propto \left\{ \langle |\mathbf{p}(t)|^2 \rangle_0 - (\mathbf{k} \cdot \langle (\mathbf{x}(t) - \mathbf{x}(s)) \mathbf{p}(t) \rangle_0)^2 \right\} e^{-k^2 \mu_t T(t-s)} = 0. \quad (18)$$

Therefore,

$$\langle S_{\text{int}} \rangle_0 = 0. \quad (19)$$

The next step is to calculate the mean square displacement (MSD), i.e., to calculate  $\langle [\mathbf{x}(t_f) - \mathbf{x}(t_i)]^2 \rangle$  for a long time interval  $t_f - t_i$ . Then, the effective diffusion coefficient can be given as

$$D_{\text{eff}} = \lim_{(t_f - t_i) \rightarrow \infty} \frac{1}{2d(t_f - t_i)} \langle [\mathbf{x}(t_f) - \mathbf{x}(t_i)]^2 \rangle, \quad (20)$$

where  $d$  is the dimension of the system. According to Eq. (17), the key step of calculating the MSD is handling  $\langle [\mathbf{x}(t_f) - \mathbf{x}(t_i)]^2 S_{\text{int}} \rangle_0$ , i.e., calculating the following two correlation functions, one is

$$\begin{aligned} & \langle [\mathbf{x}(t_f) - \mathbf{x}(t_i)]^2 \mathbf{p}(t) e^{-i\mathbf{k} \cdot [\mathbf{x}(t) - \mathbf{x}(s)]} \rangle_0 \\ &= -2i\mathbf{k} \cdot \langle [\mathbf{x}(t) - \mathbf{x}(s)] [\mathbf{x}(t_f) - \mathbf{x}(t_i)] \rangle_0 \langle [\mathbf{x}(t_f) - \mathbf{x}(t_i)] \mathbf{p}(t) \rangle_0 e^{-k^2 \mu_t T(t-s)} \\ &= 4\mathbf{k} \mu_t T L([t_i, t_f] \cap [s, t]) \chi_{[t_i, t_f]}(t) e^{-k^2 \mu_t T(t-s)} \\ &= 4\mathbf{k} \mu_t T [t - \max(t_i, s)] \chi_{[t_i, t_f]}(t) e^{-k^2 \mu_t T(t-s)}, \end{aligned} \quad (21)$$

and the other is

$$\begin{aligned} & \langle [\mathbf{x}(t_f) - \mathbf{x}(t_i)]^2 \mathbf{p}(t) \mathbf{p}(s) e^{-i\mathbf{k} \cdot [\mathbf{x}(t) - \mathbf{x}(s)]} \rangle_0 \\ &= \left\{ 4\mu_t T [t - \max(s, t_i)] \mathbf{k} \mathbf{k} - 2\chi_{[t_i, t_f]}(s) \mathbf{1} \right\} e^{-k^2 \mu_t T(t-s)} \chi_{[t_i, t_f]}(t), \end{aligned} \quad (22)$$

for  $t > s$  (the omitted mathematical details can be found in Appendix B in Supplementary information). After the calculation in Eq. (S9) (Supplementary information), we get

$$\begin{aligned} \langle [\mathbf{x}(t_f) - \mathbf{x}(t_i)]^2 S_{\text{int}} \rangle_0 &= 2\mu_t T (t_f - t_i) \frac{\mu_t \mu_b \rho_0}{(2\pi)^3} \int \frac{k^4 U_k^2}{G_k(k^2 \mu_t T + G_k)} d^3 \mathbf{k} \\ &+ \frac{\mu_t^2 \rho_0 D_b}{(2\pi)^3} (t_f - t_i) \int \frac{2k^4 U_k^2}{(\tau_b G_k)^2 - 1} \left\{ \frac{\tau_b \mu_t T k^2 - 1}{(\mu_t T k^2 + \tau_b^{-1})^2} - \frac{(\mu_t T k^2 / G_k) - 1}{(\mu_t T k^2 + G_k)^2} \right\} d^3 \mathbf{k} \\ &+ o(t_f - t_i), \end{aligned} \quad (23)$$

where  $G_k = \mu_b k^2 (T + \rho_0 V_k)$  reflects the bath properties including background temperature  $T$ , number density  $\rho_0$  and interactions between bath particles. At last, taking the long-time limit of  $t_f - t_i$ , the  $o(t_f - t_i)$  term can be neglected, the effective diffusion coefficient of a tracer in an active bath is obtained

$$D_{\text{eff}} = \mu_t T \left\{ 1 - \int_0^\infty g_T(k) dk + \int_0^\infty g_A(k) dk \right\}, \tag{24a}$$

to the linear order, wherein

$$g_T(k) = \frac{\mu_t \mu_b \rho_0}{6\pi^2} \frac{k^6 U_k^2}{G_k(k^2 \mu_t T + G_k)}, \tag{24b}$$

$$g_A(k) = \frac{\mu_t \rho_0 D_b / T}{6\pi^2} \frac{k^6 U_k^2}{(\tau_b G_k)^2 - 1} \left[ \frac{\mu_t T k^2 / G_k - 1}{(\mu_t T k^2 + G_k)^2} - \frac{\tau_b \mu_t T k^2 - 1}{(\mu_t T k^2 + \tau_b^{-1})^2} \right]. \tag{24c}$$

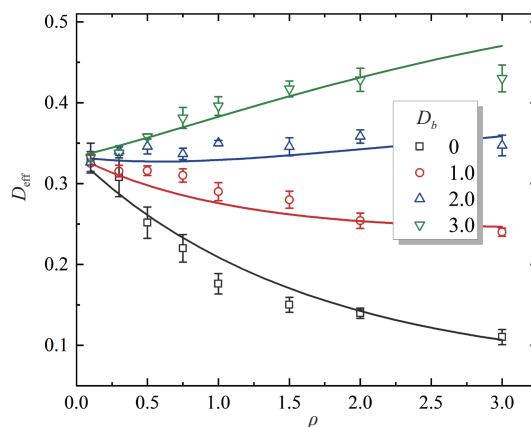
This is the main result of the present work. In this equation, “1” in the brace of Eq. (24a) denotes the bare diffusion of a free tracer particle. The second term in the brace denotes the “passive part” of the tracer-bath interaction which is always a negative contribution to effective diffusion and recovers the results in Ref. [70]. In the absence of activity, the FDT holds since the effective mobility of the tracer satisfies  $\mu_{\text{eff}} = D_{\text{eff}}/T$  [70], wherein they have obtained an effective mobility coefficient  $\mu_{\text{eff}} = \mu_t (1 - \int_0^\infty g_T(k) dk)$  (expressed with notations of the present work for convenience). The third term is a pure “active” contribution on the diffusion, which is a positive contribution and explicitly gives the nontrivial dependence of  $D_{\text{eff}}$  on the bath parameters,  $\rho_0$ ,  $D_b$ ,  $\tau_b$  and interactions  $U(r)$  and  $V(r)$ . For this linear truncation,  $D_{\text{eff}}$  is a linear function of  $D_b$ . However, the dependence of  $\tau_b$  and  $\rho_0$  (which is also contained in  $G_k$ ) is illegible, which require numerical calculations to determine (see Section “Simulation results”). Further mathematical analysis of this expression is shown in Appendix C in Supplementary information.

## SIMULATION RESULTS

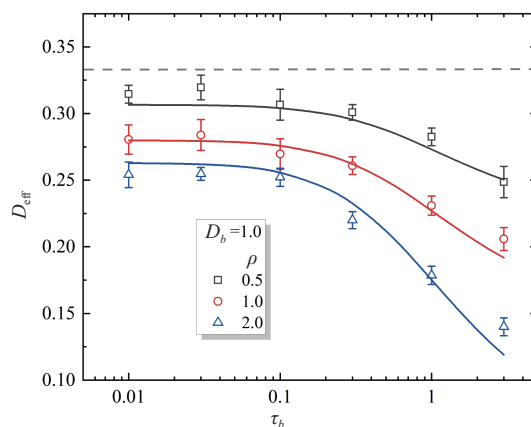
In this section, we show numerical calculations of Eq. (24a) with the persistent time of active force  $\tau_b$  and the number density of bath particles  $\rho$ , at small activity  $D_b$  region. Then, by comparing these results with computer simulations, the validity and applicability of the theory can be verified.

In the present work, we choose  $V(r)$  and  $U(r)$  as both harmonic potentials,  $V(r) = \frac{\kappa_b}{2} (r - \sigma_{bb})^2$  for  $r < \sigma_{bb}$ , and  $U(r) = \frac{\kappa_t}{2} (r - \sigma_{tb})^2$  for  $r < \sigma_{tb}$ . We set  $\sigma_{bb}$  as the unit of length,  $\kappa_b \sigma_{bb}^2$  as the unit of energy, and  $1/(\mu_b \kappa_b)$  as the unit of time. The common parameters are set as:  $\sigma_{tb} = 2.0$ ,  $\kappa_t = 1.0$ ,  $\mu_t = 0.333$ ,  $T = 1.0$ . The other parameters are set as variables which are explicitly given in the following figures. In computer simulations, we construct a three-dimensional system with periodic boundary containing (1+4095) particles. The diffusion coefficient is calculated through a long-time simulation ( $\sim 10^8$  steps with  $10^{-3}$  as the time step) and averaged over 20 samples with random initial configurations.

Firstly, we focus on the contribution of bath number density  $\rho$  on  $D_{\text{eff}}$ , shown in Figure 2. In Figures 2 and 3, dots and corresponding error bars are the direct simulations, and lines are numerical calculation of Eq. (24a). In general,  $D_{\text{eff}}$  shows a diverse dependence on  $\rho$ . For small active force amplitude  $D_b$ ,  $D_{\text{eff}}$  decreases with  $\rho$  as the tracer’s behavior in a passive particle bath. For large activity situation,  $D_{\text{eff}}$  shows the opposite behavior. Consequently, one may expect that there is a moderate activity region that  $D_{\text{eff}}$  has a non-monotonic dependence on  $\rho$ .



**Figure 2** The dependence of the effective diffusion on the number density of active bath particle  $\rho$ . Dots and corresponding error bars are simulation results of  $D_{\text{eff}}$ . Solid lines are the numerical calculations of  $D_{\text{eff}}$ . Both results show that, with the increase of activity  $D_b$ , effective diffusion  $D_{\text{eff}}$  gradually changes from monotonic decrease to monotonic increase with the number density of bath particle  $\rho$ , including a non-monotonic interval around  $D_b = 2.0$ . Herein,  $\tau_b$  is set as 0.1.



**Figure 3** The dependence of the effective diffusion on the active force persistent time  $\tau_b$ . Dots and corresponding error bars are simulation results of  $D_{\text{eff}}$ . Solid lines are the numerical calculations of  $D_{\text{eff}}$ . Both show that  $D_{\text{eff}}$  monotonically decreases with the persistent time  $\tau_b$ . The horizontal dash line denotes the bare diffusion coefficient of the tracer particle.

We then investigate the dependence of  $D_{\text{eff}}$  on persistent time  $\tau_b$ . According to Eq. (24a),  $D_{\text{eff}}$  decreases with  $\tau_b$  since both  $(G_k \tau_b)^2 - 1$  and  $\frac{\tau_b \mu_r T k^2 - 1}{(\mu_r T k^2 + \tau_b^{-1})^2}$  increase with  $\tau_b$  monotonically. This prediction has been confirmed in simulations, as shown in Figure 3. Physically, when the persistent time of the active force tends to zero, the active OU particle can be reduced to an ordinary Brownian particle under a higher temperature. If the activity amplitude  $D_b$  is constant, the longer  $\tau_b$  means a larger deviation of equilibrium. Based on the results here, we might conclude that an active OU particle bath that stays closer to equilibrium, is more conducive to the tracer diffusion, when the activity amplitude is given.

## CONCLUSION

This study aims to shed light on the intricacies of tracer diffusion in an active particle bath. By employing the generalized Dean's equation, incorporating the path integral method, and utilizing computer simulations,



we characterize the impact of self-propulsion on the diffusion behavior of a passive tracer particle. In summary, the effective diffusion decreases with persistent time  $\tau_b$ , and exhibits a variety of dependencies on bath density, depending on  $D_b$ . The obtained insights expand our understanding of collective dynamics and transport phenomena in non-equilibrium systems, with potential applications in diverse scientific disciplines. For further studies, an extension of the active bath situation is straightforward since it has been confirmed to calculate the mobility of a tracer in particle bath [70, 71]. Additionally, after the effective mobility is achieved, the fluctuation-dissipation theorem can be further investigated to determine its validity or deviations with respect to the activity parameters.

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## Author contributions

H.Z. directed the project. F.M. derived the theory, wrote codes, and wrote the manuscript. All authors commented on the manuscript.

## Conflict of interest

The authors declare no conflict of interest.

## Supplementary information

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