





#### **傅孝明** 中国科学技术大学

# Art design

# Peeling art

Computational Peeling Art Design

https://www.youtube.com/watch?v=JIOUHAkQdc4

NOW I'VE SEEN EVERYTHING

### **Popular art form**



### **Peeling art examples**





#### **Problem: cut generation**



#### complex, tedious, time consuming

# Peeling art design problem







# Challenges



- Non-trivial to optimize the similarity
- Unsuitable input shape



# **Existing work: cut generation**



- Minimum spanning tree method [Chai et al. 2018; Sheffer 2002; Sheffer and Hart 2002]
- Mesh segmentation approaches [Julius et al. 2005; Lévy et al. 2002; Sander et al. 2002, 2003; Zhang et al. 2005; Zhou et al. 2004]
- Simultaneous optimization [Li et al. 2018; Poranne et al.2017]
- Variational method [Sharp and Crane 2018]

#### **unfolded shapes** *≠* **input shapes**

### Our approach





Key idea







# **Mapping computation**





Two goals:1. Low isometric distortion2. Area of *R* approaches zero

$$\min E_{iso}(S^m, S) + wE_{shr}(R)$$

### **Isometric energy**

• ARAP distortion metric [Liu et al. 2008]

$$E_{iso}(S^{m}, S) = \sum_{i=1}^{N_{f}} Area(f_{i})||J_{i} - R_{i}||_{F}^{2}$$

 $R_i$  is an orthogonal matrix



# Shrink energy

• Our novel rank-one energy  $E_{shr}(R) = \sum_{i=1}^{N_{R_f}} Area(t_i) ||J_i - B_i||_F^2$   $B_i \text{ is a rank one matrix}$ 

- Other choices
  - Frobenius energy  $||J_i||_F^2$
  - Determinant energy  $det(J_i)$





### Suitable input





### Unsuitable input



### **Iterative interaction**



#### **Interaction place**





#### Interaction 1: shape augmentation



#### Interaction 2: part deletion



#### Interaction 3: angle augmentation





#### Mode 3: Angle augmentation

#### Interaction 4: curvature reduction



### Interaction 5: pre-processing



### **Interaction 5: pre-processing**





Input with specify area



#### Unprocessed: high distortion



#### Processed: low distortion

#### **Cut generation**





# **Real peeling**









#### Real peeling

**Drawing graticule** 

0 × playback

#### Shapes designed by Yoshihiro Okada 👩



#### **Comparison to Yoshihiro Okada**





Okada's

Eagle

Dove

#### Shrimp

# anes Deci $\mathbf{n}$ playback

#### **Our results**















Papercraft









### **Developable Surfaces**



Zero Gaussian curvature



### **Developable Surfaces**







#### Ship hulls



Clothing

Origami



#### Architecture

#### Goal





Not globally developable

Piecewise developable approximation Small number of patches High similarity

# Challenges



• Determining the numbers, placements and shapes of patches under the developability and similarity constraints



### **Related Work**

#### Segmentation-based



[Shatz et al. 2006]

[lon et al. 2020]

Pro: explicit patches

Con: large approximation error

#### **Deformation-based**



[Stein et al. 2018] [Binninger et al. 2021]

#### Pro: seam curves

Con: no explicit patch layouts



#### **Method – Deformation**





# **Edge-oriented Developability**



The Gauss map degenerates if the determinant condition is satisfied

# **Edge-oriented Developability**

U

- Weaker than the definition in [Stein et al. 2018]
- Some special examples satisfy our edge-oriented definition directly



### **Deformation Optimization**



#### 

Challenges:

• Highly nonlinear



Auxiliary variables

• Hard to minimize

#### **Deformation Energy – Developability**

**n**, .

$$E_{dev} = \sum_{ij \in \mathcal{E}} \left( \|[\mathbf{n}_{ij}, \mathbf{n}_{ki}, \mathbf{n}_{il}] - P_r([\mathbf{n}_{ij}, \mathbf{n}_{ki}, \mathbf{n}_{il}])\|_F^2 + \\\|[\mathbf{n}_{ij}, \mathbf{n}_{jk}, \mathbf{n}_{lj}] - P_r([\mathbf{n}_{ij}, \mathbf{n}_{jk}, \mathbf{n}_{lj}])\|_F^2 \right) + \\\sum_{ijk \in \mathcal{F}} \|[\mathbf{n}_{ij}, \mathbf{n}_{jk}, \mathbf{n}_{ki}] - P_r([\mathbf{n}_{ij}, \mathbf{n}_{jk}, \mathbf{n}_{ki}])\|_F^2 \\ The projection to the rank-two matrix space$$

#### **Deformation Energy – Approximation**

$$E_{app} = \sum_{i \in \mathcal{V}} \|\mathbf{v}_i - \mathbf{P}_v(\mathbf{v}_i)\|_2^2$$
  
The projection to  
the input mesh



### **Deformation Energy – Distortion**

$$E_{\text{dis}} = E_{\text{shape}} + \omega_{\text{sim}} E_{\text{sim}}$$

$$E_{\text{shape}} = \frac{1}{2} \sum_{ij \in \mathcal{E}} \|\mathbf{e}_{ij} - s_{ij} R_{ij} \mathbf{e}_{ij}^{0}\|_{2}^{2} + \|\mathbf{n}_{jil} - R_{ij} U_{ij}^{\top} \mathbf{n}_{jil}^{0}\|_{2}^{2} \right)$$

$$\mathbf{n}_{ij} = R_{ij} \mathbf{n}_{ij}^{0}$$

$$\mathbf{n}_{ijk} = R_{ij} U_{ij} \mathbf{n}_{ijk}^{0}$$

# **Deformation optimization**

#### repeat

$$\begin{split} & P_r(\cdot) \leftarrow \mathsf{UpdatePr}(A), \forall A \in \mathcal{A}_{ij}; \\ & R_{ij} \leftarrow \mathsf{UpdateR}(\mathbf{v}_i, s_{ij}, U_{ij}, \mathbf{n}_{ijk}, P_r(\cdot)); \\ & U_{ij} \leftarrow \mathsf{UpdateU}(R_{ij}, \mathbf{n}_{ijk}); \\ & P_v(\cdot) \leftarrow \mathsf{UpdatePv}(\mathbf{v}_i); \\ & \mathbf{v}_i \leftarrow \mathsf{UpdateV}(s_{ij}, R_{ij}, P_v(\cdot)); \\ & \mathbf{n}_{ijk} \leftarrow \mathsf{UpdateN}(U_{ij}, R_{ij}); \\ & s_{ij} \leftarrow \mathsf{UpdateS}(\mathbf{v}_i, R_{ij}); \\ & k \leftarrow k + 1; \end{split}$$

until k < N;



### Method – Segmentation



### Segmentation – Coarse partition





Segmentation algorithm Step-by-step in [Tong et al. 2020]

# Segmentation – Patch merging

Minimum area P<sub>min</sub>

 $P = \arg \min_{P \in \mathcal{P}_{\min}} Str(P, P_{\min})$  Straightness

 $Len(P, P_{min}) > \epsilon_{len} \qquad Length \\ Cur(P, P_{min}) < \epsilon_{cur} \qquad Curvature$ 

Iterative strategy

 $N_p = 103$ 



### Method – Refinement

- Small approximation error
- Smooth patches
- Smooth seam curves



### Method – Refinement

- Method in [lon et al. 2020]: DOG projection The distance to  $\mathcal{M}_d$
- Developability
- Smoothness
- Seam smoothness
- Connectedness

Cut overlaps





### **More Examples**



#### Comparisons



### Comparisons



#### Fabrication



#### Fabrication





