

微分几何第二章习题

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习题 1 (P28,T1). 求下列曲线的弧长与曲率:

$$(1) \quad y = ax^2;$$

$$(2) \quad \frac{x^2}{a^2} + \frac{y^2}{b^2} = 1;$$

$$(3) \quad \mathbf{r}(t) = (a \cosh t, b \sinh t);$$

$$(4) \quad \mathbf{r}(t) = (t, a \cosh \frac{t}{a}) (a > 0).$$

解. 对于平面参数曲线 $\mathbf{r}(t) = (x(t), y(t))$, 有弧长参数

$$s(t) = \int_0^t |\mathbf{r}'(\theta)| d\theta, \quad |\mathbf{r}'(t)| = \sqrt{(x'(t))^2 + (y'(t))^2},$$

从而我们有

$$\mathbf{t}(s) = \mathbf{t}(s(t)) = \frac{d\mathbf{r}}{ds} = \frac{d\mathbf{r}}{dt} / \frac{ds}{dt} = \frac{\mathbf{r}'(t)}{|\mathbf{r}'(t)|} = \frac{(x'(t), y'(t))}{\sqrt{(x'(t))^2 + (y'(t))^2}}$$

及

$$\mathbf{n}(s) = \mathbf{n}(s(t)) = \frac{(-y'(t), x'(t))}{\sqrt{(x'(t))^2 + (y'(t))^2}},$$

求导有

$$\dot{\mathbf{t}}(s) = \frac{d\mathbf{t}}{ds} = \frac{d\mathbf{t}}{dt} / \frac{ds}{dt} = \frac{\left(y'(t)(x''(t)y'(t) - x'(t)y''(t)), x'(t)(x'(t)y''(t) - x''(t)y'(t)) \right)}{\{(x'(t))^2 + (y'(t))^2\}^2},$$

由曲率公式 $\dot{\mathbf{t}}(s(t)) = \kappa(t)\mathbf{n}(s(t))$ 便得平面曲线曲率公式为

$$\kappa(t) = \frac{x'(t)y''(t) - x''(t)y'(t)}{\{(x'(t))^2 + (y'(t))^2\}^{3/2}},$$

这便是第二题的结论。

(1) 曲线参数化 $\mathbf{r}(t) = (t, at^2)$, $|\mathbf{r}'(t)| = \sqrt{1 + 4a^2t^2}$, 从而弧长参数为

$$\begin{aligned} s(t) &= \int_0^t \sqrt{1 + 4a^2\theta^2} d\theta = \frac{1}{2}\theta\sqrt{1 + 4a^2\theta^2} + \frac{1}{4a} \ln(2a\theta + \sqrt{1 + 4a^2\theta^2}) \Big|_{\theta=0}^{\theta=t} \\ &= \frac{1}{2}t\sqrt{1 + 4a^2t^2} + \frac{1}{4a} \ln(2at + \sqrt{1 + 4a^2t^2}), \end{aligned}$$

Date: November 10, 2016.

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代入公式得曲率为

$$\kappa(t) = \frac{2a}{(1+4a^2t^2)^{3/2}}.$$

(2) 曲线参数化 $\mathbf{r}(t) = (a \cos t, b \sin t)$, $t \in [0, 2\pi]$, $|\mathbf{r}'(t)| = \sqrt{a^2 \sin^2 t + b^2 \cos^2 t}$, 直接计算便有

$$s(t) = \int_0^t |\mathbf{r}'(\theta)| d\theta = \int_0^t \sqrt{a^2 \sin^2 \theta + b^2 \cos^2 \theta} d\theta,$$

$$\kappa(t) = \frac{ab}{(a^2 \sin^2 t + b^2 \cos^2 t)^{3/2}}.$$

(3) $|\mathbf{r}'(t)| = \sqrt{a^2 \sinh^2 t + b^2 \cosh^2 t}$, 直接计算便有

$$s(t) = \int_0^t |\mathbf{r}'(\theta)| d\theta = \int_0^t \sqrt{a^2 \sinh^2 \theta + b^2 \cosh^2 \theta} d\theta,$$

$$\kappa(t) = -\frac{ab}{(a^2 \sinh^2 t + b^2 \cosh^2 t)^{3/2}}.$$

(4) $|\mathbf{r}'(t)| = \sqrt{1 + \sinh^2 \frac{t}{a}}$, 直接计算便有

$$s(t) = \int_0^t |\mathbf{r}'(\theta)| d\theta = \int_0^t \sqrt{1 + \sinh^2 \frac{\theta}{a}} d\theta,$$

$$\kappa(t) = \frac{\cosh \frac{t}{a}}{a(1 + \sinh^2 \frac{t}{a})^{3/2}} = \frac{1}{a \cosh^2 \frac{t}{a}}.$$

习题 2 (P28,T3). 设曲线 C 在极坐标 (r, θ) 下的表示为 $r = f(\theta)$, 证明曲线 C 的曲率表达式为

$$\kappa(\theta) = \frac{f^2(\theta) + 2(f'(\theta))^2 - f(\theta)f''(\theta)}{\left\{f^2(\theta) + (f'(\theta))^2\right\}^{3/2}}.$$

解. 曲线 C 参数化 $\mathbf{r}(\theta) = (x(\theta), y(\theta)) = (r \cos \theta, r \sin \theta) = (f(\theta) \cos \theta, f(\theta) \sin \theta)$, 直接计算有

$$x'(\theta) = f'(\theta) \cos \theta - f(\theta) \sin \theta,$$

$$x''(\theta) = f''(\theta) \cos \theta - 2f'(\theta) \sin \theta - f(\theta) \cos \theta,$$

$$y'(\theta) = f'(\theta) \sin \theta + f(\theta) \cos \theta,$$

$$y''(\theta) = f''(\theta) \sin \theta + 2f'(\theta) \cos \theta - f(\theta) \sin \theta,$$

$$(x'(\theta))^2 + (y'(\theta))^2 = f^2(\theta) + (f'(\theta))^2,$$

$$x'(\theta)y''(\theta) - x''(\theta)y'(\theta) = f^2(\theta) + 2(f'(\theta))^2 - f(\theta)f''(\theta),$$

代入第二题结果即可.

习题 3 (P28,T4). 求下列曲线的曲率和挠率:

- (1) $\mathbf{r}(t) = (a \cosh t, a \sinh t, bt)$ ($a > 0$);
- (2) $\mathbf{r}(t) = (3t - t^2, 3t^2, 3t + t^2)$;
- (3) $\mathbf{r}(t) = (a(1 - \sin t), a(1 - \cos t), bt)$ ($a > 0$);
- (4) $\mathbf{r}(t) = (at, \sqrt{2}a \ln t, \frac{a}{t})$ ($a > 0$).

解. 首先证明下述 \mathbb{E}^3 中参数曲线 $\mathbf{r}(t)$ 的曲率和挠率公式:

$$\kappa(t) = \frac{|\mathbf{r}'(t) \wedge \mathbf{r}''(t)|}{|\mathbf{r}'(t)|^3}, \quad \tau(t) = \frac{(\mathbf{r}'(t), \mathbf{r}''(t), \mathbf{r}'''(t))}{|\mathbf{r}'(t) \wedge \mathbf{r}''(t)|^2}.$$

直接计算, 弧长参数为

$$\begin{aligned} s(t) &= \int_0^t |\mathbf{r}'(\theta)| d\theta, \\ \mathbf{t} &= \frac{d\mathbf{r}}{ds} = \frac{d\mathbf{r}}{dt} / \frac{ds}{dt} = \frac{\mathbf{r}'(t)}{|\mathbf{r}'(t)|}, \\ \dot{\mathbf{t}} &= \frac{1}{|\mathbf{r}'(t)|} \frac{d\mathbf{t}}{dt} = \frac{1}{|\mathbf{r}'(t)|^4} \left((\mathbf{r}'(t), \mathbf{r}'(t)) \mathbf{r}''(t) - (\mathbf{r}'(t), \mathbf{r}''(t)) \mathbf{r}'(t) \right) \\ &= \frac{\mathbf{r}'(t) \wedge (\mathbf{r}''(t) \wedge \mathbf{r}'(t))}{|\mathbf{r}'(t)|^4}, \end{aligned}$$

上述最后一个等式用到了向量外积公式

$$\mathbf{a} \wedge (\mathbf{b} \wedge \mathbf{c}) = \langle \mathbf{a}, \mathbf{c} \rangle \mathbf{b} - \langle \mathbf{a}, \mathbf{b} \rangle \mathbf{c}.$$

注意到 $\mathbf{r}'(t) \perp (\mathbf{r}''(t) \wedge \mathbf{r}'(t))$, 则有

$$\kappa(t) = |\dot{\mathbf{t}}| = \frac{|\mathbf{r}'(t) \wedge \mathbf{r}''(t)|}{|\mathbf{r}'(t)|^3},$$

故而

$$\begin{aligned} \mathbf{n} &= \frac{\dot{\mathbf{t}}}{\kappa} = \frac{\mathbf{r}'(t) \wedge (\mathbf{r}''(t) \wedge \mathbf{r}'(t))}{|\mathbf{r}'(t)| |\mathbf{r}'(t) \wedge \mathbf{r}''(t)|}, \\ \mathbf{b} &= \mathbf{t} \wedge \mathbf{n} = \frac{\mathbf{r}'(t) \wedge (\mathbf{r}'(t) \wedge (\mathbf{r}''(t) \wedge \mathbf{r}'(t)))}{|\mathbf{r}'(t)|^2 |\mathbf{r}'(t) \wedge \mathbf{r}''(t)|} \\ &= \frac{\langle \mathbf{r}'(t), \mathbf{r}''(t) \wedge \mathbf{r}'(t) \rangle \mathbf{r}'(t) - \langle \mathbf{r}'(t), \mathbf{r}'(t) \rangle (\mathbf{r}''(t) \wedge \mathbf{r}'(t))}{|\mathbf{r}'(t)|^2 |\mathbf{r}'(t) \wedge \mathbf{r}''(t)|} \\ &= \frac{\mathbf{r}'(t) \wedge \mathbf{r}''(t)}{|\mathbf{r}'(t) \wedge \mathbf{r}''(t)|}, \end{aligned}$$

$$\begin{aligned} \dot{\mathbf{b}} &= \frac{1}{|\mathbf{r}'(t)|} \frac{d\mathbf{b}}{dt} \\ &= \frac{(\mathbf{r}'(t) \wedge \mathbf{r}'''(t)) |\mathbf{r}'(t) \wedge \mathbf{r}''(t)|^2 - \langle \mathbf{r}'(t) \wedge \mathbf{r}''(t), \mathbf{r}'(t) \wedge \mathbf{r}'''(t) \rangle (\mathbf{r}'(t) \wedge \mathbf{r}''(t))}{|\mathbf{r}'(t)| |\mathbf{r}'(t) \wedge \mathbf{r}''(t)|^3}, \end{aligned}$$

注意到

$$\mathbf{n} = \frac{\langle \mathbf{r}'(t), \mathbf{r}'(t) \rangle \mathbf{r}''(t) - \langle \mathbf{r}'(t), \mathbf{r}''(t) \rangle \mathbf{r}'(t)}{|\mathbf{r}'(t)| |\mathbf{r}'(t) \wedge \mathbf{r}''(t)|},$$

则得挠率

$$\begin{aligned}\tau(t) &= -\langle \dot{\mathbf{b}}(t), \mathbf{n}(t) \rangle \\ &= -\frac{\langle \mathbf{r}'(t) \wedge \mathbf{r}''(t), \mathbf{r}''(t) \rangle}{|\mathbf{r}'(t) \wedge \mathbf{r}''(t)|^2} \\ &= \frac{\left(\mathbf{r}'(t), \mathbf{r}''(t), \mathbf{r}'''(t) \right)}{|\mathbf{r}'(t) \wedge \mathbf{r}''(t)|^2}.\end{aligned}$$

这样我们便得到了 \mathbb{E}^3 中参数曲线 $\mathbf{r}(t)$ 的曲率和挠率公式:

$$\kappa(t) = \frac{|\mathbf{r}'(t) \wedge \mathbf{r}''(t)|}{|\mathbf{r}'(t)|^3}, \quad \tau(t) = \frac{\left(\mathbf{r}'(t), \mathbf{r}''(t), \mathbf{r}'''(t) \right)}{|\mathbf{r}'(t) \wedge \mathbf{r}''(t)|^2}.$$

(1) 求导得

$$\begin{aligned}\mathbf{r}'(t) &= (a \sinh t, a \cosh t, b), \\ \mathbf{r}''(t) &= (a \cosh t, a \sinh t, 0), \\ \mathbf{r}'''(t) &= (a \sinh t, a \cosh t, 0),\end{aligned}$$

直接代入上述公式便有

$$\kappa(t) = \frac{a \sqrt{a^2 + b^2 \cosh 2t}}{(a^2 \cosh 2t + b^2)^{3/2}}, \quad \tau(t) = \frac{b}{a^2 + b^2 \cosh 2t}.$$

(2) 求导得

$$\begin{aligned}\mathbf{r}'(t) &= (3 - 2t, 6t, 3 + 2t), \\ \mathbf{r}''(t) &= (-2, 6, 2), \\ \mathbf{r}'''(t) &= (0, 0, 0),\end{aligned}$$

直接代入上述公式便有

$$\kappa(t) = \frac{3\sqrt{11}}{(22t^2 + 9)^{3/2}}, \quad \tau(t) \equiv 0.$$

(3) 求导得

$$\begin{aligned}\mathbf{r}'(t) &= (-a \cos t, a \sin t, b), \\ \mathbf{r}''(t) &= (a \sin t, a \cos t, 0), \\ \mathbf{r}'''(t) &= (a \cos t, -a \sin t, 0),\end{aligned}$$

直接代入上述公式便有

$$\kappa(t) = \frac{a}{a^2 + b^2}, \quad \tau(t) = -\frac{b}{a^2 + b^2}.$$

(4) 求导得

$$\begin{aligned}\mathbf{r}'(t) &= \left(a, \frac{\sqrt{2}a}{t}, -\frac{a}{t^2}\right), \\ \mathbf{r}''(t) &= \left(0, -\frac{\sqrt{2}a}{t^2}, \frac{2a}{t^3}\right), \\ \mathbf{r}'''(t) &= \left(0, \frac{2\sqrt{2}a}{t^3}, -\frac{6a}{t^4}\right),\end{aligned}$$

直接代入上述公式便有

$$\kappa(t) = \frac{\sqrt{2}t^2}{a(1+t^2)^2}, \quad \tau(t) = \frac{\sqrt{2}t^2}{a(1+t^2)^2}.$$

习题 4 (P28,T6). 证明: 曲线

$$\mathbf{r}(s) = \left(\frac{(1+s)^{\frac{3}{2}}}{3}, \frac{(1-s)^{\frac{3}{2}}}{3}, \frac{s}{\sqrt{2}}\right) \quad (-1 < s < 1)$$

以 s 为弧长参数, 并求出它的曲率、挠率和 Frenet 标架.

证明.

$$|\mathbf{r}'(s)| = \left| \left(\frac{\sqrt{1+s}}{2}, -\frac{\sqrt{1-s}}{2}, \frac{1}{\sqrt{2}} \right) \right| = 1,$$

从而可知 s 是弧长参数.

$$\begin{aligned}\mathbf{t}(s) &= \mathbf{r}'(s) = \left(\frac{\sqrt{1+s}}{2}, -\frac{\sqrt{1-s}}{2}, \frac{1}{\sqrt{2}} \right), \\ \dot{\mathbf{t}}(s) &= \frac{1}{4} \left(\frac{1}{\sqrt{1+s}}, \frac{1}{\sqrt{1-s}}, 0 \right),\end{aligned}$$

故得曲率和主法向量

$$\kappa(s) = |\dot{\mathbf{t}}(s)| = \frac{\sqrt{2}}{4\sqrt{1-s^2}}, \quad \mathbf{n}(s) = \frac{\dot{\mathbf{t}}(s)}{|\dot{\mathbf{t}}(s)|} = \frac{\sqrt{2}}{2} \left(\sqrt{1-s}, \sqrt{1+s}, 0 \right).$$

则副法向量和挠率为

$$\mathbf{b}(s) = \mathbf{t}(s) \wedge \mathbf{n}(s) = \left(-\frac{\sqrt{1+s}}{2}, \frac{\sqrt{1-s}}{2}, \frac{\sqrt{2}}{2} \right), \quad \tau(s) = \langle \mathbf{n}'(s), \mathbf{b}(s) \rangle = \frac{\sqrt{2}}{4\sqrt{1-s^2}}.$$

Frenet 标架为 $\{\mathbf{r}(s); \mathbf{t}(s), \mathbf{n}(s), \mathbf{b}(s)\}$, 数据从上.

□

习题 5 (P29,T10). 设 $\mathcal{T}(X) = XT + P$ 是 \mathbb{E}^3 的一个合同变换, $\det T = -1$, $\mathbf{r}(t)$ 是 \mathbb{E}^3 的正则曲线. 求曲线 $\tilde{\mathbf{r}} = T \circ \mathbf{r}$ 与曲线 \mathbf{r} 的弧长参数、曲率、挠率之间的关系.

解. 分别记 $\mathbf{r}(t)$ 和 $\tilde{\mathbf{r}}(t)$ 的弧长参数为 s 和 \tilde{s} , 则有

$$\tilde{s}(t) = \int_0^t |\mathbf{r}'(\theta)| d\theta = \int_0^t |\mathbf{r}'(\theta)| |\det T| d\theta = \int_0^t |\mathbf{r}'(\theta)| d\theta = s(t),$$

故二者弧长参数一致, 依次记两条曲线的相关参数为 $\mathbf{t}, \mathbf{n}, \mathbf{b}, \kappa, \tau, \tilde{\mathbf{t}}, \tilde{\mathbf{n}}, \tilde{\mathbf{b}}, \tilde{\kappa}, \tilde{\tau}$. 则有

$$\tilde{\mathbf{t}} = \frac{d\tilde{\mathbf{r}}}{d\tilde{s}} = \frac{d(rT + P)}{ds} = \frac{dr}{ds} T = \mathbf{t}T,$$

继而

$$\tilde{\kappa}\tilde{n} = \frac{d\tilde{t}}{d\tilde{s}} = \frac{dt}{ds} = \frac{dt}{ds}T = \kappa nT,$$

这便表明

$$\tilde{\kappa} = \kappa, \quad \tilde{n} = nT.$$

$\tilde{r}(t)$ 副法向量

$$\tilde{b} = \tilde{t} \wedge \tilde{n} = (tT) \wedge (nT) = \det T \cdot (t \wedge n)T = -(t \wedge n)T = -bT,$$

上述倒数第二个等式用到了第一章习题 5 的结果:

$$(\mathcal{T}v) \wedge (\mathcal{T}w) = \det \mathcal{T} \cdot \mathcal{T}(v \wedge w),$$

其中 \mathcal{T} 是 \mathbb{E}^3 的一个合同变换, $\tilde{r}(t)$ 挠率为

$$\tilde{\tau} = \left\langle \frac{d\tilde{n}}{d\tilde{s}} \right\rangle = \left\langle \frac{dn}{ds}T, -bT \right\rangle = -\frac{dn}{ds}T \cdot (bT)^t = -\frac{dn}{ds}T \cdot T^t b^t = -\left\langle \frac{dn}{ds}, b \right\rangle = -\tau.$$

综上所述, $\tilde{r}(t)$ 和 $r(t)$ 满足关系:

$$\tilde{s}(t) = s(t), \quad \tilde{\kappa}(t) = \kappa(t), \quad \tilde{\tau}(t) = -\tau(t).$$

习题 6 (P29,T11). 设弧长参数曲线 $C : r(s)$ 的曲率 $\kappa > 0$, 挠率 $\tau > 0$, $b(s)$ 是 C 的副法向量, 定义曲线 \tilde{C} :

$$\tilde{r}(s) = \int_0^s b(u)du,$$

(1) 证明 s 是曲线 C 的弧长参数并且 $\tilde{\kappa} = \tau$, $\tilde{\tau} = \kappa$;

(2) 求 C 的 Frenet 标架.

证明. (1) 由于 $|\tilde{r}'(s)| = |b(s)| = 1$, 故 s 是曲线 \tilde{C} 的弧长参数.

$$\tilde{t}(s) = \frac{d\tilde{r}}{ds} = b(s), \quad \dot{\tilde{t}}(s) = \frac{d\tilde{t}}{ds} = \frac{db}{ds} = -\tau(s)n(s),$$

故有

$$\tilde{\kappa}(s) = \tau(s), \quad \tilde{n}(s) = \frac{\dot{\tilde{t}}(s)}{\tilde{\kappa}(s)} = -n(s), \quad \tilde{b}(s) = \tilde{t}(s) \wedge \tilde{n}(s) = -b(s) \wedge n(s) = t(s),$$

$$\dot{\tilde{b}}(s) = \frac{dt}{ds} = \kappa(s)n(s), \quad \tilde{\tau}(s) = -\langle \dot{\tilde{b}}(s), \tilde{b}(s) \rangle = \kappa(s).$$

(2) 由上述计算过程可知, 曲线 \tilde{C} 的 Frenet 标架为

$$\{\tilde{r}(s); \tilde{t}(s), \tilde{n}(s), \tilde{b}(s)\} = \{\tilde{r}(s); b(s), -n(s), t(s)\},$$

由 $r(s)$ 易得曲线 \tilde{C} 的 Frenet 方程. □

习题 7 (P29,T12). 设曲线 $r(s)$, 它的曲率和挠率分别是 $\kappa, \tau, r(s)$ 的单位切向量 $t(s)$ 可视作单位球面 S^2 上的一条曲线, 称为曲线 $r(s)$ 的切线像. 证明: 曲线 $\tilde{r}(s) = t(s)$ 的曲率、挠率分别为

$$\tilde{\kappa} = \sqrt{1 + \left(\frac{\tau}{\kappa}\right)^2}, \quad \tilde{\tau} = \frac{\frac{d}{ds}\left(\frac{\tau}{\kappa}\right)}{\kappa[1 + (\frac{\tau}{\kappa})^2]}.$$

证明. 注意 s 不一定是曲线 $\tilde{r}(s)$ 的弧长参数, 可利用第二章第 5 题的结论, 直接计算有

$$\begin{aligned}\tilde{r}'(s) &= \frac{d\mathbf{t}}{ds} = \kappa \mathbf{n}, \quad |\tilde{r}'(s)| = \kappa, \\ \tilde{r}''(s) &= \frac{d}{ds}(\kappa \mathbf{n}) = \kappa' \mathbf{n} + \kappa \frac{d\mathbf{n}}{ds} = \kappa' \mathbf{n} + \kappa(-\kappa \mathbf{t} + \tau \mathbf{b}) \\ &= -\kappa^2 \mathbf{t} + \kappa' \mathbf{n} + \kappa \tau \mathbf{b}, \\ \tilde{r}'''(s) &= \kappa'' \mathbf{n} + \kappa' \frac{d\mathbf{n}}{ds} - 2\kappa \kappa' \mathbf{t} - \kappa^2 \frac{d\mathbf{t}}{ds} + \kappa' \tau \mathbf{b} + \kappa \tau' \mathbf{b} + \kappa \tau \frac{d\mathbf{b}}{ds} \\ &= \kappa'' \mathbf{n} + \kappa'(-\kappa \mathbf{t} + \tau \mathbf{b}) - 2\kappa \kappa' \mathbf{t} - \kappa^2(\kappa \mathbf{n}) + \kappa' \tau \mathbf{b} + \kappa \tau' \mathbf{b} + \kappa \tau(-\tau \mathbf{n}) \\ &= -3\kappa \kappa' \mathbf{t} + (\kappa'' - \kappa^3 - \kappa \tau^2) \mathbf{n} + (2\kappa' \tau + \kappa \tau') \mathbf{b},\end{aligned}$$

则有

$$\begin{aligned}\tilde{r}'(s) \wedge \tilde{r}''(s) &= \kappa^2 \tau \mathbf{t} + \kappa^3 \mathbf{b}, \quad |\tilde{r}'(s) \wedge \tilde{r}''(s)| = \kappa^2 \sqrt{\kappa^2 + \tau^2}, \\ (\tilde{r}'(s), \tilde{r}''(s), \tilde{r}'''(s)) &= \langle \tilde{r}'(s) \wedge \tilde{r}''(s), \tilde{r}'''(s) \rangle \\ &= \kappa^2 \tau(-3\kappa \kappa') + \kappa^3(2\kappa' \tau + \kappa \tau') \\ &= \kappa^4 \tau' - \kappa^3 \kappa' \tau,\end{aligned}$$

故得 $\tilde{r}(s)$ 的曲率和挠率分别为

$$\begin{aligned}\tilde{\kappa} &= \frac{|\tilde{r}'(s) \wedge \tilde{r}''(s)|}{|\tilde{r}'(s)|^3} = \sqrt{1 + \left(\frac{\tau}{\kappa}\right)^2}, \\ \tilde{\tau} &= \frac{(\tilde{r}'(s), \tilde{r}''(s), \tilde{r}'''(s))}{|\tilde{r}'(s) \wedge \tilde{r}''(s)|^2} = \frac{\kappa^4 \tau' - \kappa^3 \kappa' \tau}{\kappa^4(\kappa^2 + \tau^2)} = \frac{\frac{d}{ds}(\frac{\tau}{\kappa})}{\kappa[1 + (\frac{\tau}{\kappa})^2]}.\end{aligned}$$

□

习题 8 (P29,T13). (1) 求曲率 $\kappa(s) = \frac{a}{a^2+s^2}$ (s 是弧长参数) 的平面曲线;

(2) 求曲率 $\kappa(s) = \frac{1}{\sqrt{a^2-s^2}}$ (s 是弧长参数) 的平面曲线.

解. 对于弧长参数平面曲线 $r(s) = (x(s), y(s))$, 假设已知曲率 $\kappa(s)$, 下面我们给出曲线方程的一般求解过程:

首先 s 作为弧长参数给出了约束条件:

$$(x'(s))^2 + (y'(s))^2 = 1 \tag{1}$$

接下来有

$$\begin{aligned}\mathbf{t}(s) &= \mathbf{r}'(s) = (x'(s), y'(s)), \\ \mathbf{n}(s) &= (-y'(s), x'(s)), \\ \dot{\mathbf{t}}(s) &= \mathbf{r}''(s) = (x''(s), y''(s)) = \kappa(s) \mathbf{n}(s),\end{aligned}$$

则应有方程:

$$\begin{cases} x''(s) &= -\kappa(s)y'(s), \\ y''(s) &= \kappa(s)x'(s), \end{cases} \tag{2}$$

根据方程 (1) 我们可以假设

$$\begin{cases} x'(s) &= \cos(\theta(s)), \\ y'(s) &= \sin(\theta(s)), \end{cases} \tag{3}$$

其中 $\theta = \theta(s)$ 是关于 s 的函数, 结合方程 (2)、(3) 我们有关于 $\theta(s)$ 的一阶 ODE

$$\theta'(s) = \kappa(s), \quad (4)$$

则有

$$\theta(s) = \theta(0) + \int_0^s \kappa(t) dt = \int_0^s \kappa(t) dt, (\text{相差一个刚体运动}) \quad (5)$$

(1) 若 $\kappa(s) = \frac{a}{a^2+s^2}$, 则由 (4) 知 $\theta(s) = \int_0^s \frac{a}{a^2+s^2} ds = \arctan \frac{s}{a}$, 从而有

$$\begin{cases} x(s) &= x(0) + \int_0^s x'(t) dt = x(0) + \int_0^s \cos(\arctan \frac{t}{a}) dt \\ &= x(0) + \int_0^s \frac{a}{\sqrt{a^2+t^2}} dt = x(0) + a \ln(s + \sqrt{a^2 + s^2}), \\ y(s) &= y(0) + \int_0^s y'(t) dt = y(0) + \int_0^s \sin(\arctan \frac{t}{a}) dt \\ &= y(0) + \int_0^s \frac{s}{\sqrt{a^2+t^2}} dt = y(0) + \sqrt{a^2 + s^2}, \end{cases}$$

所以我们要求的平面曲线为 $\mathbf{r}(s) = (a \ln(s + \sqrt{a^2 + s^2}), \sqrt{a^2 + s^2})$ (相差一个刚体运动, 这是由于曲率的刚体不变性).

(2) 若 $\kappa(s) = \frac{1}{\sqrt{a^2-s^2}}$, 则由 (4) 知 $\theta(s) = \int_0^s \frac{1}{\sqrt{a^2-s^2}} ds = \arcsin \frac{s}{a}$, 从而有

$$\begin{cases} x(s) &= x(0) + \int_0^s x'(t) dt = x(0) + \int_0^s \cos(\arcsin \frac{t}{a}) dt \\ &= x(0) + \int_0^s \sqrt{1 - (\frac{t}{a})^2} dt = x(0) + \frac{1}{2} \left(s \sqrt{1 - (\frac{t}{a})^2} + a \arcsin \frac{s}{a} \right), \\ y(s) &= y(0) + \int_0^s y'(s) ds = y(0) + \int_0^s \sin(\arcsin \frac{t}{a}) dt \\ &= y(0) + \int_0^s \frac{t}{a} dt = y(0) + \frac{s^2}{2a}, \end{cases}$$

所以我们要求的平面曲线为 $\mathbf{r}(s) = \left(\frac{1}{2} \left(s \sqrt{1 - (\frac{t}{a})^2} + a \arcsin \frac{s}{a} \right), \frac{s^2}{2a} \right)$ (相差一个刚体运动, 这是由于曲率的刚体不变性).

习题 9 (P29,T14). 证明: 对 \mathbb{E}^3 的弧长参数曲线 $\mathbf{r}(s)$, 有

$$(1) \left(\frac{d\mathbf{r}}{ds}, \frac{d^2\mathbf{r}}{ds^2}, \frac{d^3\mathbf{r}}{ds^3} \right) = \kappa^2 \tau;$$

$$(2) \left(\frac{dt}{ds}, \frac{d^2t}{ds^2}, \frac{d^3t}{ds^3} \right) = \kappa^3 (\kappa \dot{\tau} - \dot{\kappa} \tau) = \kappa^5 \frac{d}{ds} \left(\frac{\tau}{\kappa} \right).$$

证明. (1) 直接计算有

$$\frac{d\mathbf{r}}{ds} = \mathbf{t}, \quad \frac{d^2\mathbf{r}}{ds^2} = \dot{\mathbf{t}} = \kappa \mathbf{n}, \quad \frac{d^3\mathbf{r}}{ds^3} = \ddot{\mathbf{t}} = \kappa \mathbf{n} + \kappa \dot{\mathbf{n}} = \kappa \mathbf{n} + \kappa (-\kappa \mathbf{t} + \tau \mathbf{b}) = -\kappa^2 \mathbf{t} + \kappa \mathbf{n} + \kappa \tau \mathbf{b},$$

故有

$$\begin{aligned} \left(\frac{d\mathbf{r}}{ds}, \frac{d^2\mathbf{r}}{ds^2}, \frac{d^3\mathbf{r}}{ds^3} \right) &= \left\langle \frac{d\mathbf{r}}{ds}, \frac{d^2\mathbf{r}}{ds^2}, \frac{d^3\mathbf{r}}{ds^3} \right\rangle = \langle \mathbf{t} \wedge \kappa \mathbf{n}, -\kappa^2 \mathbf{t} + \kappa \mathbf{n} + \kappa \tau \mathbf{b} \rangle \\ &= \langle \kappa \mathbf{b}, -\kappa^2 \mathbf{t} + \kappa \mathbf{n} + \kappa \tau \mathbf{b} \rangle \\ &= \kappa^2 \tau. \end{aligned}$$

(2) 利用 (1) 直接计算有

$$\frac{d\mathbf{t}}{ds} = \frac{d^2\mathbf{r}}{ds^2} = \kappa \mathbf{n}, \quad \frac{d^2\mathbf{t}}{ds^2} = \frac{d^3\mathbf{r}}{ds^3} = -\kappa^2 \mathbf{t} + \kappa \mathbf{n} + \kappa \tau \mathbf{b},$$

$$\begin{aligned}
\frac{d^3 \mathbf{t}}{ds^3} &= -2\kappa\dot{\kappa}\mathbf{t} + \ddot{\kappa}\mathbf{n} + \dot{\kappa}\dot{\mathbf{n}} + \dot{\kappa}\tau\mathbf{b} + \kappa\dot{\tau}\mathbf{b} + \kappa\tau\dot{\mathbf{b}} \\
&= -2\kappa\dot{\kappa}\mathbf{t} + \ddot{\kappa}\mathbf{n} + \dot{\kappa}(-\kappa\mathbf{t} + \tau\mathbf{b}) + \dot{\kappa}\tau\mathbf{b} + \kappa\dot{\tau}\mathbf{b} + \kappa\tau(-\tau\mathbf{n}) \\
&= -3\kappa\dot{\kappa}\mathbf{t} + (\ddot{\kappa} - \kappa\tau^2)\mathbf{n} + (2\dot{\kappa}\tau + \kappa\dot{\tau})\mathbf{b},
\end{aligned}$$

故有

$$\begin{aligned}
\left(\frac{d\mathbf{t}}{ds}, \frac{d^2\mathbf{t}}{ds^2}, \frac{d^3\mathbf{t}}{ds^3} \right) &= \left\langle \frac{d\mathbf{t}}{ds} \wedge \frac{d^2\mathbf{t}}{ds^2}, \frac{d^3\mathbf{t}}{ds^3} \right\rangle \\
&= \left\langle \kappa\mathbf{n} \wedge (-\kappa^2\mathbf{t} + \ddot{\kappa}\mathbf{n} + \kappa\tau\mathbf{b}), -3\kappa\dot{\kappa}\mathbf{t} + (\ddot{\kappa} - \kappa\tau^2)\mathbf{n} + (2\dot{\kappa}\tau + \kappa\dot{\tau})\mathbf{b} \right\rangle \\
&= \left\langle \kappa^2\tau\mathbf{t} + \kappa^3\mathbf{b}, -3\kappa\dot{\kappa}\mathbf{t} + (\ddot{\kappa} - \kappa\tau^2)\mathbf{n} + (2\dot{\kappa}\tau + \kappa\dot{\tau})\mathbf{b} \right\rangle \\
&= \kappa^4\dot{\tau} - \kappa^3\dot{\kappa}\tau \\
&= \kappa^5 \frac{d}{ds} \left(\frac{\tau}{\kappa} \right).
\end{aligned}$$

□

习题 10 (P29,T15). 证明: 满足条件

$$\left(\frac{1}{\kappa} \right)^2 + \left[\frac{1}{\tau} \frac{d}{ds} \left(\frac{1}{\kappa} \right) \right]^2 = \text{常数} \quad (6)$$

的曲线, 或者是球面曲线, 或者 κ 是常数.

证明. 显然 κ 是常数满足条件, 下设 κ 不是常数. 实际上若 κ 不为常数, $\mathbf{r}(s)$ 是球面曲线当且仅当上述方程成立, 不妨设 s 为弧长参数.

先证必要性:

若 $\mathbf{r}(s)$ 是球面曲线, 则存在某常数 C 和固定点 $\mathbf{r}(s_0)$ 使得

$$|\mathbf{r}(s) - \mathbf{r}(s_0)| = C, \quad (7)$$

求导有

$$\langle \mathbf{r}(s) - \mathbf{r}(s_0), \mathbf{t}(s) \rangle = 0, \quad (8)$$

$$1 + \langle \mathbf{r}(s) - \mathbf{r}(s_0), \kappa(s)\mathbf{n}(s) \rangle = 0, \quad (9)$$

$$\langle \mathbf{t}(s), \kappa(s)\mathbf{n}(s) \rangle + \langle \mathbf{r}(s) - \mathbf{r}(s_0), \kappa'(s)\mathbf{n}(s) + \kappa(s)(-\kappa(s)\mathbf{t}(s) + \tau(s)\mathbf{b}(s)) \rangle = 0, \quad (10)$$

由 (8)、(9)、(10) 可得 $\mathbf{r}(s) - \mathbf{r}(s_0) \in \text{Span}\{\mathbf{n}(s), \mathbf{b}(s)\}$, 并且

$$\langle \mathbf{r}(s) - \mathbf{r}(s_0), \mathbf{n}(s) \rangle = -\frac{1}{\kappa(s)}, \quad (11)$$

$$\langle \mathbf{r}(s) - \mathbf{r}(s_0), \mathbf{b}(s) \rangle = \frac{1}{\tau(s)} \frac{\kappa'(s)}{\kappa^2(s)} = -\frac{1}{\tau(s)} \frac{d}{ds} \left(\frac{1}{\kappa(s)} \right), \quad (12)$$

由于 $\mathbf{r}(s) - \mathbf{r}(s_0) = \langle \mathbf{r}(s) - \mathbf{r}(s_0), \mathbf{n}(s) \rangle \mathbf{n}(s) + \langle \mathbf{r}(s) - \mathbf{r}(s_0), \mathbf{b}(s) \rangle \mathbf{b}(s)$, 再结合 (7)、(11)、(12) 便得方程 (6).

再证充分性:

构造参数曲线

$$\tilde{\mathbf{r}}(s) = \mathbf{r}(s) + \frac{1}{\kappa(s)}\mathbf{n}(s) + \frac{1}{\tau(s)} \frac{d}{ds} \left(\frac{1}{\kappa(s)} \right) \mathbf{b}(s),$$

下面证如此构造的参数曲线 $\tilde{r}(s)$ 是常数曲线:

$$\begin{aligned}\tilde{r}'(s) &= \mathbf{t}(s) + \frac{d}{ds} \left(\frac{1}{\kappa(s)} \right) \mathbf{n}(s) + \frac{1}{\kappa(s)} (-\kappa(s)\mathbf{t}(s) + \tau(s)\mathbf{b}(s)) \\ &\quad + \frac{d}{ds} \left(\frac{1}{\tau(s)} \frac{d}{ds} \left(\frac{1}{\kappa(s)} \right) \right) \mathbf{b}(s) + \frac{1}{\tau(s)} \frac{d}{ds} \left(\frac{1}{\kappa(s)} \right) (-\tau(s)\mathbf{n}(s)) \\ &= \tau(s) \left\{ \frac{1}{\kappa(s)} + \frac{1}{\tau(s)} \frac{d}{ds} \left[\frac{1}{\tau(s)} \frac{d}{ds} \left(\frac{1}{\kappa(s)} \right) \right] \right\} \mathbf{b}(s),\end{aligned}\tag{13}$$

由原方程 (6) 有

$$2 \frac{1}{\kappa(s)} \frac{d}{ds} \left(\frac{1}{\kappa(s)} \right) + 2 \frac{1}{\tau(s)} \frac{d}{ds} \left(\frac{1}{\kappa(s)} \right) \frac{d}{ds} \left(\frac{1}{\tau(s)} \frac{d}{ds} \left(\frac{1}{\kappa(s)} \right) \right) = 0,\tag{14}$$

这表明

$$\frac{1}{\kappa(s)} + \frac{1}{\tau(s)} \frac{d}{ds} \left(\frac{1}{\tau(s)} \frac{d}{ds} \left(\frac{1}{\kappa(s)} \right) \right) = 0,$$

结合 (13) 我们可知

$$\tilde{r}'(s) \equiv 0,$$

从而

$$\mathbf{r}(s_0) = \tilde{\mathbf{r}}(s) = \tilde{\mathbf{r}}(s) = \mathbf{r}(s) + \frac{1}{\kappa(s)} \mathbf{n}(s) + \frac{1}{\tau(s)} \frac{d}{ds} \left(\frac{1}{\kappa(s)} \right) \mathbf{b}(s),$$

结合 (6) 我们最终得到

$$|\mathbf{r}(s) - \mathbf{r}(s_0)| = \text{常数},$$

这样我们便证明了 $\mathbf{r}(s)$ 是球面曲线.

□

习题 11 (P30,T20). 证明: 曲线 $\mathbf{r}(t) = (t + \sqrt{3} \sin t, 2 \cos t, \sqrt{3}t - \sin t)$ 与曲线 $\tilde{\mathbf{r}}(t) = (2 \cos \frac{t}{2}, 2 \sin \frac{t}{2}, -t)$ 是合同的.

证明. 要证明 $\mathbf{r}(t)$ 和 $\tilde{\mathbf{r}}(t)$ 的合同性, 我们需要下面的定理:

定理 (P25, 定理 4.2). 设 $\mathbf{r}_1(s)$ 和 $\mathbf{r}_2(s)$ 是 \mathbb{E}^3 的两条弧长参数曲线, 定义在同一个参数区间 (a, b) 上. 设 $\kappa_1(s) = \kappa_2(s) > 0$, $\tau_1(s) = \tau_2(s)$, $\forall s \in (a, b)$. 则存在 \mathbb{E}^3 的一个刚体运动 \mathcal{T} 把曲线 \mathbf{r}_2 变成 \mathbf{r}_1 , 即 $\mathbf{r}_1 = \mathcal{T} \circ \mathbf{r}_2$, 也即曲线 \mathbf{r}_1 和 \mathbf{r}_2 是合同的.

直接计算有

$$\begin{aligned}\mathbf{r}'(t) &= (1 + \sqrt{3} \cos t, -2 \sin t, \sqrt{3} - \cos t), & \tilde{\mathbf{r}}'(t) &= (-\sin \frac{t}{2}, \cos \frac{t}{2}, -1); \\ \mathbf{r}''(t) &= (-\sqrt{3} \sin t, -2 \cos t, \sin t), & \tilde{\mathbf{r}}''(t) &= (-\frac{1}{2} \cos \frac{t}{2}, -\frac{1}{2} \sin \frac{t}{2}, 0); \\ \mathbf{r}'''(t) &= (-\sqrt{3} \cos t, 2 \sin t, \cos t), & \tilde{\mathbf{r}}'''(t) &= (\frac{1}{4} \sin \frac{t}{2}, -\frac{1}{4} \cos \frac{t}{2}, 0);\end{aligned}$$

从而便有

$$\begin{aligned}\kappa(t) &= \frac{|\mathbf{r}'(t) \wedge \mathbf{r}''(t)|}{|\mathbf{r}'(t)|^3} = \frac{1}{4}, & \tilde{\kappa}(t) &= \frac{|\tilde{\mathbf{r}}'(t) \wedge \tilde{\mathbf{r}}''(t)|}{|\tilde{\mathbf{r}}'(t)|^3} = \frac{1}{4}; \\ \tau(t) &= \frac{(\mathbf{r}'(t), \mathbf{r}''(t), \mathbf{r}'''(t))}{|\mathbf{r}'(t) \wedge \mathbf{r}''(t)|^2} = -\frac{1}{4}, & \tilde{\tau}(t) &= \frac{(\tilde{\mathbf{r}}'(t), \tilde{\mathbf{r}}''(t), \tilde{\mathbf{r}}'''(t))}{|\tilde{\mathbf{r}}'(t) \wedge \tilde{\mathbf{r}}''(t)|^2} = -\frac{1}{4};\end{aligned}$$

由此可知曲线 $\mathbf{r}(t)$ 与 $\tilde{\mathbf{r}}(t)$ 是合同的.

□

2.2 习题解析

2.2.1

注 弧长指曲线长度，若曲线长度无限，求一段的长度。

(1) 提示 $\sqrt{ax^2 + c}$ 的原函数为

$$\frac{x}{2}\sqrt{ax^2 + c} + \frac{c}{2\sqrt{a}} \log(x\sqrt{a} + \sqrt{ax^2 + c})$$

$$k = \frac{2|a|}{(4a^2x^2 + 1)^{\frac{3}{2}}}$$

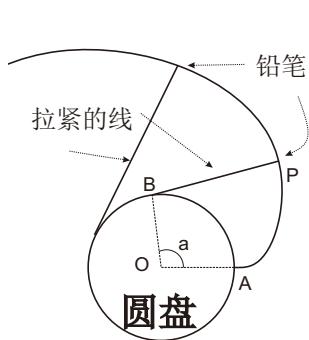
(2)

$$k = \frac{1}{\left(\frac{x^2}{a^4} + \frac{y^2}{b^4}\right)^{\frac{3}{2}} a^2 b^2}$$

$$\text{周长} = 2a\pi \left[1 - \left(\frac{1}{2}\right)^2 e^2 - \left(\frac{1 \cdot 3}{2 \cdot 4}\right)^2 \frac{e^4}{3} - \left(\frac{1 \cdot 3 \cdot 5}{2 \cdot 4 \cdot 6}\right)^2 \frac{e^6}{5} - \dots \right]$$

$$(3) k = \frac{|ab|}{(a^2 sh^2 t + b^2 ch^2 t)^{\frac{3}{2}}}, \quad (4) k = \frac{1}{ach^2 \frac{t}{a}}$$

◎补充习题.



如左图所示，在圆盘上绕上一根不会伸缩的细线，线端栓一支铅笔，将线端拉紧，并逐渐拉开，铅笔尖在纸上画出的曲线就是圆的渐开线。求

(1) 渐开线的参数表达式，

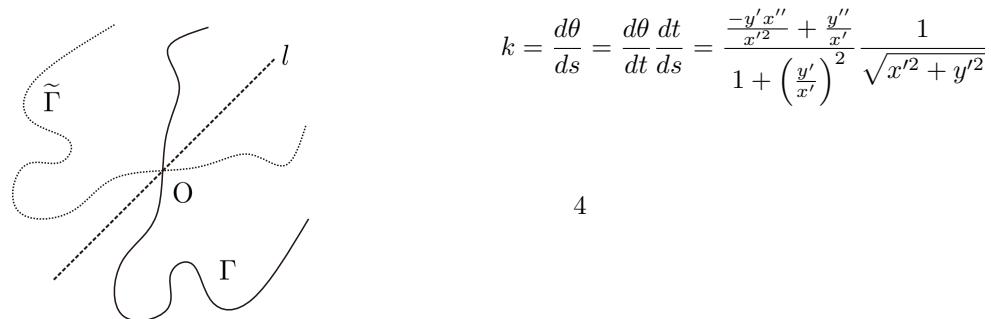
(2) 渐开线的曲率，

(3) AP 段的弧长，已知 OA 与 OB 的夹角为 a 。

2.2.2

$$\vec{t} = \frac{(x', y')}{\sqrt{x'^2 + y'^2}}, \quad \frac{ds}{dt} = \left| \frac{d\vec{r}}{dt} \right| = \sqrt{x'^2 + y'^2}$$

若记 θ 为曲线切向与 x 轴的夹角，如果在一点处 $x' \neq 0$ 则在这一点的邻域内 $x' \neq 0$, $\theta = \arctan \frac{y'}{x'}$



若在某点 P 处, $x' = 0$ 则 $y' \neq 0$, 不妨设这点为原点。可将曲线沿直线 l 翻转(这里 $l = \{x = y\}$)。翻转得到的曲线记为 $\tilde{\Gamma}$, $\tilde{\Gamma}$ 的参数表达式为 $\tilde{r}(t) = (y(t), x(t))$ 。 $\tilde{\Gamma}$ 的曲率 $\tilde{k}(t) = -k(t)$, 再利用前面结果(交换 x, y), 得:

$$\tilde{k}(t) = -k(t) = -\frac{-y''x' + y'x''}{(x'^2 + y'^2)^{\frac{3}{2}}}$$

2.2.3 略

2.2.4

$$(1) \quad k = \frac{a\sqrt{a^2 + b^2}ch2t}{(a^2ch2t + b^2)^{\frac{3}{2}}}, \quad \tau = \frac{b}{b^2ch2t + a^2} \quad (2) \quad \tau = 0, \quad k = \frac{3\sqrt{11}}{(22t^2 + 9)^{\frac{3}{2}}}$$

$$(3) \quad k = \frac{a}{a^2 + b^2}, \quad \tau = \frac{-b}{a^2 + b^2} \quad (4) \quad k = \frac{\sqrt{2}t^2}{a(1 + t^2)^2}, \quad \tau = \frac{\sqrt{2}t^2}{a(1 + t^2)}$$

2.2.5

$$\begin{aligned} \vec{r}'(t) &= \frac{d\vec{r}}{ds} \frac{ds}{dt} = \vec{t} \left| \frac{d\vec{r}}{dt} \right| \\ \vec{r}''(t) &= \frac{d\vec{t}}{ds} \left(\frac{ds}{dt} \right)^2 + \vec{t} \frac{d}{dt} \left| \frac{d\vec{r}}{dt} \right| = k\vec{n} \left| \frac{d\vec{r}}{dt} \right|^2 + \vec{t} \frac{d}{dt} \left| \frac{d\vec{r}}{dt} \right| \\ \vec{r}'''(t) &= k\tau\vec{b} \left| \frac{d\vec{r}}{dt} \right|^2 + (*)\vec{n} + (*)\vec{t} \end{aligned}$$

将以上表达式代入, 并利用 $(\vec{t}, \vec{n}, \vec{b}) = 1$ 即可。

⑤补充习题. 判断如下两等式是否正确: (1) $\frac{ds}{dt} = \left| \frac{d\vec{r}}{dt} \right|$, (2) $\frac{d^2s}{dt^2} = \left| \frac{d^2\vec{r}}{dt^2} \right|$.

2.2.6

$$\vec{t} = \left(\frac{\sqrt{1+s}}{2}, \frac{\sqrt{1-s}}{2}, \frac{1}{\sqrt{2}} \right)$$

$$\vec{n} = \left(\frac{\sqrt{1-s}}{\sqrt{2}}, -\frac{\sqrt{1+s}}{\sqrt{2}}, 0 \right)$$

$$\vec{b} = \left(-\frac{\sqrt{1+s}}{2}, -\frac{\sqrt{1-s}}{2}, \frac{1}{\sqrt{2}} \right)$$

$$b = k = \frac{1}{2\sqrt{2}\sqrt{1-s^2}}$$

⑥补充习题. 证明该曲线落在一个圆锥面上。

2.2.7

(1) 由于 $e^{-\frac{1}{t^2}}$ 的各阶导数 = 0.

(2)

$$t \rightarrow 0^-, \{\vec{t}, \vec{n}, \vec{b}\} \rightarrow \{(0, 1, 0), (1, 0, 0), (0, 0, -1)\},$$

$$t \rightarrow 0^+, \{\vec{t}, \vec{n}, \vec{b}\} \rightarrow \{(0, 1, 0), (0, 0, 1), (1, 0, 0)\},$$

◎补充习题. 是否存在满足以下要求的定义在 $(0, 1]$ 上的光滑空间曲线 $\vec{r}(t)$, 若存在请具体构造, 若不存在请说明理由

1. 当 $t \rightarrow 0$ 时, $k, \tau \rightarrow \infty$, $\vec{r}(t) \rightarrow$ 原点, 且曲线长度有限, 即

$$\int_{\epsilon}^1 |\vec{r}(t)| dt \leq 1, \text{ 对所有 } \epsilon > 0$$

2. 当 $t \rightarrow 0$ 时, $k \rightarrow 0, \tau \rightarrow \infty$ (且要求存在常数 $\delta > 0$, s.t. $k > \delta t$), $\vec{r}(t) \rightarrow$ 原点. 仍然要求曲线长度有限。

3. 当 $t \rightarrow 0$ 时, $k \rightarrow \infty, \tau \rightarrow 0$ (且要求 $\tau > 0$), $\vec{r}(t) \rightarrow$ 原点. 仍然要求曲线长度有限。

4. 当 $t \rightarrow 0$ 时, $k \rightarrow 0, \tau \rightarrow 0$, $\vec{r}(t) \rightarrow$ 原点, 但要求曲线长度无限, 即

$$\int_{\epsilon}^1 |\vec{r}(t)| dt \rightarrow \infty, \text{ as } \epsilon \rightarrow 0$$

2.2.8

若存在 $\epsilon > 0$, 使得 $\vec{r}(t)$ 在 $\{t_0 - \epsilon, t_0 + \epsilon\}$ 上有定义, 则

$$0 = \frac{d|\vec{r} - P_0|^2}{dt}(t_0) = \frac{d}{dt} \langle \vec{r} - P_0, \vec{r} - P_0 \rangle(t_0) = 2 \langle \frac{d}{dt} \vec{r}(t_0), \vec{r}(t_0) - P_0 \rangle = 2 \langle \vec{t}(t_0) \frac{ds}{dt}, \vec{r}(t_0) - P_0 \rangle$$

2.2.9

(1) 设存在 λ , 使得 $\vec{r} + \lambda \vec{t} = 0$, 求导得 $\vec{t} + \lambda k \vec{n} + \lambda' \vec{t} = 0 \Rightarrow \lambda' = -1, \lambda k = 0$. 故在 $\lambda \neq 0$ 处 $k = 0$, 由于 k 是连续函数, 且 λ 只能在孤立点处取零, 所以 $k \equiv 0$.

(2) 设存在 λ , 使得 $\vec{r} + \lambda \vec{n} = 0$, 求导得 $\vec{t} + \lambda(-k \vec{t} + \tau \vec{b}) + \lambda' \vec{n} = 0 \Rightarrow \lambda k = 1, \lambda \tau = 0, \lambda' = 0$. 故 $\lambda \equiv Constant$, 且 $\lambda \neq 0$ (因为 $\lambda k = 1$). 由此 $\tau \equiv 0, k = \frac{1}{\lambda} \equiv Constant$

◎补充习题. 我们称空间曲线一点处的主法向 \vec{n} 和副法向 \vec{b} 张成的平面为曲线在该点处的法平面, 证明: 若一条曲线 ($k \neq 0$) 在任意点处的法平面过定点, 则该曲面是球面曲线。

◎补充习题. 是否存在一条光滑的空间曲线, 副法线过定点?

◎补充习题. $\vec{r}(t)$ 为 R^3 中正则曲线, 存在常数 $\alpha_1, \alpha_2, \alpha_3$, 使得直线族 $\{\vec{r}(t) + \lambda(\alpha_1 \vec{t}(t) + \alpha_2 \vec{n}(t) + \alpha_3 \vec{b}(t)) | \lambda \in R\}$ 过定点, 问给定 $\alpha_1, \alpha_2, \alpha_3$, 如果曲线足够长, 我们是否可以确定这条曲线的几何形状?

◎补充习题. 判断如下命题是否正确, 如正确请证明, 不正确请举例说明。

若 R^3 中一条曲线主法线过给定直线, 则该曲线为圆柱螺线或圆。

2.2.10

弧长参数不变, $\tilde{n}(t) = n(t), \tilde{\tau}(t) = -\tau(t)$

2.2.11

先求出 $\tilde{r}(s)$ 的Frenet标架, 由于 $|\vec{b}| = 1$ 故 s 也是 \tilde{r} 的弧长参数。

$$\begin{aligned}\tilde{t}(s) &= \frac{d\tilde{r}(s)}{ds} = \vec{b}(s) \\ \tilde{n}(s) &= \frac{d\tilde{t}(s)}{ds} / \left| \frac{d\tilde{t}(s)}{ds} \right| = \frac{d\vec{b}(s)}{ds} / \left| \frac{d\vec{b}(s)}{ds} \right| = \frac{-k\vec{n}}{k} = -\vec{n} \\ \tilde{b}(s) &= \tilde{t} \wedge \tilde{n} = \tilde{b} \wedge (-\vec{n}) = \vec{t} \\ \Rightarrow \tilde{k} &= \left| \frac{d\tilde{t}(s)}{ds} \right| = \left| \frac{d\vec{b}(s)}{ds} \right| = \tau, \quad \tilde{\tau} = \left\langle \frac{d\tilde{n}}{ds}, \tilde{b}(s) \right\rangle = \left\langle k\vec{t} - \tau\vec{b}, \vec{t} \right\rangle = k\end{aligned}$$

2.2.12

首先我们计算 $\tilde{r}(s) = \vec{t}(s)$ 的Frenet标架(记 \tilde{r} 的弧长参数为 σ)

$$\tilde{t}(s) = \frac{d\tilde{r}(\sigma)}{d\sigma} = \frac{d\tilde{r}(s)}{ds} \frac{ds}{d\sigma} = \frac{d\vec{t}(s)}{ds} \frac{ds}{d\sigma} = k\vec{n}(s) \frac{ds}{d\sigma}$$

由于 \tilde{t} 长度为1, 故 $\frac{d\sigma}{ds} = k$, 且 $\tilde{t} = \vec{n}$

$$\tilde{n}(s) = \frac{d\tilde{t}(\sigma)}{d\sigma} / \left| \frac{d\tilde{t}(\sigma)}{d\sigma} \right| = \frac{d\vec{n}(s)}{ds} \frac{ds}{d\sigma} / \left| \frac{d\tilde{t}(\sigma)}{d\sigma} \right| = \frac{-k\vec{t}(s) + \tau\vec{b}(s)}{k \left| \frac{d\tilde{t}(\sigma)}{d\sigma} \right|}$$

由于 $|\tilde{n}| = 1$, 故 $k \left| \frac{d\tilde{t}(\sigma)}{d\sigma} \right| = k\tilde{k} = \sqrt{k^2 + \tau^2} \Rightarrow \tilde{k} = \sqrt{1 + (\frac{\tau}{k})^2}$, $\tilde{n} = \frac{-k\vec{t} + \tau\vec{b}}{\sqrt{k^2 + \tau^2}}$

$$\text{由 } \vec{b} = \vec{t} \wedge \vec{n}, \text{ 得 } \vec{b} \wedge \vec{t} = \vec{n}, \vec{n} \wedge \vec{b} = \vec{t} \Rightarrow \vec{b} = \vec{t} \wedge \tilde{n} = \frac{k\vec{b} + \tau\vec{t}}{\sqrt{k^2 + \tau^2}}$$

$$\begin{aligned}\tilde{\tau} &= \left\langle \frac{d\tilde{n}(\sigma)}{d\sigma}, \tilde{b}(\sigma) \right\rangle \\ &= \left\langle \frac{ds}{d\sigma} \frac{d}{ds} \left(\frac{-k\vec{t} + \tau\vec{b}}{\sqrt{k^2 + \tau^2}} \right), \frac{k\vec{b} + \tau\vec{t}}{\sqrt{k^2 + \tau^2}} \right\rangle \\ &= \left[\frac{d}{ds} \left(\frac{-k}{\sqrt{k^2 + \tau^2}} \right) \right] \frac{\tau}{k\sqrt{k^2 + \tau^2}} + \left[\frac{d}{ds} \left(\frac{\tau}{\sqrt{k^2 + \tau^2}} \right) \right] \frac{1}{\sqrt{k^2 + \tau^2}} \\ &= \frac{1}{k} \frac{\frac{d}{ds} \left(\frac{\tau}{k} \right)}{1 + \left(\frac{\tau}{k} \right)^2}\end{aligned}$$

②补充习题. 设 $k \neq 0, \tau \neq 0$ 对 $\hat{r} = \vec{b}$ 计算曲率挠率。

2.2.13

设曲线在 (x, y) 平面上，曲线切向与 x 轴的夹角为 θ 。

(1)由曲率定义，本题应有 $a > 0$

$$k = \frac{d\theta}{ds} = \frac{a}{a^2 + s^2} \text{ 积分得 } \theta = \arctan \frac{s}{a} + C, a \tan(\theta - C) = s$$

不同的 C 意味着将曲线旋转，故不失一般性我们可以取 $C \equiv 0$.

$$\text{这时 } \vec{t} = \frac{(a, s)}{\sqrt{a^2 + s^2}}, \text{ 积分得 } \vec{r} = \left(\log\left(\sqrt{\frac{s^2}{a^2} + 1} + \frac{s}{a}\right), \sqrt{a^2 + s^2} \right)$$

(2)

$$k = \frac{d\theta}{ds} = \frac{1}{\sqrt{a^2 - s^2}}, \text{ 积分得 } \theta = \arcsin \frac{s}{a} + C, \sin(\theta - C) = \frac{s}{a}$$

$$\text{同上可以取 } C \equiv 0, \text{ 这时 } \vec{t} = \left(\frac{\sqrt{a^2 - s^2}}{a}, \frac{s}{a} \right), (\text{这里假设 } a > 0)$$

$$\text{积分得 } \vec{r} = \left(\frac{a}{2} \left(\frac{s}{a} \sqrt{1 - \frac{s^2}{a^2}} + \arcsin \frac{s}{a} \right), \frac{s^2}{2a} \right)$$

◎补充习题. 试求出以上两曲线更简洁的(非弧长参数)表达式。

◎补充习题. 有一条平面曲线 $\vec{r}(t)$,

$$|\frac{d\vec{r}}{dt}| = \sqrt{1 + t^2}, k = \frac{t^2 + 2}{(t^2 + 1)^{\frac{3}{2}}}$$

求 $\vec{r}(t)$ 表达式。

◎补充习题. 有一条平面弧长参数曲线 $\vec{r}(s)$,

$$k = \frac{1}{\sqrt{2s}},$$

求 $\vec{r}(s)$ 参数表达式.

2.2.14

方法一: 利用 $(\vec{t}, \vec{n}, \vec{b}) = <\vec{t} \wedge \vec{n}, \vec{b}> = 1$, 及Frenet标架的运动方程。

$$\frac{d^4 \vec{r}}{ds^4} = (-3\dot{k}k)\vec{t} + (\ddot{k} - k^3 - k\tau^2)\vec{n} + (2\dot{k}\tau + k\dot{\tau})\vec{b}$$

方法二: 对于第二问, 将本节12题的 $\tilde{k}, \tilde{\tau}$, 代入本题第一问, 并注意参数的选取。

◎补充习题. 计算:

$$\left(\frac{d\vec{b}}{ds}, \frac{d^2\vec{b}}{ds^2}, \frac{d^3\vec{b}}{ds^3} \right)$$

2.2.15

如 \vec{r} 为球面曲线，则 \vec{r} 的法平面过定点(参考本节第9题补充习题)，可设存在 λ, μ , 使得

$$\begin{aligned}\vec{r} + \lambda \vec{n} + \mu \vec{b} &\equiv 0 \text{ 求导得 } \vec{t} + \lambda' \vec{n} + \lambda(-k\vec{t} + \tau \vec{b}) + \mu' \vec{b} + \mu(-\tau \vec{n}) = 0 \\ \Rightarrow \lambda k &= 1, \quad \lambda' = \mu \tau, \quad \lambda \tau + \mu' = 0 \\ \Rightarrow \vec{r} + \frac{1}{k} \vec{n} + \frac{1}{\tau} \frac{d}{ds} \left(\frac{1}{k} \right) \vec{b} &\text{为圆心}\end{aligned}$$

由此我们希望由条件 $\left(\frac{1}{k}\right)^2 + \left[\frac{1}{\tau} \frac{d}{ds} \left(\frac{1}{k}\right)\right]^2$ 可以推出 $\vec{r} + \frac{1}{k} \vec{n} + \frac{1}{\tau} \frac{d}{ds} \left(\frac{1}{k}\right) \vec{b}$ 为常值

$$\begin{aligned}0 &= \frac{d}{ds} \left[\left(\frac{1}{k} \right)^2 + \left(\frac{1}{\tau} \frac{d}{ds} \left(\frac{1}{k} \right) \right)^2 \right] \\ &= \frac{2}{k} \left(\frac{1}{k} \right)' + \frac{2}{\tau} \left(\frac{1}{k} \right)' \left(\frac{1}{\tau} \left(\frac{1}{k} \right)' \right)' \\ &= \frac{2}{\tau} \left(\frac{1}{k} \right)' \left[\frac{\tau}{k} + \left(\frac{1}{\tau} \left(\frac{1}{k} \right)' \right)' \right] \\ \frac{d}{ds} \left[\vec{r} + \frac{1}{k} \vec{n} + \frac{1}{\tau} \frac{d}{ds} \left(\frac{1}{k} \right) \vec{b} \right] &= \left[\left(\frac{1}{\tau} \left(\frac{1}{k} \right)' \right)' + \frac{\tau}{k} \right] \vec{b}\end{aligned}$$

所以如果 k 不是常值，则 $\vec{r} + \frac{1}{k} \vec{n} + \frac{1}{\tau} \frac{d}{ds} \left(\frac{1}{k}\right) \vec{b}$ 为常值。

2.2.16

设 P_0 为原点， l 为 z 轴，则在 P_0 点附近，可设曲线为：

$$\begin{aligned}\vec{r}(t) &= (x(t), y(t), t), \quad x(0) = y(0) = x'(0) = y'(0) = 0 \\ x(t) &= x''(0) \frac{t^2}{2} + O(t^3), \quad y(t) = y''(0) \frac{t^2}{2} + O(t^3)\end{aligned}$$

计算得

$$k(0) = \left| \frac{d^2 \vec{r}}{dt^2} \right| (0) = \left| \frac{(x'', y'', 0)}{\sqrt{x''^2 + y''^2 + 1}} \right| (0) = \sqrt{x''(0)^2 + y''(0)^2}$$

设 $P = \vec{r}(t)$, 则

$$\begin{aligned}\lim_{P \rightarrow P_0} \frac{2d(P, l)}{d^2(P_0, P)} &= \lim_{t \rightarrow 0} \frac{2\sqrt{x^2(t) + y^2(t)}}{x^2(t) + y^2(t) + t^2} = \lim_{t \rightarrow 0} \frac{\sqrt{x''(0)^2 t^4 + y''(0)^2 t^4 + O(t^5)}}{t^2 + O(t^3)} \\ &= \sqrt{x''(0)^2 + y''(0)^2} = k(0)\end{aligned}$$

◎补充习题. 仍用本题的记号，设 L 是 P_0 点处曲线 C 的切向与主法向张成的平面。证明：

$$\lim_{P \rightarrow P_0} \frac{3d(P, L)}{d(P, l)d(P, P_0)} = \tau(P_0)$$

②补充习题. 证明:通过平移旋转,一条正则曲线可局部表示为

$$\vec{r}(t) = (t, \frac{k}{2}t^2 + O(t^3), \frac{k\tau}{6}t^3 + O(t^4))$$

2.2.17

方法一: 将 $\tau = c\kappa (\kappa \neq 0)$ 代入本节12题, 得 $\tilde{k} = \sqrt{1+c^2}$, $\tilde{\tau} = 0$, 故 $\vec{t}(s)$ 是一个圆, $\vec{b}(s)$ 是常向量(但注意此时 s 不是 $\tilde{r}(s) = \vec{t}(s)$ 的弧长参数)。

由此任给某圆的一个参数化 $\vec{a}(t)$,

$$\int_0^s \vec{a}(t) dt \triangleq \vec{r}(s)$$

为满足条件的曲线。

方法2:

$$\frac{d}{ds} \begin{pmatrix} \vec{t} \\ \vec{n} \\ \vec{b} \end{pmatrix} = \begin{pmatrix} k & & \\ -k & \tau & \\ & -\tau & \end{pmatrix} \begin{pmatrix} \vec{t} \\ \vec{n} \\ \vec{b} \end{pmatrix} = k \begin{pmatrix} 1 & & \\ -1 & c & \\ & -c & \end{pmatrix} \begin{pmatrix} \vec{t} \\ \vec{n} \\ \vec{b} \end{pmatrix}$$

$$\begin{pmatrix} 1 & & \\ -1 & c & \\ & -c & \end{pmatrix} = O^T \begin{pmatrix} & & \sqrt{c^2+1} \\ & -\sqrt{c^2+1} & \end{pmatrix} O$$

$$\text{上式中, } O = \begin{pmatrix} \frac{c}{\sqrt{c^2+1}} & & \frac{1}{\sqrt{c^2+1}} \\ -\frac{1}{\sqrt{c^2+1}} & 1 & \frac{c}{\sqrt{c^2+1}} \end{pmatrix}, O^T O = O O^T = I$$

$$\text{故 } \frac{d}{ds} O \begin{pmatrix} \vec{t} \\ \vec{n} \\ \vec{b} \end{pmatrix} = k \begin{pmatrix} & & \sqrt{c^2+1} \\ & -\sqrt{c^2+1} & \end{pmatrix} O \begin{pmatrix} \vec{t} \\ \vec{n} \\ \vec{b} \end{pmatrix}$$

$$\text{由此得 } \frac{d}{ds} \begin{pmatrix} c\vec{t} + \vec{b} \\ \sqrt{c^2+1} \end{pmatrix} = 0,$$

$$\frac{d}{ds} \vec{n} = k\sqrt{c^2+1} \begin{pmatrix} -c\vec{t} + \vec{b} \\ \sqrt{c^2+1} \end{pmatrix},$$

$$\frac{d}{ds} \begin{pmatrix} -c\vec{t} + \vec{b} \\ \sqrt{c^2+1} \end{pmatrix} = -k\sqrt{c^2+1} \vec{n}$$

$$c\vec{t} + \vec{b} \equiv c\vec{t}(0) + \vec{b}(0)$$

$$\frac{-c\vec{t} + \vec{b}}{\sqrt{c^2+1}} = -\sin(\sqrt{c^2+1} \int k) \vec{n}(0) + \cos(\sqrt{c^2+1} \int k) \begin{pmatrix} -c\vec{t}(0) + \vec{b}(0) \\ \sqrt{c^2+1} \end{pmatrix}$$

$$\Rightarrow \vec{t} = \frac{1}{2c} \left(c\vec{t}(0) + \vec{b}(0) + \sqrt{c^2+1} \sin(\sqrt{c^2+1} \int_0^s k) \vec{n}(0) - \cos(\sqrt{c^2+1} \int_0^s k) (-c\vec{t}(0) + \vec{b}(0)) \right)$$

对 t 积分可得 \vec{r} 。

◎补充习题. 注意到在本节 15 题中, 若

$$\left(\frac{1}{k}\right)^2 + \left[\frac{1}{\tau} \frac{d}{ds} \left(\frac{1}{k}\right)\right]^2 = 1, \text{ 则 } \tau = \frac{\frac{d}{ds} \left(\frac{1}{k}\right)}{\sqrt{1 - \left(\frac{1}{k}\right)^2}}$$

$$\text{取 } k = \frac{1}{\sqrt{1 - a^2}}, \text{ 得到 } \tau = \frac{-a'}{\sqrt{1 - a^2}}, \frac{\tau}{k} = -a'$$

所以若 $a' = \text{const}$ 则 $\frac{\tau}{k}$ 为常数。如果取 $a = s$, 则

$$k = \frac{1}{\sqrt{1 - s^2}}, \tau = \frac{-1}{\sqrt{1 - s^2}}$$

请具体写出该曲线。

◎补充习题. 证明, 一条空间曲线若切向与固定方向成定角, 则该曲线满足 $\tau = ck$ 。证明, 反之亦然, 即若一条曲线满足 $\tau = ck$, 则该曲线的切向与某一固定方向成定角。提示利用上面的方法。

18* 注 参考本节第六题。

2.2.18

(1) 本书定义曲率时要求选定 \vec{n} 使得 $\{\vec{t}, \vec{n}\}$ 与 $\{\partial_x, \partial_y\}$ 定向相同, 即可通过旋转平移使 $\{\vec{t}, \vec{n}\}$ 与 $\{\partial_x, \partial_y\}$ 重合。

$$\tilde{k}(t) = -k(-t)$$

(2)

$$\tilde{k}(t) = k(-t), \tilde{\tau}(t) = \tau(-t)$$

2.2.19

$$\vec{v} = k\vec{b} + \tau\vec{t}$$

2.2.20

$\vec{r}(\frac{t}{2})$ 沿方向 $(\frac{1}{2}, 0, \frac{\sqrt{3}}{2})$ 跑向无穷远处, $\tilde{r}(t)$ 沿方向 $(0, 0, -1)$ 跑向无穷远处。为找到使两曲线重合的刚体运动, 我们先将 $\vec{r}(\frac{t}{2})$ 绕 y 轴旋转使 $\vec{r}(\frac{t}{2}), \tilde{r}(t)$ 以相同速度跑向无穷远处。

$$\vec{r}(\frac{t}{2}) \begin{pmatrix} -\frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & -\frac{\sqrt{3}}{2} \end{pmatrix} = (-2 \sin \frac{t}{2}, 2 \cos \frac{t}{2}, -t)$$

然后再将 $(-2 \sin \frac{t}{2}, 2 \cos \frac{t}{2}, -t)$ 绕 z 轴旋转, 可使其与 $\tilde{r}(t)$ 重合。

2.2.21

◎补充习题. 给定 k, τ 为 x, y, z, s 的光滑函数。证明, 存在空间曲线 $\vec{r}(s) : R \rightarrow R^3 = \{(x, y, z)\}$, 使得 $k = k(\vec{r}(s), s), \tau = \tau(\vec{r}(s), s)$