## RIEMANNIAN GEOMETRY EXCERCISE 5

1. Recall the Koszul formula states that: for any  $X, Y, Z \in \Gamma(TM)$ , we have

$$\begin{split} 2\langle \nabla_X Y, Z \rangle = & X\langle Y, Z \rangle + Y\langle Z, X \rangle - Z\langle X, Y \rangle \\ & - \langle X, [Y, Z] \rangle + \langle Y, [Z, X] \rangle + \langle Z, [X, Y] \rangle \end{split}$$

Suppose we know the following fact: There exist three vector files  $\mathbf{i}, \mathbf{j}, \mathbf{k}$  on  $\mathbb{S}^3 \subset \mathbb{R}^4$  which are linearly independent at any point of  $\mathbb{S}^3$ , such that

$$[\mathbf{i},\mathbf{j}] = \mathbf{k}, \ [\mathbf{j},\mathbf{k}] = \mathbf{i}, \ [\mathbf{k},\mathbf{i}] = \mathbf{j}.$$

Assign to  $\mathbb{S}^3$  a Riemmannian metric g such that  $\mathbf{i}, \mathbf{j}, \mathbf{k}$  are orthonormal at any point. Calculate the Levi-Civita connection  $\nabla$  of  $(\mathbb{S}^3, g)$ .

2. (Isometries preserve Levi-Civita connections) Let  $(M_1, g_1)$ ,  $(M_2, g_2)$  be two Riemannian manifolds. Let  $\nabla^{(1)}$ ,  $\nabla^{(2)}$  be their Levi-Civita connections, respectively. Suppose  $\varphi : M_1 \to M_2$  be an isometry. Prove that for any  $X, Y \in \Gamma(TM_1)$ , we have

$$d\varphi\left(\nabla_X^{(1)}Y\right) = \nabla_{d\varphi(X)}^{(2)}d\varphi(Y).$$

3. (Induced connection) Let M,N be two smooth manifold and  $\varphi:N\to M$  be a smooth map. A vector field along  $\varphi$  is an assignment

$$x \in N \mapsto T_{\varphi(x)}M.$$

Let  $\{E_i\}_{i=1}^n$  be a frame field in a neighborhood U of  $\varphi(x) \in M$ . Then for any  $y \in \varphi^{-1}(U)$ , we have

$$V(x) = V^{i}(x)E_{i}(\varphi(x)).$$

Let  $u \in T_x N$ . We define

(0.1) 
$$\widetilde{\nabla}_u V := u(V^i)(x)E_i(\varphi(x)) + V^i(x)\nabla_{d\varphi(u)}E_i$$

where  $\nabla$  is an affine connection on M.

- (i) Check that  $\widetilde{\nabla}_u V$  is well defined, i.e., (0.1) is independent of the choices of  $\{E_i\}$ .
- (ii) Let g be a Riemannian metric on M. Prove that if  $\nabla$  on M is compatible with g, then for vector fields V, W along  $\varphi$ , and  $u \in T_x N$ , we have

$$u\langle V,W\rangle = \langle \widetilde{\nabla}_u V,W\rangle + \langle V,\widetilde{\nabla}_u W\rangle.$$

(iii) Prove that if  $\nabla$  on M is torsion free, then for any  $X, Y \in \Gamma(TN)$ , we have

$$\widetilde{\nabla}_X d\varphi(Y) - \widetilde{\nabla}_Y d\varphi(X) - d\varphi\left([X, y]\right) = 0.$$

4. (Variation of energy functional: A coordinate-free calculation) Let  $\gamma : [a, b] \to M$  be a smooth curve, and

$$\alpha: (-\epsilon, \epsilon) \times [a, b] \to M, \ (s, t) \mapsto \alpha(s, t).$$

be a variation, where (M,g) is a Riemmanian manifold with a Levi-Civita connection.

Recall the energy functional of a curve  $\gamma$  is

$$E(\gamma) := \frac{1}{2} \int_{a}^{b} \left\langle d\gamma \left( \frac{\partial}{\partial t} \right), d\gamma \left( \frac{\partial}{\partial t} \right) \right\rangle dt.$$

For convenience, we denote by

$$W(t) := d\alpha \left(\frac{\partial}{\partial s}\right) (0, t), \text{ and } \dot{\gamma}(t) := d\gamma \left(\frac{\partial}{\partial t}\right).$$

Prove the following variation formula:

$$\frac{d}{ds}_{|_{s=0}} E(\bar{\alpha}(s)) = -\int_{a}^{b} \left\langle W(t), \frac{D\dot{\gamma}}{dt}(t) \right\rangle dt - \left\langle W(a), \frac{D\dot{\gamma}}{dt}(a) \right\rangle + \left\langle W(b), \frac{D\dot{\gamma}}{dt}(b) \right\rangle,$$
  
where  $\bar{\alpha}(s) := \alpha(s, \cdot) : t \mapsto \alpha(s, t).$ 

5. Let  $S^n$  be the sphere with the induced metric g from the Euclidean metric in  $\mathbb{R}^{n+1}$ . We denote by  $\overline{\nabla}$  the canonical Levi-Civita connection on  $\mathbb{R}^{n+1}$ . For any  $X, Y \in \Gamma(T\mathbb{S}^n)$ , one can extend X, Y to smooth vector field  $\overline{X}, \overline{Y}$  on  $\mathbb{R}^{n+1}$ , at least near  $\mathbb{S}^n$ .

By locality, the vector  $\overline{\nabla}_{\overline{X}}\overline{Y}$  at any  $p \in \mathbb{S}^n$  depends only on  $\overline{X}(p) = X(p)$  and the vectors  $\overline{Y}(q) = Y(q)$  for  $q \in \mathbb{S}^n$ . That is,  $\overline{\nabla}_{\overline{X}}\overline{Y}$  is independent of the extension of X, Y we choose. So we will write  $\overline{\nabla}_X Y$  instead of  $\overline{\nabla}_{\overline{X}}\overline{Y}$  at points on  $\mathbb{S}^n$ . We define  $\nabla_X Y$  to be the orthogonal projection of  $\overline{\nabla}_X Y$  onto the tangent space

of  $\mathbb{S}^n$ , i.e.,

$$\nabla_X Y := \overline{\nabla}_X Y - \langle \overline{\nabla}_X Y, \mathbf{n} \rangle \mathbf{n},$$

where **n** is the unit out normal vector on  $\mathbb{S}^n$ .

- (i) Prove that  $\nabla$  is an affine connection on  $\mathbb{S}^n$ .
- (ii) Prove that  $\nabla$  is the Levi-Civita connection of  $(\mathbb{S}^n, g)$ .