

Proof of $\gamma_{\lambda v}(t) = \gamma_v(\lambda t)$.

Denote by $h(t) = \gamma_v(\lambda t) = (y^1(t), \dots, y^n(t))$, where

$$y^i(t) = x^i(\lambda t).$$

We check $\ddot{y}^i(t) + \Gamma_{jk}^i(y(t)) \dot{y}^j(t) \dot{y}^k(t) = 0$

$$= \lambda^2 \ddot{x}^i(\lambda t) + \lambda^2 \Gamma_{jk}^i(x(\lambda t)) \dot{x}^j(\lambda t) \dot{x}^k(\lambda t) = 0$$

That is h is also a geodesic. Moreover

$$h(0) = \gamma_v(0) = q, \quad \dot{h}(0) = \lambda v.$$

By the uniqueness of geodesics,

$$h(t) = \gamma_{\lambda v}(t).$$

Lemma (Homogeneity of a geodesic, [doC, Lemma 2.6 §3.2])

If the geodesic $\gamma(t, q, v)$ is defined on the interval $t \in (-\varepsilon, \varepsilon)$,

then the geodesic $\gamma(t, q, \lambda v)$, $\lambda \in \mathbb{R}$, $\lambda > 0$, is defined on

the interval $t \in \left(-\frac{\varepsilon}{\lambda}, \frac{\varepsilon}{\lambda}\right)$ and

$$\gamma(t, q, \lambda v) = \gamma(\lambda t, q, v)$$