

第十三讲

2020年4月7日 9:36

$c: I \rightarrow M$   $C^\infty$  curve  $t \mapsto c(t), t \in I$ .

Vector field along  $c: t \mapsto V(t) \in T_{c(t)}M, t \in I$

Smooth. Covariant derivative of  $V(t)$  along  $c$ .

$$\frac{DV}{dt}$$

Chart  $(U, x)$   $V = V^i(x) \frac{\partial}{\partial x^i}$

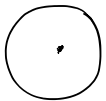
Case 1:  $V \in \Gamma(TM)$   $V|_c$

$$\begin{aligned} \nabla_{dc(\frac{d}{dt})} V(c(t)) &= \nabla_{dc(\frac{d}{dt})} \left( V^i(x) \frac{\partial}{\partial x^i} \right) (c(t)) \\ &= \underbrace{dc(\frac{d}{dt})(V^i)}(c(t)) \frac{\partial}{\partial x^i}(c(t)) + V^i(c(t)) \cdot \nabla_{dc(\frac{d}{dt})} \frac{\partial}{\partial x^i}(c(t)) \\ &= \frac{dV^i(c(t))}{dt} \frac{\partial}{\partial x^i}(c(t)) + V^i(c(t)) \nabla_{dc(\frac{d}{dt})} \frac{\partial}{\partial x^i}(c(t)) \end{aligned}$$

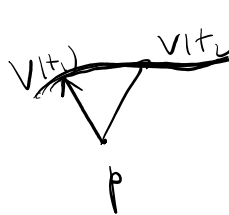
Case 2:  $V(t)$  a vector field along  $c$ .

$$V(t) = V^i(t) \frac{\partial}{\partial x^i}(c(t))$$

$$\boxed{\frac{DV}{dt} = \frac{dV^i(t)}{dt} \frac{\partial}{\partial x^i}(c(t)) + V^i(t) \nabla_{dc(\frac{d}{dt})} \frac{\partial}{\partial x^i}(c(t))}$$

Remark:   $c: I \rightarrow M$   $t \mapsto p$   $C^\infty$  curve

A vector field  $V(t)$  along  $c$ :

$$V(t) = V^i(t) \frac{\partial}{\partial x^i}(c(t)) = V^i(t) \frac{\partial}{\partial x^i}(p)$$


$$V(t) = (V^1(t), \dots, V^n(t)) \in T_p M$$

$$\frac{DV}{dt} = \frac{dV^i(t)}{dt} \frac{\partial}{\partial x^i}(p) + V^i(t) \left( \nabla_{dc(\frac{d}{dt})} \frac{\partial}{\partial x^i} \right) (p)$$



$$\sum_{k=1}^n \frac{dv^k}{dt} + v^j \frac{dc^i}{dt} \{ij\}^k \quad \left. \right\} \frac{d}{dt} X^k(c(t))$$

$$\Leftrightarrow \begin{cases} \frac{dv^k}{dt} + \sum_{i,j=1}^n v^j \frac{dc^i}{dt} \{ij\}^k = 0, & k=1, \dots, n \\ v^k(t_0) = v_0^k \end{cases} \quad (v^1, \dots, v^n)$$

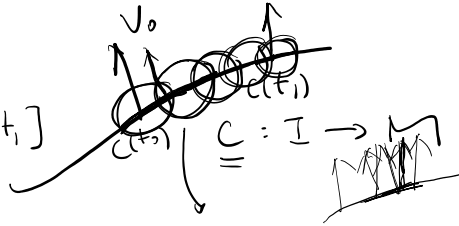
ODE theory:  $\Rightarrow \exists!$  solution on  $I$ .



$$c|_I \subset (u, x)$$

claim: parallel

$\forall t_1 \in I, \exists! V(t), t \in [t_0, t_1]$   
s.t.  $V(t_0) = V_0$

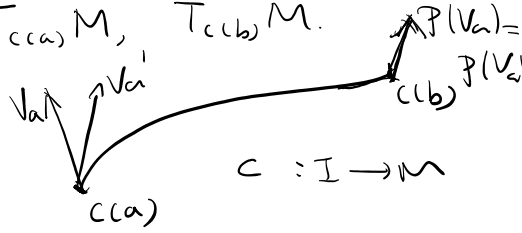


$[t_0, t_1]$  compact,  $c([t_0, t_1])$  compact in  $M$   
 $\Rightarrow$  finite covering of  $c([t_0, t_1])$  via charts.

Consider the tangent spaces  $T_{c(a)}M, T_{c(b)}M$ .

$$\mathcal{P}_{c,a,b} = \mathcal{P}: T_{c(a)}M \rightarrow T_{c(b)}M$$

$$V_a \mapsto \mathcal{P}(V_a)$$



parallel transportation eq. is linear  $\Rightarrow$

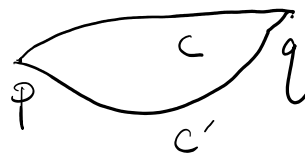
$$\begin{cases} \mathcal{P}(V_a + W_a) = \mathcal{P}(V_a) + \mathcal{P}(W_a) \\ \mathcal{P}(\lambda V_a) = \lambda \mathcal{P}(V_a) \end{cases} \quad \text{linear map}$$

$\bullet$   $\mathcal{P}$  is injective.  $V_a \neq V_a' \Rightarrow \mathcal{P}(V_a) \neq \mathcal{P}(V_a')$   
parallel transportation equation is unique

$T_{c(a)}M, T_{c(b)}M$  have the same dimension.

$\Rightarrow \mathcal{P}$  is a linear isomorphism between  $T_{c(a)}M, T_{c(b)}M$ .

$\nabla$  "connection".



$$X, Y \in \Gamma(TM), \nabla_X Y \in \Gamma(TM)$$

$\uparrow \mathcal{P}(c'(t))$

$$X, Y \in \Gamma(TM), \nabla_X Y \in \Gamma(TM) \quad \text{--- } c'$$

Proposition:  $\nabla_X Y(p) = \nabla_{X_p} Y(p)$

Let  $c$  be a  $C^\infty$  curve with  $c(0) = p$ ,  $\dot{c}(0) = X_p$ .

Then.  $\nabla_X Y(p) = \nabla_{X_p} Y = \lim_{h \rightarrow 0} \frac{1}{h} \underbrace{(\mathcal{P}_{c,0,h}^{-1})}_{c,0,h} (Y(c(h)) - \underbrace{Y(c(0))}_p)$

Proof:  $T_p M$   $\{E_i(0), i=1, \dots, n\}$   $\in T_p M$   $T_p M$   
 a basis

define  $E_i(t) := \mathcal{P}_{c,0,t}(E_i(0))$ ,  $i=1, \dots, n$

s.t.  $\{E_i(t), i=1, \dots, n\}$  is a basis of  $T_{c(t)}M$ ,  $\forall t \in I$ .

$Y(c(t)) = \sum_{i=1}^n f_i(t) E_i(t)$  frame field.

$$\begin{aligned} & \lim_{h \rightarrow 0} \frac{1}{h} (\mathcal{P}_{c,0,h})^{-1} (Y(c(h)) - Y(p)) \\ &= \lim_{h \rightarrow 0} \frac{1}{h} (\mathcal{P}_{c,0,h})^{-1} \left( \sum_i f_i(h) E_i(h) - \sum_i f_i(0) E_i(0) \right) \\ &= \lim_{h \rightarrow 0} \frac{1}{h} \left( \sum_i f_i(h) \underbrace{(\mathcal{P}_{c,0,h})^{-1}(E_i(h))}_{E_i(0)} - \sum_i f_i(0) E_i(0) \right) \end{aligned}$$

$$= \sum_i \left( \lim_{h \rightarrow 0} \frac{1}{h} (f_i(h) - f_i(0)) \right) E_i(0) = \sum_i \frac{df_i}{dt} \Big|_{t=0} E_i(0)$$

$$= \frac{D}{dt} \Big|_{t=0} \sum_i f_i(t) E_i(t) = \frac{DY}{dt} = \nabla_{X_p} Y = \nabla_{d(c/dt)} Y$$

休区 3/10:45

$M, (U, \alpha), f: M \rightarrow \mathbb{R}$

$$\left( \frac{\partial f}{\partial x^i} \right) \leftrightarrow \sum_i \frac{\partial f}{\partial x^i} dx^i = df$$

$\underbrace{\quad \quad \quad}_{\text{...}} \underbrace{\quad \quad \quad}_{\text{...}}$

$$V = v^i \frac{\partial}{\partial x^i}$$

$$\left( \frac{\partial v^i}{\partial x^j} + v^k \Gamma_{ij}^k \right)$$

$$\nabla_{\frac{\partial}{\partial x^i}} V = \nabla_{\frac{\partial}{\partial x^i}} \left( v^j \frac{\partial}{\partial x^j} \right) = \frac{\partial v^j}{\partial x^i} \frac{\partial}{\partial x^j} + v^j \left\{ \begin{matrix} k \\ ij \end{matrix} \right\} \frac{\partial}{\partial x^k}$$

$$= \left( \frac{\partial v^k}{\partial x^j} + v^i \left\{ \begin{matrix} k \\ ij \end{matrix} \right\} \right) \frac{\partial}{\partial x^k}$$

Koszul

### §3. Covariant derivative of a tensor field.

$$Y \in \Gamma(TM), \quad X \quad (1,0)\text{-tensor} \quad \nabla_Y X$$

$$f: M \rightarrow \mathbb{R} \quad (0,0)\text{-tensor} \quad \nabla_Y f := Y(f) = \underline{df(Y)}$$

A.  $(r,s)$ -tensor field  $X \in \Gamma(TM), \nabla_X A?$

Proposition:  $(M, \nabla)$  affine connection over vector field

There exists a unique connection on all tensorfields:  
for any  $r, s \in \mathbb{Z}_{\geq 0}$

$$\nabla: \Gamma(TM) \times \Gamma(\otimes^{r,s} TM) \rightarrow \Gamma(\otimes^{r,s} TM)$$

such that  $(X, A) \mapsto \nabla(X, A) := \nabla_X A$

~~(i)  $\nabla_{fX+gY} A = f \nabla_X A + g \nabla_Y A$  (tensorial)~~

(ii)  $\nabla_X (A_1 + A_2) = \nabla_X A_1 + \nabla_X A_2$  ( $\mathbb{R}$ -linear)

(iii)  $\nabla_X (fA) = X(f) \nabla_X A + f \nabla_X A$  (Leibniz rule)  $fA = f \otimes A$

and

(iv)  $\nabla$  coincide with the given connections on  $\Gamma(TM)$  and  $\Gamma^*(M)$

(v)  $\nabla_X (T_1 \otimes T_2) = \nabla_X T_1 \otimes T_2 + T_1 \otimes \nabla_X T_2$

(vi)  $C(\nabla_X T) = \nabla_X (CT)$ , where

(vi)  $C(\nabla_X T) = \nabla_X(CT)$ , where  
 $C: \Gamma(\otimes^{r,s} TM) \rightarrow \Gamma(\otimes^{r-1,s+1} TM)$

Remark:  $V_1, \dots, V_n, \omega^1, \dots, \omega^n$

$$A = \sum A_{j_1 \dots j_s}^{i_1 \dots i_r} \underbrace{V_{i_1} \otimes \dots \otimes V_{i_r}}_{\text{circled}} \otimes \dots \otimes \underbrace{\omega^{j_1}}_{\text{circled}} \otimes \dots \otimes \omega^{j_s}$$

$$CA = \sum A_{j_1 \dots j_s}^{i_1 \dots i_r} \omega^{j_1}(V_{i_1}) \underbrace{V_{i_1} \otimes \dots \otimes V_{i_r}}_{\text{circled}} \otimes \underbrace{\omega^{j_2} \otimes \dots \otimes \omega^{j_s}}_{\text{circled}}$$

Proof:  $\nabla_X A$  Suppose  $\nabla$  exists.

$$\nabla_X A_{j_1 \dots j_s}^{i_1 \dots i_r}, \quad \nabla_X V_{i_1}, \quad \nabla_X \omega^{j_1}$$

?  $\nabla_X \omega$ , for  $\omega \in \Omega^1(M) = \Gamma(T^*M)$

$\forall Y \in \Gamma(TM), (\nabla_X \omega)(Y) = ?$ ,  $\forall Y \in \Gamma(TM)$

$\omega(Y) \in C^\infty(M)$

$$\nabla_X(\omega(Y)) = X(\omega(Y)) = \nabla_X(C(Y \otimes \omega))$$

$$\stackrel{(vi)}{=} C(\nabla_X(Y \otimes \omega)) \stackrel{(vi)}{=} C(\nabla_X Y \otimes \omega + Y \otimes \nabla_X \omega)$$

$$= \underbrace{\omega(\nabla_X Y)} + \underbrace{(\nabla_X \omega)(Y)}$$

$$\Rightarrow \boxed{(\nabla_X \omega)(Y) = X(\omega(Y)) - \omega(\nabla_X Y)}$$

$\Rightarrow$  uniqueness

Existence:  $\nabla_X f, \nabla_X V, \nabla_X \omega$  def

$$\Rightarrow \nabla_X A \stackrel{\text{def}}{=} \text{[ ]}$$

Exercise.  $\square$

Remark (1)  $\nabla_X f, \nabla_X V, \nabla_X \omega$

Claim:  $\nabla_{fX+gY} w = f \nabla_X w + g \nabla_Y w$   
 $\forall f, g \in C^\infty(M), X, Y \in \Gamma(TM)$ .

Proof:  $\forall Z \in \Gamma(TM)$ ,

$$\begin{aligned} (fX+gY)(w(Z)) &= \nabla_{fX+gY} w(Z) \\ &= \underbrace{(\nabla_{fX+gY} w)(Z)} + \underbrace{w(\nabla_{fX+gY} Z)} \\ &= \underbrace{f X(w(Z)) + g Y(w(Z))}_{f \nabla_X w + g \nabla_Y w} + \underbrace{f w(\nabla_X Z) + g w(\nabla_Y Z)}_{w(f \nabla_X Z + g \nabla_Y Z)} \\ &= (f \nabla_X w + g \nabla_Y w)(Z) + w(\nabla_{fX+gY} Z) \end{aligned}$$

Remark: (locality)

$$\nabla_X A(p)$$

$$\nabla_X A(p) = \nabla_{X_p} A$$



$$\nabla_{1+X} A = \nabla_X (1+A)$$

In a chart  $(U, x)$   $X = X^i \frac{\partial}{\partial x^i}$ ,  $A = w = w_i dx^i$

$$\begin{aligned} \left( \nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^j} \right) \left( \nabla_{\frac{\partial}{\partial x^i}} dx^j \right) \left( \frac{\partial}{\partial x^k} \right) \\ \left\{ \begin{matrix} k \\ i, j \end{matrix} \right\} \frac{\partial}{\partial x^k} &= \frac{\partial}{\partial x^i} \left( dx^j \left( \frac{\partial}{\partial x^k} \right) \right) - dx^j \left( \nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^k} \right) \\ &= 0 - dx^j \left( \left\{ \begin{matrix} k \\ i, k \end{matrix} \right\} \frac{\partial}{\partial x^i} \right) \end{aligned}$$

$$= \{ \delta_{ik} \} dx^j$$

$$= - \left\{ \begin{matrix} l \\ ik \end{matrix} \right\} \delta_{lj} = - \left\{ \begin{matrix} j \\ ik \end{matrix} \right\}$$

$$\Rightarrow \boxed{\nabla_{\partial_i} dx^j = - \left\{ \begin{matrix} j \\ ik \end{matrix} \right\} dx^k}$$

Given  $n^3$   $C^\infty$  fct.  $\left\{ \begin{matrix} i \\ jk \end{matrix} \right\} \Rightarrow \nabla_x A$   
in local.

休息到 11:40

Parallel transportation

$V, W$  two vector spaces

$f: V \rightarrow W$  isomorphism

$\Rightarrow$  ~~induced~~ induces an isomorphism

$$f^*: W^* \rightarrow V^*$$

$$\alpha \mapsto f^*(\alpha), \text{ where } \forall v \in V, f^*(\alpha)(v) := \alpha(f(v))$$

$$\tilde{f} (v_1 \otimes \dots \otimes v_r \otimes \alpha' \otimes \dots \otimes \alpha^r)$$

$$= f(v_1) \otimes \dots \otimes f(v_r) \otimes (f^*)^{-1}(\alpha') \otimes \dots \otimes (f^*)^{-1}(\alpha^r)$$

$$\Rightarrow \tilde{f}: \otimes^{r,s} V \rightarrow \otimes^{r,s} W \text{ linear isomorphism}$$

$$\tilde{P}_{c,a,b}: \otimes^{r,s} T_{c(a)} M \rightarrow \otimes^{r,s} T_{c(b)} M$$

Define  $\nabla_x A \in T(\otimes^{r,s} TM)$

$$\text{s.t. } \nabla_x A(p) := \nabla_{x_p} A := \lim_{h \rightarrow 0} \frac{1}{h} (\tilde{P}_{c,0,h}^{-1}(A(c(h))) - A)$$

where  $c$  is a  $C^\infty$  curve with  $c(0) = p, \dot{c}(0) = X_p$

Verify that  $\nabla_x A$  satisfies all the properties



$$T_{c(0)}M = T_pM \quad \text{a basis } \{E_i(0)\}_{i=1}^n$$

Define  $E_i(h) := \mathcal{P}_{c,0,h}(E_i(0))$  a frame field

Let  $\{w^i(0)\}_{i=1}^n$  is a basis of  $T_p^*M$

Define  $w^i(h) := (\mathcal{P}_{c,0,h}^*)^{-1}(w^i(0)), i=1, \dots, n$

Claim:  $w^i(h)(E_j(h)) = \delta_j^i, \forall h, \forall i, j$

Proof:  $\mathcal{P}_{c,0,h}^* : T_{c(h)}^*M \rightarrow T_{c(0)}^*M$   
 $w^i(h) \mapsto \mathcal{P}_{c,0,h}^*(w^i(h))$

$\forall v(0) \in T_{c(0)}M$ , we have by def.

$$\mathcal{P}_{c,0,h}^*(w^i(h))(v(0)) := w^i(h)(\mathcal{P}_{c,0,h}(v(0)))$$

$$\begin{aligned} w^i(h)(E_j(h)) &= w^i(h)(\mathcal{P}_{c,0,h}(E_j(0))) \\ &= \mathcal{P}_{c,0,h}^*(w^i(h))(E_j(0)) \\ &= w^i(0)(E_j(0)) = \delta_j^i. \quad \square \end{aligned}$$

$$\begin{cases} V(h) = \sum_{i=1}^n f^i(h) \underline{E_i(h)} \\ \omega(h) = \sum_{j=1}^n g_j^\theta(h) \underline{\omega_j^s(h)} \end{cases} \text{parallel.}$$

$$\underline{\nabla_x A.} \quad \boxed{\nabla_x (V \otimes \omega) = \nabla_x V \otimes \omega + V \otimes \nabla_x \omega}$$

$$\Rightarrow \frac{d}{dh} (f^i(h) g_j(h)) = \frac{df^i}{dh} g_j + f^i \frac{dg_j}{dh}$$

$$\nabla_x C(V \otimes \omega) \neq C(\nabla_x (V \otimes \omega))$$

Exercise

$\eta \in \Omega^1(M), \forall Y \in T(TM)$

$$(\nabla_{x_p} \eta)(Y) = \eta(\nabla_{x_p} Y) - \nabla_{x_p}(\eta(Y)) \quad \square$$

§4. Levi-Civita (Riemannian) connection

$$\underline{x(t) = (x^1(t), \dots, x^n(t)) \quad \text{geodesic}}$$

$$\underline{\ddot{x}^i(t) + \Gamma_{jk}^i \dot{x}^j(t) \dot{x}^k(t) = 0, \quad i=1, \dots, n}$$

$$\dot{x}(t) = (\dot{x}^1(t), \dots, \dot{x}^n(t)) = \dot{x}^i(t) \frac{\partial}{\partial x^i}$$

$$\frac{D\dot{x}}{dt} = \frac{d}{dt} (\dot{x}^i(t) \frac{\partial}{\partial x^i}) + \dot{x}^i(t) \nabla_{\dot{x}} \frac{\partial}{\partial x^i}$$

$$= \ddot{x}^i(t) \frac{\partial}{\partial x^i} + \dot{x}^i(t) \dot{x}^j(t) \left\{ \begin{matrix} i \\ j \end{matrix} \right\} \frac{\partial}{\partial x^k}$$

$$= (\ddot{x}^k(t) + \dot{x}^i(t) \dot{x}^j(t) \left\{ \begin{matrix} k \\ j \end{matrix} \right\}) \frac{\partial}{\partial x^k}$$

If  $\left\{ \begin{matrix} k \\ j \end{matrix} \right\} = \Gamma_{ji}^k$ , then for a geodesic,  $\frac{D\dot{x}}{dt} = 0$

下课