

第十四讲

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Levi-Civita connection.

Hope: Find an affine connection ∇ on M , such that the geodesic equation can be reformulated as

$$\gamma = \gamma(t), \quad \boxed{\nabla_{\dot{\gamma}(t)} \dot{\gamma}(t) = 0} \quad \leftarrow$$

(local charts: (U, x) , Find an affine connection ∇ , s.t. ∇ is locally determined by Γ_{jk}^i , $i, j, k = 1, \dots, n$)

Rossual

Recall: $\gamma = \gamma(t)$ geodesic, $\boxed{g(\dot{\gamma}(t), \dot{\gamma}(t)) \equiv \text{const}}$, $\forall t$

$$0 \equiv \frac{d}{dt} \left(g(\dot{\gamma}(t), \dot{\gamma}(t)) \cdot \dot{\gamma}(t) \right) = \frac{d}{dt} \left(g(\dot{\gamma}(t), \dot{\gamma}(t)) \right) \cdot \dot{\gamma}(t) \\ \equiv \left(\nabla_{\dot{\gamma}(t)} g \right) (\dot{\gamma}(t), \dot{\gamma}(t)) + 2g \left(\nabla_{\dot{\gamma}(t)} \dot{\gamma}(t), \dot{\gamma}(t) \right)$$

If such an affine connection ∇ exists, then Hope find ∇ , s.t. 0

$$0 = \left(\nabla_{\dot{\gamma}(t)} g \right) (\dot{\gamma}(t), \dot{\gamma}(t))$$

Definition: We say ∇ is compatible with g , if the Ric. metric tensor g is parallel.

(Recall g parallel, $\nabla_X g = 0, \forall X \in \Gamma(TM)$)

If ∇ is compatible with g , then

$$X(g(Y, Z)) = g(\nabla_X Y, Z) + g(Y, \nabla_X Z)$$

Consider an affine connection ∇ , $\boxed{\nabla \text{ compatible with } g}$

Question: In a chart (U, x)

$$\nabla \leftrightarrow \left\{ \begin{matrix} i \\ jk \end{matrix} \right\} \quad \nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^j} := \left\{ \begin{matrix} k \\ ij \end{matrix} \right\} \frac{\partial}{\partial x^k}$$

$$\left\{ \begin{matrix} i \\ jk \end{matrix} \right\} \neq \Gamma_{jk}^i$$

$$\frac{\partial}{\partial x^k} g \left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right) = g_{ij,k}$$

$$= g \left(\nabla_{\frac{\partial}{\partial x^k}} \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right) + g \left(\frac{\partial}{\partial x^i}, \nabla_{\frac{\partial}{\partial x^k}} \frac{\partial}{\partial x^j} \right)$$

$$= 0 + g \left(\frac{\partial}{\partial x^i}, \left\{ \begin{matrix} l \\ ik \end{matrix} \right\} \frac{\partial}{\partial x^l} \right)$$

$$= g\left(\left\{\frac{\partial}{\partial x^i}\right\}, \left\{\frac{\partial}{\partial x^j}\right\}\right) + g\left(\left\{\frac{\partial}{\partial x^i}\right\}, \left\{\frac{\partial}{\partial x^k}\right\}\right)$$

$$= \left\{\frac{\partial}{\partial x^i}\right\} g_{ij} + \left\{\frac{\partial}{\partial x^j}\right\} g_{ik}$$

$$\Rightarrow \begin{cases} g_{ij,k} = g_{ij} \left\{\frac{\partial}{\partial x^k}\right\} + g_{ik} \left\{\frac{\partial}{\partial x^j}\right\} & (*) \\ g_{jk,i} = g_{jk} \left\{\frac{\partial}{\partial x^i}\right\} + g_{il} \left\{\frac{\partial}{\partial x^k}\right\} \\ g_{ki,j} = g_{ki} \left\{\frac{\partial}{\partial x^j}\right\} + g_{kj} \left\{\frac{\partial}{\partial x^i}\right\} \end{cases} \quad \Gamma_{jk}^i = \Gamma_{kj}^i$$

$$g_{ij,k} + g_{ki,i} - g_{ki,j} = g_{ij} \left(\left\{\frac{\partial}{\partial x^k}\right\} + \left\{\frac{\partial}{\partial x^i}\right\} \right) + g_{ik} \left(\left\{\frac{\partial}{\partial x^j}\right\} - \left\{\frac{\partial}{\partial x^k}\right\} \right) + g_{kj} \left(\left\{\frac{\partial}{\partial x^i}\right\} - \left\{\frac{\partial}{\partial x^j}\right\} \right)$$

• symmetric $\left\{\frac{\partial}{\partial x^j}\right\} = \left\{\frac{\partial}{\partial x^k}\right\}$

$$\Rightarrow \frac{1}{2} g^{pj} (g_{ij,k} + g_{jk,i} - g_{ki,j}) = 2 g_{ij} \left\{\frac{\partial}{\partial x^k}\right\} g^{jp}$$

$$\Rightarrow \left\{\frac{\partial}{\partial x^k}\right\} = \Gamma_{ki}^p$$

Restriction: ① $\nabla_X g = 0, \forall X \in \Gamma(TM)$

② $\left\{\frac{\partial}{\partial x^j}\right\} = \left\{\frac{\partial}{\partial x^k}\right\}$ symmetric

$$\nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^k} = \left\{\frac{\partial}{\partial x^i}\right\} \frac{\partial}{\partial x^i}$$

$$\nabla_{\frac{\partial}{\partial x^k}} \frac{\partial}{\partial x^j} = \left\{\frac{\partial}{\partial x^i}\right\} \frac{\partial}{\partial x^i}$$

$$\nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^k} = \nabla_{\frac{\partial}{\partial x^k}} \frac{\partial}{\partial x^j}$$

$(U, \alpha) \Rightarrow \forall X, Y$ v. f on U

$$\nabla_X Y = \nabla_Y X$$

$$D(X, Y) =: \nabla_X Y - \nabla_Y X \equiv 0 ?$$

$D(fX, Y) \neq f D(X, Y), \forall f \in C^\infty(M)$ not a tensor!

$$\nabla_{fX} Y - \nabla_Y (fX) = f \nabla_X Y + \underbrace{Y(f)X}_{\text{circled}} - f \nabla_Y X$$

Definition: Torsion tensor $T(X, Y) =: \nabla_X Y - \nabla_Y X - [X, Y], \forall X, Y \in \Gamma(TM).$

Definition. Torsion tensor $T(X, Y) := \nabla_X Y - \nabla_Y X - [X, Y]$,
 $\forall X, Y \in \Gamma(TM)$.

$$T \equiv 0. \quad \left[\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right] = 0$$

$$T(fX, Y) = f \nabla_X Y - \underline{Y(f)X} - f \nabla_Y X - [fX, Y].$$

$$\begin{aligned} [fX, Y]h &= fX(Y(h)) - Y(fX(h)) \\ &= f \cdot X(Y(h)) - Y(f)X(h) - f Y(X(h)), \forall h \end{aligned}$$

$$\Rightarrow [fX, Y] = f[X, Y] - \underline{Y(f)X}$$

$$\Rightarrow T(fX, Y) = fT(X, Y). \quad \square$$

Conclusion. ∇ affine connection s.t. Definition

(a) ∇ compatible with g

Levi-Civita connection
 (Christoffel connection)

(b) $T \equiv 0$ torsion-free

Existence? Uniqueness?

Define a connection:

$\forall X, Y \in \Gamma(TM), \nabla_X Y \in \Gamma(TM)$, s.t. $\forall p \in M, p \in U, (U, x)$ chart.

$$\nabla_X Y(p) := \left(X^i \frac{\partial Y^k}{\partial x^i} + X^i Y^j \Gamma_{ij}^k \right) \frac{\partial}{\partial x^k}$$

well-defined?



independent of choice of charts.

Exercise

transformation formula of Γ_{ij}^k

$$\Gamma_{jk}^i(x) = \tilde{\Gamma}_{\alpha\beta}^{\alpha} (y(x)) \frac{\partial y^{\alpha}}{\partial x^j} \frac{\partial y^{\beta}}{\partial x^k} \frac{\partial x^i}{\partial y^{\alpha}} + \frac{\partial^2 y^{\alpha}}{\partial x^j \partial x^k} \frac{\partial x^i}{\partial y^{\alpha}}$$

例 2:55.

What is an affine connection?

$\nabla \Leftrightarrow \{ \Gamma_{jk}^i \}$ n³ C^∞ -fit on each local chart (U, x)

which have the "correct" transformation behavior.

$$X = X^i \frac{\partial}{\partial x^i}$$

$$\frac{\partial X^i}{\partial x^k} + \Gamma_{hk}^i X^h$$

tensor

$$A_{i_1 \dots i_r}^{j_1 \dots j_s} \frac{\partial}{\partial x^{i_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{i_r}} \otimes dx^{j_1} \otimes \dots \otimes dx^{j_s}$$

$$A_{j_1 \dots j_s}^{i_1 \dots i_r} \frac{\partial}{\partial x^{i_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{i_r}} \otimes dx^{j_1} \otimes \dots \otimes dx^{j_s} \quad \text{tensor}$$

$$\frac{\partial (A_{j_1 \dots j_s}^{i_1 \dots i_r})}{\partial x^k} + \text{? } A_{j_1 \dots j_s}^{i_1 \dots i_r}$$

Thm (The fundamental theorem of Rie. geometry)

On any Rie. mfd (M, g) , $\exists!$ Levi-Civita connection.

- (M, g) Rie mfd
- metric \Rightarrow distance fun.
 - metric \Rightarrow Rie. measure
 - metric \Rightarrow Levi-Civita connection

Proof: $\int \nabla$ Assume existence, ∇

$$\forall X, Y \in \Gamma(TM) \quad \langle \nabla_X Y, Z \rangle = \underline{g(\nabla_X Y, Z)}$$

$$\forall Z \in \Gamma(TM)$$

$$\langle \nabla_X Y, Z \rangle \stackrel{\nabla g \equiv 0}{=} X \langle Y, Z \rangle - \langle Y, \nabla_X Z \rangle \quad \nabla_X Z = \nabla_Z X + [X, Z]$$

$$\stackrel{T \equiv 0}{=} X \langle Y, Z \rangle - \langle Y, \nabla_Z X + [X, Z] \rangle$$

$$= \underline{X \langle Y, Z \rangle} - \underline{\langle Y, [X, Z] \rangle} - \underline{\langle Y, \nabla_Z X \rangle}$$

$$= X \langle Y, Z \rangle - \langle Y, [X, Z] \rangle - (Z \langle Y, X \rangle - \langle \nabla_Z Y, X \rangle)$$

$$= X \langle Y, Z \rangle - \langle Y, [X, Z] \rangle - Z \langle Y, X \rangle + \langle \nabla_Z Y, X \rangle$$

$$= X \langle Y, Z \rangle - Z \langle Y, X \rangle - \langle Y, [X, Z] \rangle + \langle [Z, Y], X \rangle$$

$$+ Y \langle Z, X \rangle - \langle Z, \nabla_Y X \rangle$$

$$= X \langle Y, Z \rangle + Y \langle Z, X \rangle - Z \langle X, Y \rangle$$

$$+ \langle [Z, Y], X \rangle - \langle Y, [X, Z] \rangle - \langle Z, [Y, X] \rangle$$

$$- \langle Z, \nabla_Y X \rangle$$

Koszul formula

$$\Rightarrow \boxed{2 \langle \nabla_X Y, Z \rangle = X \langle Y, Z \rangle + Y \langle Z, X \rangle - Z \langle X, Y \rangle - \langle X, [Y, Z] \rangle + \langle Y, [Z, X] \rangle + \langle Z, [X, Y] \rangle} \quad (*)$$

\Rightarrow uniqueness.

$\forall X, Y, Z \in \Gamma(TM)$

⇒ uniqueness.

Existence. define the connection via \otimes . □

$$X = \frac{\partial}{\partial x^i}, \quad Y = \frac{\partial}{\partial x^j}, \quad Z = \frac{\partial}{\partial x^k}$$

geodesic: $\nabla_{\dot{\gamma}} \dot{\gamma} = \frac{D\dot{\gamma}}{dt} = 0$ a vector field along γ .

Lemma. $V(t), W(t)$ are two vector fields along a curve c .

$$\text{Then } \frac{d}{dt} \langle V(t), W(t) \rangle = \langle \frac{DV}{dt}, W(t) \rangle + \langle V(t), \frac{DW}{dt} \rangle$$

Proof: $(U, x) \quad c(t) = (c^1(t), \dots, c^n(t))$

$$V(t) = V^i(t) \frac{\partial}{\partial x^i}(c(t)), \quad W(t) = W^j(t) \frac{\partial}{\partial x^j}(c(t))$$

$$\frac{d}{dt} \langle V(t), W(t) \rangle = \frac{d}{dt} \left(V^i(t) W^j(t) \left\langle \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right\rangle_{c(t)} \right)$$

$$= \frac{d}{dt} (V^i(t) W^j(t)) \left\langle \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right\rangle_{c(t)}$$

$$+ V^i(t) W^j(t) \cdot \frac{d}{dt} \left\langle \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right\rangle_{c(t)}$$

$$\parallel \frac{d}{dt} \left\langle \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right\rangle$$

$$\parallel \left\langle \nabla_{\frac{d}{dt}} \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right\rangle + \left\langle \frac{\partial}{\partial x^i}, \nabla_{\frac{d}{dt}} \frac{\partial}{\partial x^j} \right\rangle$$

$$= \left\langle \dot{V}^i(t) \frac{\partial}{\partial x^i} + V^i(t) \nabla_{\frac{d}{dt}} \frac{\partial}{\partial x^i}, W^j(t) \frac{\partial}{\partial x^j} \right\rangle$$

$$+ \left\langle V^i(t) \frac{\partial}{\partial x^i}, \dot{W}^j(t) \frac{\partial}{\partial x^j} + W^j(t) \nabla_{\frac{d}{dt}} \frac{\partial}{\partial x^j} \right\rangle$$

$$= \left\langle \frac{DV}{dt}, W \right\rangle + \left\langle V, \frac{DW}{dt} \right\rangle. \quad \square$$

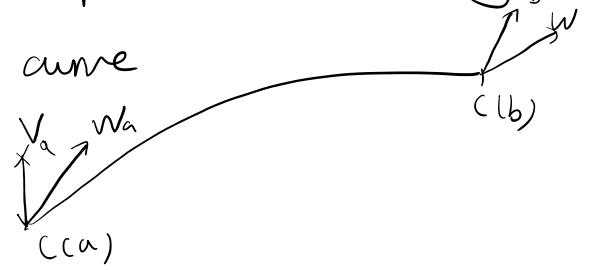
Cor. geodesic eq: $\frac{D\dot{\gamma}}{dt} = 0$.

Cor. (M, g, ∇) , ∇ compatible with $g \iff$ any

parallel transport is an isometry

Proof: $c: [a, b] \rightarrow M$ C^∞ curve

$$P_{c, a, b}: T_{c(a)}M \rightarrow T_{c(b)}M$$



linear isometry preserve $\langle \cdot, \cdot \rangle$ isometry

" \Rightarrow "

$$P_{c, a, t}(V_a) = V(t), \quad V(b) := V_b$$

$$P_{c, a, t}(W_a) = W(t), \quad W(b) := W_b$$

$$\Rightarrow V(b) = P_{c, a, b}(V_a), \quad W(b) = P_{c, a, b}(W_a)$$

$$\langle V(b), W(b) \rangle = \langle V_a, W_a \rangle$$

$$\frac{d}{dt} \langle V(t), W(t) \rangle = 0 \stackrel{\nabla g = 0}{=} \langle \frac{DV}{dt}, W \rangle + \langle V, \frac{DW}{dt} \rangle = 0$$

\Leftarrow If parallel transports are isometry.

∇ $\forall X, Y, Z \in T(TM)$,

$$X \langle Y, Z \rangle (p) = \langle \nabla_X Y, Z \rangle (p) + \langle Y, \nabla_X Z \rangle (p)$$

Consider $X \langle Y, Z \rangle (p) = X(p) \langle Y, Z \rangle$

Find a curve c , s.t. $c(0) = p$, $\dot{c}(0) = X(p)$.

$$X(p) \langle Y, Z \rangle = \left. \frac{d}{dt} \langle Y(c(t)), Z(c(t)) \rangle \right|_{t=0}$$

$T_p M$. $\{E_1, \dots, E_n\}$ orthonormal basis $X(p)$ $\langle E_i, E_j \rangle = \delta_{ij}$

$\{E_1(t), \dots, E_n(t)\}$ orthonormal $c(0) = p$

$\{E_1(t), \dots, E_n(t)\}$ orthonormal $^{(10)=p}$
 frame field.
 $E_i(t) = \mathcal{P}_{c,0,t}(E_i)$

$$\begin{aligned}
 \underline{X(p) \langle Y, Z \rangle} &= \frac{d}{dt} \Big|_{t=t_0} \langle \underline{Y^i(t) E_i(t)}, \underline{Z^j(t) E_j(t)} \rangle \\
 &= \frac{d}{dt} \Big|_{t=t_0} \left(\sum_{i=1}^n Y^i(t) Z^i(t) \right) \\
 &= \sum_{i=1}^n \left(\dot{Y}^i(t) Z^i(t) + Y^i(t) \dot{Z}^i(t) \right) \\
 &= \langle \underline{\dot{Y}^i(t) E_i(t)}, \underline{Z^j(t) E_j(t)} \rangle + \langle \underline{Y^i(t) E_i(t)}, \underline{\dot{Z}^j(t) E_j(t)} \rangle \\
 &= \langle \underline{\frac{DY}{dt} \Big|_{t_0}}, \underline{Z} \rangle + \langle \underline{Y}, \underline{\frac{DZ}{dt} \Big|_{t_0}} \rangle \\
 &= \langle \underline{\nabla_{X_p} Y}, \underline{Z} \rangle + \langle \underline{Y}, \underline{\nabla_{X_p} Z} \rangle \quad \square
 \end{aligned}$$

geodesic eq. $\frac{DY}{dt} \equiv 0$

variation of energy functional

下课