

Synge Theorem : 1936

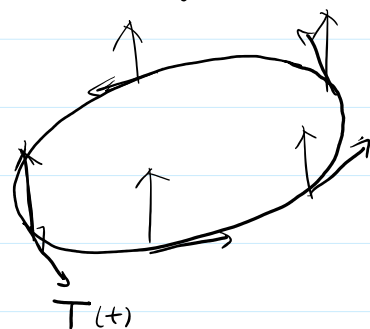
On the connectivity of spaces of positive curvature,
(Quarterly Journal of Math. (Oxford Series), 7, 316-320)
Thm (Synge) (M^n, g) , sec > 0 , M (compact)

- (a) If M is orientable, n is even, then $\pi_1(M) = \{1\}$,
i.e. M is simply connected.
- (b) If M is nonorientable, n is even, then $\pi_1(M) = \mathbb{Z}_2$.
- (c) If M is nonorientable, n is odd, contradiction.
If M is odd dim'l (i.e., n is odd), then M is orientable.

Principle: Let $\gamma: [a, b] \rightarrow M$ a closed ~~curve~~ geodesic
 $\gamma(a) = \gamma(b), \quad \dot{\gamma}(a) = \dot{\gamma}(b)$ $E(t)$

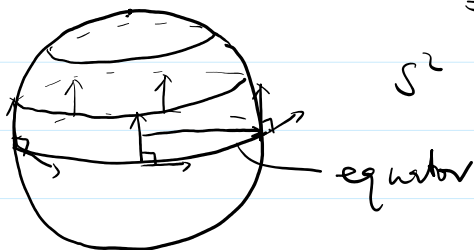
If there exists a parallel vector field along γ ,
s.t. $\langle \underline{E}(t), \underline{T}(t) \rangle = 0, \forall t$

Then γ is not minimizing in its free homotopy class.



Proof: A direct application of SVF.

$$E''(0) = \int_a^b (\underbrace{\langle \nabla_T V, \nabla_T V \rangle}_{=0} - \underbrace{\langle R(V, T)T, V \rangle}_{>0}) dt < 0. \quad \square$$



$$p = \gamma(a) = \gamma(b)$$

Consider: $P := P_{x,a,b} : T_{x(a)} M \rightarrow T_{x(b)} M$

$T(t)$ is parallel along γ , i.e. $\underline{\nabla} T(a) = \underline{T(b)}$
 $= T(a)$

multiplicity of the eigenvalue $+1 \geq 2$

Lemma: $\forall v, w \in T_p M$, $\langle P(v), P(w) \rangle = \langle v, w \rangle$
orthogonal.

matrix $P^T P = Id \Rightarrow \det(P) = \det(P) = \pm 1$.

$Pv = \lambda v \Rightarrow |v|^2 = |\lambda|^2 |v|^2 \Rightarrow \underline{|\lambda| = 1}$

~~eigenvalues~~: eigenvalues: $\lambda_1, \bar{\lambda}_1, \dots, \lambda_j, \bar{\lambda}_j, \underbrace{-1, \dots, -1}_k, \underbrace{+1, \dots, +1}_l$ ($l \geq 1$)

Aim: $l \geq 2$.

Lemma: If $\det(P) = +1$, n even, then $l \geq 2$
If $\det(P) = -1$, n odd, then $l \geq 2$.

Proof: $\det(P) = +1 \Rightarrow \left. \begin{matrix} k \text{ even} \\ n \text{ even} \end{matrix} \right\} \Rightarrow \left. \begin{matrix} l \text{ even} \\ l \geq 1 \end{matrix} \right\} \Rightarrow l \geq 2$

$\det(P) = -1 \Rightarrow \left. \begin{matrix} k \text{ odd} \\ n \text{ odd} \end{matrix} \right\} \Rightarrow \left. \begin{matrix} l \text{ even} \\ l \geq 1 \end{matrix} \right\} \Rightarrow l \geq 2$ □

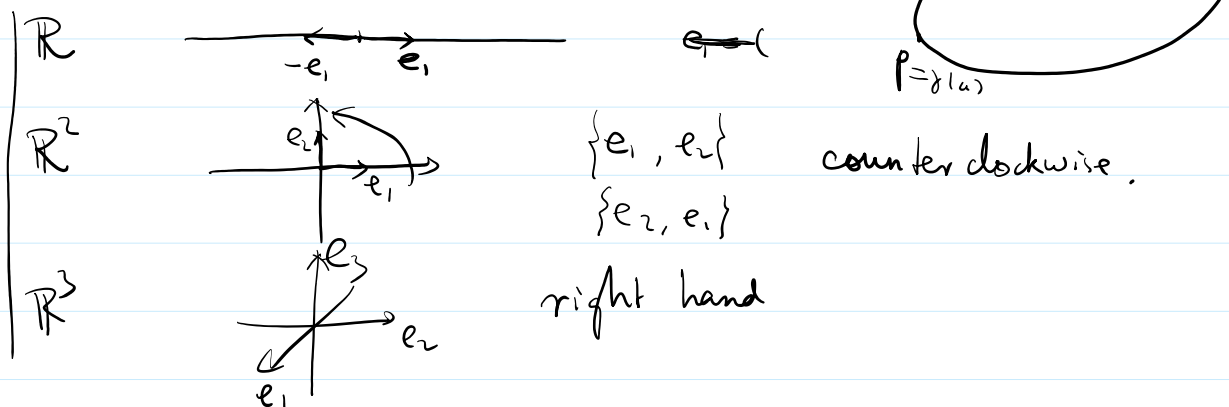
Lemma: Let (M^n, g) be an orientable ∞ Rie. mfd.

$\gamma: [a, b] \rightarrow M$ be a \wedge closed curve. $p = \gamma(a) = \gamma(b)$

Then $P := P_{\gamma, a, b}: T_p M \rightarrow T_p M$ has determinant +1.

Proof: Remains to show $\det(P) > 0$

Orientation:



Vector space V $\{f_1, \dots, f_n\}$ $\{e_1, \dots, e_n\}$
 $f_i = a_i^j e_j$ $\bigcap_{r=1}^n \wedge^n(V^*)$ $\Omega(f_1, \dots, f_n)$
 n -covector

$$f_j = a_j^i e_i$$

$$\det(a_j^i) \begin{matrix} > 0 \\ < 0 \end{matrix} \rightsquigarrow \text{equivalence class of orientations.}$$

$$\textcircled{\Omega} \in \frac{\Lambda^n(V^*)}{\sim} = \det(a) \Omega(e_1, \dots, e_n)$$

n-covector



pointwise orientation.
local
a frame
orientable

$\exists C^\infty$ n-form, nowhere vanishing, $(\omega) \Leftrightarrow \text{orientable}$

$\{e_1(a), \dots, e_n(a)\} \subset T_p M$ orthonormal

$P(e_1(a)) = e_1(b) \in T_p M.$

$P_{\gamma: a, t}(e_i(a)) = e_i(t) \in T_{\gamma(t)} M.$

$\omega(e_1(t), e_2(t), \dots, e_n(t))$ a C^∞ fct along γ .

$$\underbrace{\omega(e_1(a), \dots, e_n(a)) > 0}_{\Rightarrow \det(P) > 0} \Rightarrow \underbrace{\omega(e_1(b), \dots, e_n(b)) > 0}_{\square}$$

Proof Symp (a). $\left\{ \begin{array}{l} \text{orientable} \\ n \text{ even} \end{array} \right\} \Rightarrow \det(P) = +1 \left\{ \begin{array}{l} \text{Linear Algebra} \\ \underline{\underline{\lambda \geq 2}} \end{array} \right.$

compact $\xRightarrow{\text{Chap}^2}$ \exists minimizing closed geodesic γ in every homotopy class.

$\xrightarrow{\text{Sec} > 0}$ $\left\{ \begin{array}{l} \text{SVE} \end{array} \right.$ If γ is not a point, γ is a closed geodesic then γ can not be minimizing in its homotopy class.

□

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Proof Symp (c). (M^n, g) $\text{Sec} > 0$, compact, n odd, non orientable \rightarrow contradiction.

Proof: non-orientable $\Rightarrow \exists$ closed curve c , s.t. $[c]$ is nontrivial and null

Proof: non-orientable $\Rightarrow \exists$ closed curve c , s.t.

free homotopy class $[c]$ is nontrivial, and parallel transportation ~~along~~ each of it is orientation reversing.

compact $\Rightarrow [c] \ni$ minimizing closed geodesic γ .

non orientable $\left. \begin{array}{l} n \text{ odd} \\ \det(P) = -1 \end{array} \right\} \xRightarrow{LA} l \geq 2 \left\{ \begin{array}{l} \text{sec} > 0 \\ \text{SVF} \end{array} \right. \Rightarrow \gamma \text{ cannot be minimizing. } \square$

Synge (b). (M^n, g) compact, $\text{sec} > 0$, n even, nonorientable
 $\Rightarrow \pi_1(M) = \mathbb{Z}_2$

Proof: M^n , nonorientable $\Rightarrow \exists \hat{M}^n$ is a double cover of M , orientable

$$\left(\underline{\text{Lee}} \right) \begin{pmatrix} M \\ p \end{pmatrix} \begin{matrix} T_p M \\ O_p^1 \\ O_p^2 \end{matrix}$$

$$\hat{M} = \{ (p, O_p^i) \mid p \in M, O_p \in \{O_p^1, O_p^2\} \}$$

$$\pi: \hat{M} \rightarrow M \quad \begin{array}{l} \text{Rie. covering map} \\ \text{local isometry} \end{array} \quad \textcircled{b}$$

\hat{M}^n n even. compact, $\text{sec} > 0$ orientable.
Synge (a) \hat{M}^n is simply connected. $\Rightarrow \pi_1(M) = \mathbb{Z}_2$. \square

Remarks: (1) existence of particular Rie. metric on a given smooth manifold.

$$(2) \text{ Examples: } \mathbb{R}P^n \quad \pi: \underline{S^n} \rightarrow \mathbb{R}P^n$$

$$\Rightarrow \pi_1(\mathbb{R}P^n) = \mathbb{Z}_2$$

$$n \text{ even} \quad \mathbb{R}P^2 \quad \text{compact} \quad \text{sec} > 0, \quad \boxed{\text{non orientable}}$$

$$\boxed{\pi_1(\mathbb{R}P^2) = \mathbb{Z}_2}$$

$$n \text{ odd} \quad \mathbb{R}P^3 \quad \text{compact,} \quad \text{sec} > 0 \Rightarrow \text{orientable.}$$

(V). Space forms and Jacobi field.

• Space form: complete Rie mfd with constant sectional curvature.

Bonnet - Myers. $\sec \geq \underline{k} > 0 \Rightarrow \text{diam} \leq \frac{\pi}{\sqrt{k}}$

$$\text{diam}(S^2(\frac{1}{\sqrt{k}})) = \pi \cdot r = \pi \cdot \frac{1}{\sqrt{k}}$$

$$\sec(M^2) \geq \sec(S^2(\frac{1}{\sqrt{k}})) \Rightarrow \text{diam}(M^2) \leq \text{diam}(S^2)$$

$$K(g) = \frac{1}{A} K(g)$$

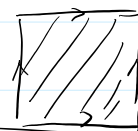
Space form with sec. curvature = 0, +1, -1.

\mathbb{R}^n

Sec = 0



flat torus



Theorem 1. $\forall c \in \mathbb{R}, \forall n \in \mathbb{Z}^+, \exists!$ (up to isometries) simply connected n -dim'l space form with sectional curvature = c .

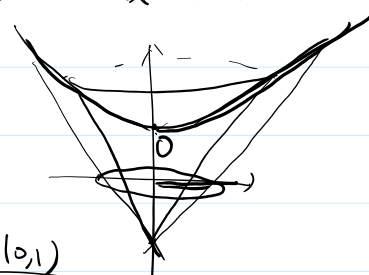
$$c = 0, +1, -1$$

$(\mathbb{R}^n, g_{\text{euc}})$

(S^n, g)

(H^n, g)

$B^n(0,1)$



$$R_{ijkl} = \frac{1}{2} \left(\frac{\partial^2 g_{jk}}{\partial x^i \partial x^l} - \frac{\partial^2 g_{ik}}{\partial x^j \partial x^l} - \frac{\partial^2 g_{jl}}{\partial x^i \partial x^k} + \frac{\partial^2 g_{il}}{\partial x^j \partial x^k} \right) + g_{mp} (\Gamma_{il}^m \Gamma_{jk}^p - \Gamma_{jl}^m \Gamma_{ik}^p)$$

Homework:

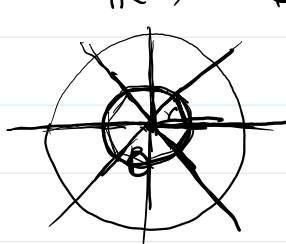
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§1. Geodesics in \mathbb{R}^n, S^n, H^n .

$$\lim_{s \rightarrow \infty} \frac{e^s - 1}{e^{s+1}} = 1$$

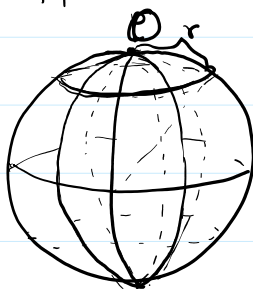
§1. Geodesics in \mathbb{R}^n , S^n , H^n .

\mathbb{R}^2 , S^2 , H^2



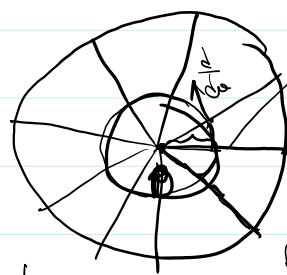
\mathbb{R}^2

diverge



S^2

diverge - converge



polar

H^2

divergence

$$\lim_{s \rightarrow \infty} \frac{e^s - 1}{e^s + 1} = 1$$

$$\gamma(s) = \left(\frac{e^s - 1}{e^s + 1} \right) \vec{p}$$

$$|\dot{\gamma}(s)|_g = 1$$

$B(0,1)$

$$(M, g) \quad C(r) := \{x \in M : d(x, o) = r\}$$

length denote $c_+(r)$, $c_-(r)$, $c_0(r)$ the length

$$(1) \quad c_0(r) = 2\pi r \quad \text{linear in } r.$$

$$(2) \quad c_+(r) = 2\pi \sin r.$$

$$(3) \quad c_-(r) = 2\pi \sinh r. \quad \text{exponential in } r$$

curve. $\gamma(\theta) = (p_r, \theta)$, $\theta \in (0, 2\pi)$

$$c_-(r) = \int_0^{2\pi} \sqrt{\frac{4p_r^2}{(1-p_r^2)^2}} d\theta \quad p_r = \frac{e^r - 1}{e^r + 1}$$

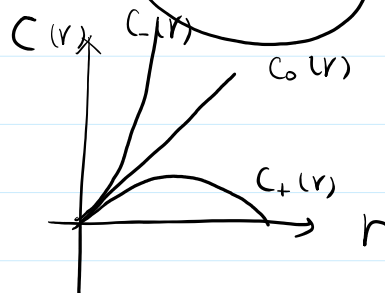
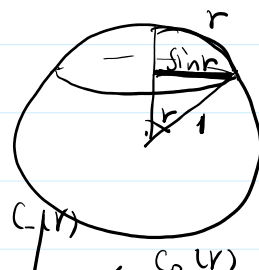
$$g = \frac{4}{(1-p^2)^2} (dp^2 + p^2 d\theta^2)$$

$$c_-(r) = \int_0^{2\pi} \frac{2p_r}{1-p_r^2} d\theta = 2\pi \cdot \frac{2 \frac{e^r - 1}{e^r + 1}}{1 - \left(\frac{e^r - 1}{e^r + 1}\right)^2} = 2\pi \left| \frac{e^r - e^{-r}}{2} \right| \sinh r$$

$$\cosh r = \frac{e^r + e^{-r}}{2}$$

What happens in general?

(M^n, g) $o \in M$, geodesic sphere $\exp_o: T_o M \rightarrow M$

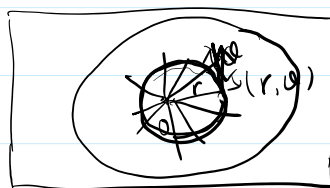


(M^n, g) $O \in M$,

geodesic sphere

$\exp_0: T_0 M \rightarrow M$

$c(r) = \text{length}(\exp_0((r, \theta)))$

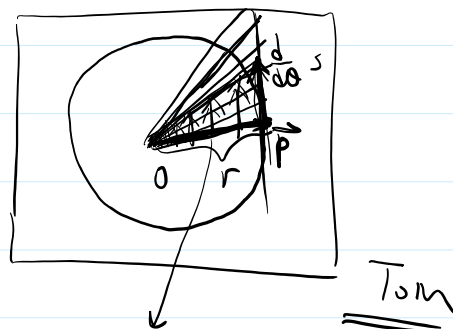
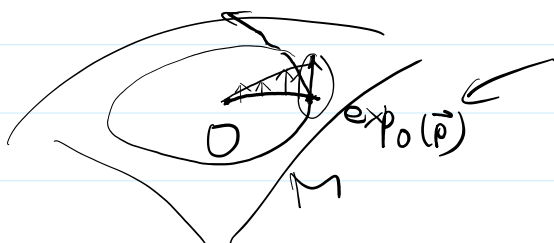


$d\exp_0(r, \theta):$
 $T_{(r, \theta)} T_0 M$

$T_0 M \rightarrow T_{\exp_0(r, \theta)} M$

$c(r) = \int_0^{2\pi} \left\langle d\exp_0(r, \theta) \left(\frac{d}{d\theta} \right), d\exp_0(r, \theta) \left(\frac{d}{d\theta} \right) \right\rangle^{1/2} d\theta$

$\vec{p} = (r, \theta)$

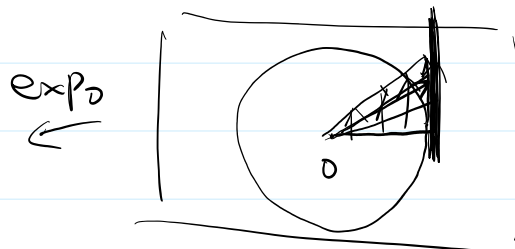
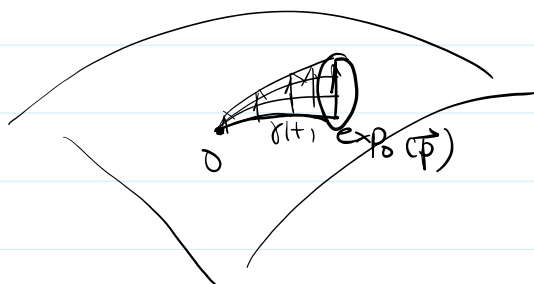


$t \mapsto \frac{t}{r} \vec{p}, t \in [0, r]$

$\gamma(t) = \exp_0 \left(\frac{t}{r} \vec{p} \right), t \in [0, r]$, radial geodesic from O

We consider: $F: [0, r] \times (-\varepsilon, \varepsilon) \rightarrow M$

$F(t, s) \mapsto \exp_0 \frac{t}{r} \left(\vec{p} + s \frac{d}{d\theta} \right)$
 $F(t, 0) = \gamma(t)$



$\gamma_s(t) = F(t, s)$ is a geodesic

variational field $V(t) = \frac{\partial F}{\partial s}(t, 0) = \frac{\partial}{\partial s} \Big|_{s=0} \exp_0 \frac{t}{r} (\vec{p} + s \frac{d}{d\theta})$

? $V(r) \stackrel{?}{=} d\exp_0(\vec{p}) \left(\frac{d}{d\theta} \right)$

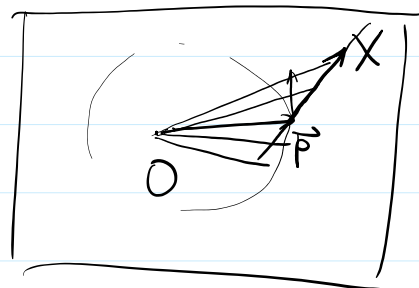
$V(r) = \frac{\partial F}{\partial s}(r, 0) = \frac{\partial}{\partial s} \Big|_{s=0} \exp_0 \frac{t}{r} (\vec{p} + s \frac{d}{d\theta}) \Big|_{t=r}$
 $= \frac{\partial}{\partial s} \Big|_{s=0} \exp_0 (\vec{p} + s \frac{d}{d\theta})$

$$= \frac{\partial}{\partial s} \Big|_{s=0} \exp_0 \left(\vec{p} + s \frac{d}{ds} \right)$$

$$\boxed{\exp_0 : T_0 M \rightarrow M} = d\exp_0(\vec{p}) \left(\frac{d}{ds} \right) \quad \square$$

We can be slightly more general.

$$X \in T_{\vec{p}}(T_0 M) \cong T_0 M.$$



$$F(t, s) = \exp_0 \frac{t}{r} (\vec{p} + sX)$$

$$t \in [0, r], \quad s \in (-\varepsilon, \varepsilon)$$

$$V(t) = \frac{\partial F}{\partial s}(t, 0) \quad \text{variational field.}$$

$$\text{Aim. } |V(t)| \quad ?$$

$$\frac{\partial F}{\partial t}(t, 0) = \underline{T(t)}$$

$$\frac{D}{dt} \frac{D}{dt} V(t) = \frac{D}{dt} \frac{D}{ds} \frac{\partial F}{\partial s} \Big|_{s=0} = \frac{D}{dt} \frac{D}{ds} \frac{\partial F}{\partial t}$$

$$= \frac{D}{ds} \left(\frac{D}{dt} \frac{\partial F}{\partial t} \right) + R \left(\frac{\partial F}{\partial t}, \frac{\partial F}{\partial s} \right) \frac{\partial F}{\partial s} \Big|_{s=0} (t, 0)$$

$$\frac{\partial F}{\partial t}(t, s) \Big|_{s=0} \equiv \text{tang velocity field of } \underline{\gamma_s(\cdot)} \quad s \in (-\varepsilon, \varepsilon)$$

$$= R \left(\frac{\partial F}{\partial t}, \frac{\partial F}{\partial s} \right) \frac{\partial F}{\partial t} (t, 0)$$

$$\boxed{\nabla_T \nabla_T V = R(T, V)T} \quad \text{i.e.} \quad \boxed{\nabla_T \nabla_T V + R(V, T)T = 0}$$

Definition (Jacobi field) Let $\gamma : [a, b] \rightarrow M$ be a ^{normal} geodesic

$$\text{Def } T(t) := \dot{\gamma}(t)$$

If a vector field V along γ satisfies

$$\nabla_T \nabla_T V + R(V, T)T = 0 \quad (1)$$

then we call V a Jacobi field along γ .

then we call V a Jacobi field along γ .
The equation (1) is called the Jacobi equation.

How to solve the equation?

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