

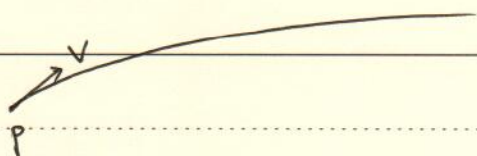
## § 2.1/2 Cut point and Cut locus

We concern the following two basic questions:

- ① Is a shortest curve parametrized by arc length a geodesic?
- ② Is a geodesic the shortest curve connecting its endpoints?

The answer to ① is yes by the local existence and uniqueness of shortest curves and the fact that every "subcurve" of a shortest one is again shortest.

However, the answer to ② is not definite. We know from previous discussion that a geodesic is shortest when its length is small enough. When the length is large, a geodesic can be not shortest anymore.



That is, for any  $p \in M$ , and  $V \in T_p M$  with  $\|V\|=1$ ,  $\wedge$  suppose the geodesic

$$\gamma(t) := \exp_p tV$$

is defined on a maximal interval  $[0, b)$ ,  $b \in \mathbb{R}_+$  or  $b = \infty$ .

Recall that the interval is open at the  $b$  end since is due to the local existence and uniqueness of geodesics.

Observe that if  $\gamma|_{[0, t]}$  is shortest, then so is  $\gamma|_{[0, t']}$  for any  $t' \in (0, t)$ . That is, if we set

$$\begin{aligned} A &:= \{t > 0 : d(p, \gamma(t)) = t\} \\ &= \{t > 0 : \gamma|_{[0, t]} \text{ is shortest}\} \end{aligned}$$

Then either  $A = (0, b)$  or  $A = (0, a]$  for some  $0 < a < b$ .

Notice that, the latter case means  $\gamma|_{[0, t]}$  is not shortest for all  $t > a$ .

• If  $A = (0, a]$  for some  $0 < a < b$ , we say that  $\gamma(a)$  is the cut point of  $p$  along the geodesic  $\gamma$ .

• If  $A = (0, b)$ , we say that  $p$  has no cut point along  $\gamma$ .

**Definition (Cut locus)** The cut locus  $C(p)$  of  $M$  of  $p$  is the set of all points which are cut points of  $p$  along some normal geodesic emanating from  $p$ .

We also call the cut locus  $\tilde{C}(0)$  of  $0 \in T_p M$  to be the set of all vectors  $\alpha X \in T_p M$  for which  $X$  is a unit tangent vector and  $\exp_p(\alpha X)$  is the cut point of  $p$  along the geodesic  $\gamma_X(t) := \exp_p(tX)$ .

**Remark.** We have then  $\exp_p(\tilde{C}(0)) = C(p)$ .

**Example.** a) Open disc in  $E^2$  with center  $p$  and radius  $r$ .

Then  $p$  has no cut points, i.e.  $C(p) = \emptyset$ . In fact, for any  $v \in T_p M$ ,  $\|v\| = 1$ , and the corresponding  $\gamma(t) := \exp_p(tX)$ , we have  $A = (0, r)$ .

b) Standard unit round sphere: the cut locus  $C(p)$  is ~~the~~ <sup>its</sup> antipodal  $p'$ . In the tangent space  $T_p M$ , we have

$$\tilde{C}(0) = \partial B(0, \pi)$$

### § 3½ Structure of complete Riemannian manifolds

We first observe that the exponential map  $\exp_p$  at any point  $p$  of a complete Riemannian manifold is surjective by Hopf-Rinow theorem. ~~And~~ <sup>Indeed</sup>, completeness ensures that there exists a shortest curve from  $p$  to any ~~other~~ point  $q \in M$ .

That is, every  $q \in M$  possesses a preimage under  $\exp_p$  in  ~~$\mathbb{C}_p \subset T_p M$~~   $T_p M$ . If we denote the shortest curve from  $p$  to  $q$  by the normal geodesic  $\gamma(t)$  with  $\gamma(0) = p$ , then the preimage of  $q$  is just  ~~$\gamma(1) \in T_p M$~~   $d(p, q) \cdot \dot{\gamma}(0) \in T_p M$ .

Recall that  $\exp_p$  is always a local diffeomorphism. In general, we cannot expect ~~that~~  $\exp_p$  to be a global diffeomorphism. That is, we care about "how global" this diffeomorphism can be. More precisely, we hope to ask

- How large can the Normal neighborhood of  $p$  be?

Let us first recall the following useful corollary of the inverse function theorem.

[See BSSG pp. 11] For any  $U \subset \mathbb{R}^n$ , a  $C^k$  mapping  $F: U \rightarrow F(U) \subset \mathbb{R}^n$  is a  $C^k$  diffeomorphism iff it is one-to-one and  $dF$  is nonsingular at any point of  $U$ .

That is, to check a  $C^k$  map to be a diffeomorphism, we only need to check its "local one-to-one" and "global one-to-one".

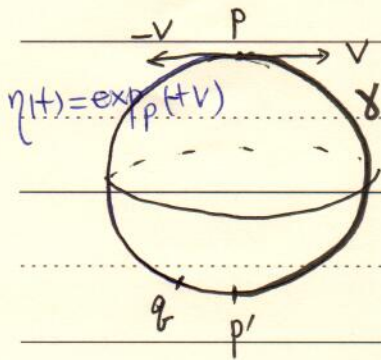
The global 1-1 ensures the existence of the inverse map, and

the nonsingularity of  $dF$  ensures the smoothness of the inverse map.

Remark. Notice that without the nonsingularity of  $dF$ , the conclusion is not true anymore. A counterexample can be  $f: \mathbb{R} \rightarrow \mathbb{R}$  s.t.  $f(x) = x^3$ . It is  $C^\infty$ , 1-1 but not a diffeomorphism.

Before the general discussion, let us first investigate some examples.

### Example 1 Round Sphere



Cut locus of  $p$ :  $C(p) = \{p'\}$

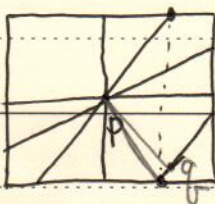
Moreover:  $\exp_p: B(0, \pi) \subset T_p M \rightarrow S^2 \setminus C(p)$  is a diffeomorphism.

In fact, this map can be expressed explicitly as:  

$$tV \mapsto \cos(t\|V\|)p + \sin(t\|V\|)\frac{v}{\|V\|}$$

With this, one can check the nonsingularity of  $d\exp_p$  at any point of  $B(0, \pi) \setminus \{0\}$ . Recall the nonsingularity of  $d\exp_p$  at 0 is known. The global 1-1 property of  $\exp_p: B(0, \pi) \subset T_p M \rightarrow S^2 \setminus C(p)$  is clear. Therefore it is a diffeomorphism.

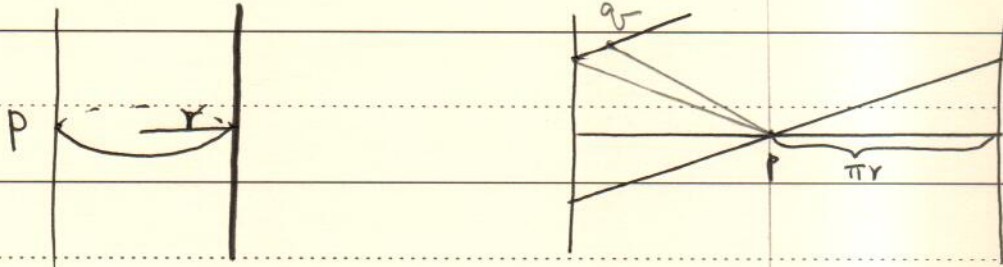
### Example 2 Flat torus



Cut locus of  $p$ :  $C(p) =$  the boundary of the rectangle under identification.  
 Intuitively,  $\exp_p$  is a diffeomorphism

from this open rectangular region in  $T_p M$  ~~and~~ to  $M \setminus C(p)$ .

### Example 3: Cylinder

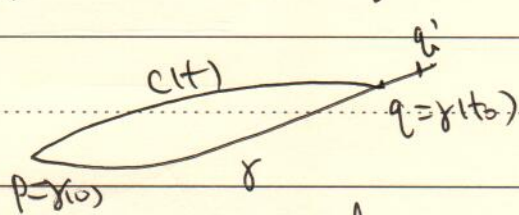


The cut locus of  $p$ :  $C(p) =$  The vertical line passing its antipodal.

The exponential map  $\exp_p$  is a diffeomorphism from the "belt region" in  $T_p M$  to the  $\text{Cylinder} \setminus C(p)$ .

The above examples tell us the cut locus seems to be the obstacle of the further extension of normal neighborhood. Indeed it

Remark  $\otimes$  The cut points in the above examples have the same property that there exist two shortest curves from  $p$  to a point in  $C(p)$ . We can show this phenomena generally implies means cut point. That is, for a given geodesic  $\gamma(t)$ , if there are two shortest curves from  $p = \gamma(0)$  and  $q = \gamma(t_0)$ , then  $q$  is a cut point all the points  $\gamma|_{[0, t]}$



is not shortest anymore for any  $t > t_0$ .

Let us denote the other <sup>shortest</sup> curve as  $c(t)$ . Then suppose  $\gamma|_{[0, t]}$  is still shortest

from  $p$  to  $q' = \gamma(t')$ , then

we have another path  $\zeta : [0, t'] \rightarrow M$

$$\zeta(t) = \begin{cases} c(t), & t \in [0, t_0] \\ \gamma(t), & t \in [t_0, t'] \end{cases}$$

which is of the same length as  $\gamma|_{[0, t]}$ , but not smooth at  $t_0$ . (By uniqueness of geodesics).

This contradicts to the fact that any shortest curve is smooth.  $\square$

If, <sup>moreover,</sup>  $t_0$  is the smallest value that such phenomena happens, then  $q$  is indeed a cut point.  $\square$

The above examples provide hints that cut locus might be the obstacle ~~of~~ to the further extension of normal neighborhood. Indeed, we have.

Theorem 1 (Cut points) Let  $(M, g)$  be complete, and let  $\gamma : [0, \infty) \rightarrow M$  be a normal geodesic with  <sup>$p = \gamma(0)$</sup>  cut point  $q = \gamma(a)$  <sup>and</sup>. Then at least one of the following holds:

(i)  $d_{\exp_p}$  is singular at  $a\dot{\gamma}(0) \in T_p M$ .

(ii) There are at least two shortest curves from  $p = \gamma(0)$  to  $q = \gamma(a)$ , and  $a$  is the minimal value such that this case happens.

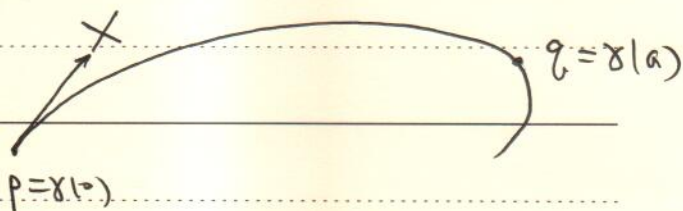
Remark. ~~It~~ <sup>Theorem</sup> means  $\exp_p$  is not injective on  $\tilde{C}(0) \subset T_p M$ .

~~Our previous~~

Proof:

Denote by  $X := \dot{\gamma}(0)$  the unit tangent vector of  $\gamma$ .

Then  $\gamma(t) := \exp_p(tX)$ .



Choose a sequence of numbers "after  $a$ ":

$$a_1 > a_2 > a_3 > \dots \quad \text{such that} \quad \lim_{i \rightarrow \infty} a_i = a.$$

By definition of a cut point, we know  $b_i := d(p, \gamma(a_i)) < a_i$ .

By completeness, there are unit tangent vectors  $X_i \in T_p M$

s.t.  $\gamma_i(t) := \exp_p(tX_i)$ ,  $t \in [0, b_i]$  is the shortest curve from  $p$  to  $\gamma(a_i) = \exp_p(b_i X_i)$ .

Since  $\gamma(a)$  is a cut point of  $p$  along  $\gamma$ , we know ~~every~~ <sup>all</sup>  $X_i$ 's are distinct from  $X$ .

By continuity of distance functions, we have

$$\lim_{i \rightarrow \infty} b_i = \lim_{i \rightarrow \infty} d(p, \gamma(a_i)) = d(p, \gamma(a)) = a.$$

Therefore  $\{b_i X_i\}_{i=1}^{\infty}$  is contained in a compact subset of  $T_p M$ .

Choosing a subsequence if necessary, we have

$$\lim_{i \rightarrow \infty} b_i X_i = aY \quad \text{for some unit vector } Y \in T_p M.$$

Observing that  $\exp_p(aY) = \lim_{i \rightarrow \infty} \exp_p(b_i X_i) = \lim_{i \rightarrow \infty} \gamma(a_i) = \gamma(a)$ ,

we see the geodesic  $t \mapsto \exp_p(tY)$ ,  $t \in [0, a]$  is a curve from  $p$  to  $\gamma(a)$  of length  $a$ , i.e., it is ~~the~~ <sup>a</sup> shortest one.

Case (1). If  $X \neq Y$ , we have two shortest curves from  $p = \gamma(0)$  to  $q = \gamma(a)$ . By the arguments from the previous Remark ④, we obtain that for any  $t \in (0, a)$ ,

There exists a unique shortest curve from  $p$  to  $\gamma(t)$ . That is,  $a$  is the minimal value such that more than one shortest curve can happen.

Case (2) If  $X = Y$ , we have

$$\lim_{i \rightarrow \infty} b_i X_i = aY = aX = \lim_{i \rightarrow \infty} a_i X.$$

On the other hand, we have

$$\exp_p(b_i X_i) = \gamma(a_i) = \exp_p(a_i X).$$

Moreover,  $b_i X_i$  and  $a_i X$  are distinct for each  $i$ , since  $b_i < a_i$ ,  $X_i \neq X$ .

Therefore,  $\exp_p$  is not 1-1 in any neighborhood of  $aX \in T_p M$ . That is,  $aX \in T_p M$  is a critical point of  $\exp_p$ . In other words,  $d\exp_p$  is a singular at  $aX = a\dot{\gamma}(0)$ .  $\square$

Now we have the following important observation: Let us ~~Theorem~~ Let  $(M^n, g)$  be complete. first introduce some notations.

For  $p \in M$ , denote by  $S_p$  the unit sphere of  $T_p M$ . Let  $\mathbb{R}^* := \mathbb{R} \cup \{\infty\}$ . We define a function

$$\tau: S_p \longrightarrow \mathbb{R}^*$$

as follows

$$\tau(X) = \begin{cases} a, & \text{if } \exp_p(aX) \text{ is the cut point of } p \text{ along the geodesic } t \mapsto \exp_p(tX). \\ \infty, & \text{if } p \text{ has no cut point along the geodesic } t \mapsto \exp_p(tX). \end{cases}$$

We further define

$$E(p) := \{tV : V \in S_p, \text{ and } 0 \leq t < \tau(V)\} \subset T_p M.$$



Theorem 2. Let  $(M^n, g)$  be complete. Then  $M$  is the disjoint union of  $\exp_p(E(p))$  and  $C(p)$ , i.e.

$$M = \exp_p(E(p)) \sqcup C(p).$$

Proof: By completeness,  $\exp_p$  is surjective on  $E(p) \cup \tilde{C}(0) \subset T_p M$ .

That is,  $M \subset \exp_p(E(p)) \cup C(p)$ .

On the other hand, ~~for~~ it is clear  $\exp_p(E(p)) \cup C(p) \subset M$ .

Therefore, we have

$$M = \exp_p(E(p)) \cup C(p).$$

Next, we show  $\exp_p(E(p)) \cap C(p) = \emptyset$ .

If not, let  $W \in E(p)$  and  $V \in \tilde{C}(0_p)$  satisfy  $\exp_p W = \exp_p V =: q$ .

Case 1 If  $\|V\| < \|W\|$ , this means the geodesic  $t \mapsto \exp_p(tW)$ ,  $t \in [0, 1]$  is not a shortest curve from  $p$  to  $q$ , which contradicts to the assumption  $W \in E(p)$ .

Case 2 If  $\|V\| > \|W\|$ , this means the geodesic  $t \mapsto \exp_p(tV)$ ,  $t \in [0, 1]$  is not a shortest curve from  $p$  to  $q$ , which contradicts to the assumption that  $V \in \tilde{C}(0_p)$ .

Case 3 If  $\|V\| = \|W\|$ , then there are two shortest curves from  $p$  to  $q$ . By the arguments of Remark (4), we obtain that  $q$  ~~is also the cut~~ lies "after" the cut point of  $p$  on the geodesic  $t \mapsto \exp_p tW$ . This contradicts to the ~~for~~ assumption that  $W \in E(p)$ .

Therefore, our assumption is wrong.  $\square$

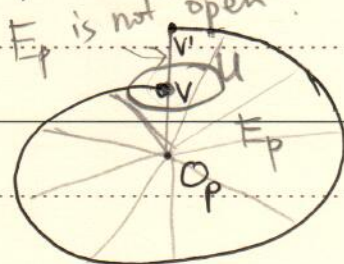
Notice that  $\exp_p$  is 1-1 on  $E(p)$  (Using Rank  $\textcircled{4}$ ).  
 (injective).

Moreover, by Theorem 1,  $d\exp_p$  is nonsingular everywhere in  $E(p)$ . So by [BSSG pp.11], we know  $\exp_p$  is a ~~diffeomorphism~~ diffeomorphism on  $E(p)$  if  $E(p) \subset T_p M \cong \mathbb{R}^n$  is open.

Question. Is  $E(p)$  always open?

One can check the examples of round sphere, flat torus, any cylinder; In those cases,  $E(p)$  are always open.

However, in general, we can not immediately exclude the following possibility:



$T_p M$

$\tilde{C}(O_p)$

A rough idea why the jump at  $v$  cannot happen:

If this happens, then  $v$  lies inside  $[O_p, v']$ . Therefore,  $d\exp_p$  is nonsingular at  $v \Leftrightarrow \exists U \ni v$  s.t.  $\exp_p|_U$  is a diffeomorphism. Then the part of  $\tilde{C}(O_p)$  in  $U$  must be mapped to cut points which possess at least 2 shortest curves. In limit, this forces  $\exp_p v$  has 2 shortest curves, contradiction!

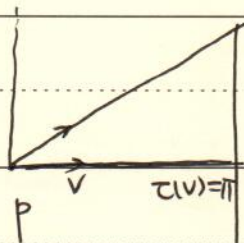
Notice that, the above case can be excluded if the function  $\tau: S_p \rightarrow \mathbb{R}^+$  is continuous! If it is

continuous, then for any Cauchy ~~limit~~ sequence  $\{\tau(V_i) V_i\}_{i=1}^{\infty}$  we have  $\{V_i\}_{i=1}^{\infty}$  is Cauchy and  $\lim_{i \rightarrow \infty} V_i = V$ . Then

$$\lim_{i \rightarrow \infty} \tau(V_i) V_i = \tau(V) V.$$

That is,  $\tilde{C}(O_p)$  is a closed. Therefore  $E_p$  is open!

However, we should be more careful: Consider the case of cylinder, we have  $\tilde{C}(O_p)$



In this case,  $\tau$  is not "continuous", but if we include  $\infty$  by  $\mathbb{R}^* = \mathbb{R} \cup \{\infty\}$  and put the topology with a basis consisting of all sets of the form  $(a, b) \subset \mathbb{R}$  together with all sets of the form  $[a, \infty] := (a, \infty) \cup \{\infty\}$ , then  $\tau$  is ~~not~~ continuous.

Theorem 3: Let  $(M^n, g)$  be complete and  $p \in M$ . Then

the function  $\tau: S_p \rightarrow \mathbb{R}^*$  is continuous.

Proof: Let  $X_1, X_2, \dots$  be a sequence of vectors in  $S_p$  converging to  $X \in S_p$ . We aim to show  $\{\tau(X_i)\}$  converges to  $\tau(X)$ .

Since ~~all~~ all the values of  $\tau$  lie in the compact set  $\{\alpha \in \mathbb{R}^* : \alpha \geq 0\}$ ,  $\{\tau(X_i)\}$  has convergent subsequences.

Pick any subsequence, which we denote still by  $\{\tau(X_i)\}$ , and denote its limit by  $\alpha \in \mathbb{R}^*$ . We compare  $\tau(X)$  and  $\alpha$ .

Case 1:  $\alpha = \infty$ .

For any given  $t$ , there exists  $N$  s.t.  $\tau(X_i) > t, \forall i \geq N$ .

Observe that

$$d(p, \exp_p(tX)) = \lim_{i \rightarrow \infty} d(p, \exp_p(tX_i)) = t$$

Since  $\tau(X_i) > t$  when  $i$  large enough.

That is,  ~~$\tau(X) > t$~~   $\tau(X) \geq t$ .

Since this holds for arbitrary given  $t$ , we have  $\tau(X) = \infty$ .

Case 2:  $\alpha < \infty$ .

That is,  $\lim_{i \rightarrow \infty} \tau(X_i) = \alpha$ , and hence  $\lim_{i \rightarrow \infty} \tau(X_i)X_i = \alpha X$ .

$$d(p, \exp_p(\alpha X)) = \lim_{i \rightarrow \infty} d(p, \exp_p(\tau(X_i)X_i)) \\ = \lim_{i \rightarrow \infty} \tau(X_i) = \alpha.$$

By definition, this means

$$\tau(X) \geq \alpha.$$

In conclusion, for any convergent subsequence  $\{\tau(X_i)\}$  with limit  $\alpha \in \mathbb{R}^*$ , we have  $\tau(X) \geq \alpha$ .

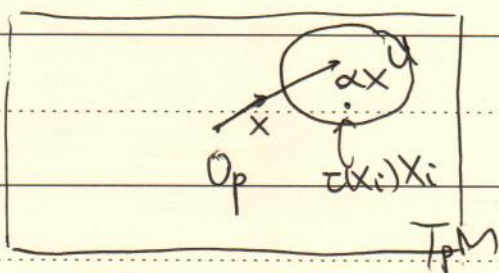
So,  $\boxed{\limsup_{i \rightarrow \infty} \tau(X_i) \leq \tau(X)}$  (1)

Next, we show the opposite one: for any convergent subsequence  $\{\tau(X_i)\}$  with limit  $\alpha \in \mathbb{R}^*$ , we have  $\tau(X) \leq \alpha$ .

We show it by contradiction. (A)

Suppose  $\tau(X) > \alpha$ . Then  $d\exp_p$  is not singular at  $\alpha X$ .

Therefore,  $\exp_p$  is a diffeomorphism on a neighborhood  $U$  of  $\alpha X$  in  $T_p M$ . Since  $\tau(X_i)X_i \rightarrow \alpha X$ , we may assume all



$$\tau(X_i)X_i \in U.$$

Hence  $d\exp_p$  is not singular at  $\tau(X_i)X_i, \forall i$ .

Then definition of  $\tau(X_i)$  and Theorem 1 implies the existence of another shortest curve from  $p$  to  $\exp_p \tau(X_i)X_i$ .

That is, there exists  $Y_i \in S_p$ , s.t.  $\exp_p \tau(X_i)Y_i = \exp_p \tau(X_i)X_i$ .

Since  $\exp_p|_U$  is 1-1, we have  $\tau(X_i)Y_i \notin U$ .

By taking a subsequence when necessary, we assume

$$\lim_{i \rightarrow \infty} Y_i = Y \in S_p.$$

Then we have  $\lim_{i \rightarrow \infty} \tau(X_i)Y_i = \alpha Y$ .

Since  $U$  is open,  $\tau(X_i)Y_i \notin U$ , we have  $\alpha Y \notin U$ .

In particular,  $\alpha Y \neq \alpha X$ .

$$\begin{aligned} \text{However, } \exp_p(\alpha Y) &= \lim_{i \rightarrow \infty} \exp_p(\tau(X_i)Y_i) = \lim_{i \rightarrow \infty} \exp_p(\tau(X_i)X_i) \\ &= \exp_p(\alpha X). \end{aligned}$$

That is, we find two shortest curves from  $p$  to  $\exp_p(\alpha X)$ .

This contradicts to the assumption that  $\tau(X) > \alpha$ .

Therefore, our assumption is wrong, and we have  $\tau(X) \leq \alpha$ .

This means

$$\tau(X) \leq \liminf_{i \rightarrow \infty} \tau(X_i) \quad (2)$$

Combining (1) and (2), we ~~find~~ arrive at

$$\tau(X) = \lim_{i \rightarrow \infty} \tau(X_i) \quad \square$$

Therefore, by previous Remarks, we derive that  $E(p)$  is open in  $T_p M$ . And by [BSSG pp.11], we see  $\checkmark$  (B)

$\exp_p : E_p V \rightarrow \exp_p(E_p) = M \setminus C(p)$   
is a diffeomorphism!!

Conclusion: What is the cut locus of a point  $p$  in a complete Rie. mfd?

It is a closed subset  $C(p)$  of  $M$  such that, after "cutting the mfd along it,"  $M \setminus C(p)$  becomes a normal neighborhood!

On page 62+(10) (claim (A)) and page 62+(11) (claim (B)),  
We still need the following result: (comparing with  
Theorem 1):

Theorem 4: Let  $(M^n, g)$  be complete, and  $p \in M$ .

~~Then~~ If  $d\exp_p$  is singular at  $\alpha X \in T_p M$ ,  $X \in S_p$ ,

Then  $\alpha \geq \tau(X)$ . Equivalently to say, if  $\alpha < \tau(X)$ ,  
then  $d\exp_p$  is nonsingular at  $\alpha X \in T_p M$ .