

LECTURE 19: THE THEOREMS OF BONNET-MYERS, SYNGE AND PREISSMAN

1. BONNET-MYERS THEOREM

Now let's turn to Riemannian manifolds with positive curvature.

Theorem 1.1 (Bonnet-Myers). *Let (M, g) be a complete Riemannian manifold whose Ricci curvature satisfies*

$$\text{Ric}(X_p) \geq (m - 1)\kappa$$

for all $X_p \in SM$, where κ is a positive constant independent of X_p . Then M is compact, and its diameter is bounded by

$$\text{diam}(M) := \sup_{p, q \in M} \text{dist}(p, q) \leq \frac{\pi}{\sqrt{\kappa}}.$$

Proof. For any $p, q \in M$, let $\gamma : [0, 1] \rightarrow M$ be a minimal geodesic joining p to q . Obviously it's enough to show $L(\gamma) \leq \frac{\pi}{\sqrt{\kappa}}$. Suppose on the contrary that

$$L(\gamma) = l > \frac{\pi}{\sqrt{\kappa}}.$$

Let $\{e_i(t)\}$ be parallel vector fields along γ which form an orthonormal basis at each point $\gamma(t)$ and so that $e_1(t) = \frac{\dot{\gamma}(t)}{l}$. For $j = 2, \dots, m$, we define

$$V_j(t) = \sin(\pi t)e_j(t).$$

Then $V_j(0) = V_j(1) = 0$, and

$$I(V_j, V_j) = - \int_0^1 \langle V_j, \nabla_{\dot{\gamma}} \nabla_{\dot{\gamma}} V_j + R(\dot{\gamma}, V_j)\dot{\gamma} \rangle dt = \int_0^1 \sin^2(\pi t)(\pi^2 - l^2 R(e_1, e_j, e_1, e_j)) dt.$$

Summing over j , we get

$$\sum_{j=2}^m I(V_j, V_j) = \int_0^1 \sin^2(\pi t)((m - 1)\pi^2 - l^2 \text{Ric}(e_1)) dt < 0.$$

So there exists some $j \geq 2$ so that

$$I(V_j, V_j) < 0.$$

It follows that there exists $\bar{q} = \gamma(t_0)$ with $0 < t_0 < 1$ which is conjugate to p along γ . In particular, γ is not shortest. A contradiction. \square

Remarks. (1) One cannot weaken the condition on Ricci curvature to $Ric > 0$ or even $K > 0$. For example, consider the paraboloid

$$\{(x, y, z) \in \mathbb{R}^3 \mid z = x^2 + y^2\}.$$

It is a surface of revolution with $K > 0$, which is not compact.

(2) The estimate is optimal in the following sense: Let M be the standard sphere of radius $\frac{1}{\sqrt{\kappa}}$, then it has Ricci curvature $(m-1)\kappa$ and diameter $\frac{\pi}{\sqrt{\kappa}}$. (Note: the diameter here is not the standard diameter as a subset in \mathbb{R}^n .)

(3) We will prove the following result of S. Y. Cheng later: If (M, g) satisfies the conditions of the Bonnet-Myers theorem and $\text{diam}(M) = \frac{\pi}{\sqrt{\kappa}}$, then (M, g) is isometric to the standard sphere of radius $\frac{1}{\sqrt{\kappa}}$.

Corollary 1.2. *Let (M, g) be a complete Riemannian manifold whose Ricci curvature is bounded below by a positive number. Then $\pi_1(M)$ is finite.*

Proof. Let \overline{M} be the universal covering of M , endowed with the pull-back metric $\overline{g} = \pi^*g$. Then $(\overline{M}, \overline{g})$ is also a complete Riemannian manifold whose Ricci curvature is bounded below by a positive number. By Bonnet-Myers theorem, \overline{M} is compact. As a consequence, $\pi : \overline{M} \rightarrow M$ has to be a finite covering. So $\pi_1(M)$ is finite. \square

In particular, we see that if M, N are compact, $\pi_1(M)$ is infinite, then $M \times N$ admits no Riemannian metric of positive Ricci curvature.

2. SYNGE'S THEOREM

Another application of the second variation formula to Riemannian manifolds with positive curvature is

Theorem 2.1 (Synge). *Let (M, g) be a compact Riemannian manifold with positive sectional curvature.*

- (1) *If M is even dimensional and orientable, then M is simply connected.*
- (2) *If M is odd dimensional, then M is orientable.*

Before proving the theorem, we need two lemmas:

Lemma 2.2. *Let (M, g) be a compact Riemannian manifold. Then for any nontrivial free homotopy class \mathcal{C} , there exists a closed geodesic γ whose length is minimal in \mathcal{C} .*

Proof. As an exercise. (See more details in PSet 3.) \square

Lemma 2.3. *Let (M, g) be an orientable Riemannian manifold, and $\gamma : [a, b] \rightarrow M$ be a closed curve, i.e. $\gamma(a) = \gamma(b) := p$. Then the parallel transport $P_{a,b}^\gamma : T_p M \rightarrow T_p M$ has determinant 1.*

Proof. In lecture 10 we have already seen that $P_{a,b}^\gamma \in O(T_p M)$. So it is enough to show $\det P_{a,b}^\gamma > 0$. To prove this, we take a *positive* m -form ω on M , and let $\{e_i\}$ be a *positive* basis of $T_p M$, i.e.

$$\omega(e_1, \dots, e_m) > 0.$$

Let $e_j(t) = P_{a,t}^\gamma(e_j)$ be the parallel transport of $\{e_i\}$ along γ . Then

$$\omega(e_1(t), \dots, e_m(t)) \neq 0$$

for all t . It follows that

$$\omega(e_1(b), \dots, e_m(b)) > 0.$$

But

$$\omega(e_1(b), \dots, e_m(b)) = (\det P_{a,b}^\gamma) \omega(e_1, \dots, e_m),$$

so we must have $\det P_{a,b}^\gamma > 0$. \square

Proof of Synge's Theorem. (1) Suppose M is not simply connected. Then there exists a nontrivial closed geodesic $\gamma : [0, 1] \rightarrow M$ which is minimum in its free homotopy class. Since the parallel transport $P_{0,1}^\gamma \in SO(T_p M)$ and satisfies

$$P_{0,1}^\gamma(\dot{\gamma}(0)) = \dot{\gamma}(0),$$

we can find $X_p \in E_p$ such that

$$P_{0,1}^\gamma(X_p) = X_p,$$

where E_p is the orthogonal complement of $\dot{\gamma}(0)$ in $T_p M$. (Here, we used the condition that $\dim M$ is even, so that $\dim E$ is odd!)

Now let $X(t)$ be the parallel vector field along γ with $X(0) = X_p$. Then

$$X(1) = P_{0,1}^\gamma(X_p) = X_p.$$

Thus for the variation γ_s of γ whose variation field is X , we have

$$\frac{d^2}{dt^2} \Big|_{t=0} E(\gamma_s) = - \int_0^1 \langle X, \nabla_{\dot{\gamma}} \nabla_{\dot{\gamma}} X + R(\dot{\gamma}, X) \dot{\gamma} \rangle dt = - \int_0^1 R(\dot{\gamma}, X, \dot{\gamma}, X) dt < 0.$$

This contradicts with the fact that γ is minimum in its homotopy class.

(2) Suppose M is not orientable, then there is a nontrivial free homotopy class \mathcal{C} so that for any closed curve $\gamma : [0, 1] \rightarrow M$ in \mathcal{C} , $\det P_{0,1}^\gamma = -1$. [Prove this!] We will take γ to be the one with minimal length in this class. Since $P_{0,1}^\gamma(\dot{\gamma}(0)) = \dot{\gamma}(0)$, we see

$$\det P_{0,1}^\gamma|_E = -1,$$

where $E = (\dot{\gamma}(0))^\perp$ is the orthogonal complement of $\dot{\gamma}(0)$ in $T_p M$. Since E is even dimensional, again we conclude that there exists $X_p \in E$ so that

$$P_{0,1}^\gamma(X_p) = X_p.$$

Now by the same argument of the proof of Synge theorem we conclude that γ is not minimum in its homotopy class, a contradiction. \square

Corollary 2.4. *If (M, g) is a compact even dimensional Riemannian manifold of positive sectional curvature, and M is not orientable, then $\pi_1(M) = \mathbb{Z}_2$.*

Proof. Let \overline{M} be the orientable double covering of M , endowed with the induced pull-back metric. Then \overline{M} is orientable and satisfies all the conditions in Syngé theorem. It follows that \overline{M} is simply connected and thus $\pi_1(M) = \mathbb{Z}_2$. \square

As a consequence, $\mathbb{RP}^2 \times \mathbb{RP}^2$ admits no metric of positive sectional curvature since $\pi_1(\mathbb{RP}^2 \times \mathbb{RP}^2) = (\mathbb{Z}/2)^2$. Recall that it is still unknown whether $S^2 \times S^2$ admits a positive sectional curvature metric: that is the Hopf's conjecture.

Remark. In the odd dimensional case we cannot say too much of its fundamental group. In fact, it is well-known that S^{2n+1} can be the universal covering space of a lot of spaces of constant curvature 1.

3. PREISSMAN'S THEOREM

We can also study the fundamental group of negative curved manifolds.

Theorem 3.1 (Preissman). *Let (M, g) be a compact Riemannian manifold with negative sectional curvature, and let $\{1\} \neq H \subset \pi_1(M)$ be a nontrivial abelian subgroup of the fundamental group. Then H is infinite cyclic.*

Remarks. (1) Recall: a cyclic group is a group generated by one element.

(2) As an immediate consequence, we see that manifolds like T^m , \mathbb{RP}^m admits no metric of negative sectional curvature.

(3) The theorem was strengthened by Myers to: Under the same assumption, any nontrivial solvable subgroup of $\pi_1(M)$ is infinite cyclic.

(4) For any closed surface M_g of genus $g \geq 2$, there is Riemannian metric of constant negative sectional curvature. [We mentioned this in lecture 9]. The fundamental group of M_g is

$$\langle a_1, b_1, \dots, a_g, b_g \mid a_1 b_1 a_1^{-1} b_1^{-1} \cdots a_g b_g a_g^{-1} b_g^{-1} = e \rangle.$$

This group is not abelian, while all its abelian subgroups are isomorphic to \mathbb{Z} .

Before we prove the theorem, we need some preparations.

Definition 3.2. Let (M, g) be a complete simply-connected Riemannian manifold, and $\gamma : \mathbb{R} \rightarrow M$ a geodesic. An isometry $f : M \rightarrow M$ is called a *translation* along γ if f has no fixed point, and $f(\gamma) = \gamma$.

Let (M, g) be any complete Riemannian manifold and $\pi : \widetilde{M} \rightarrow M$ be the universal covering. We endow with \widetilde{M} the pull back metric π^*g . Recall that for each element $\alpha \in \pi_1(M)$, one can define a deck transformation $f_\alpha : \widetilde{M} \rightarrow \widetilde{M}$ as follows: for each $\tilde{p} \in \widetilde{M}$, there is a loop γ based at $p = \pi(\tilde{p})$ whose homotopy class is α . Let $\tilde{\gamma}$ be the lift of γ with starting point \tilde{p} . Define $f_\alpha(\tilde{p})$ be the endpoint of $\tilde{\gamma}$.

One can prove that f_α is well-defined, is an isometry, and $f_\beta \circ f_\alpha = f_{\beta\alpha}$. Moreover, f_α has no fixed point if $\alpha \neq e$. Let Γ be the group of all deck transformations, then it is isomorphic to $\pi_1(M)$.

Now suppose $0 \neq \alpha \in \pi_1(M)$, and let γ be a minimal closed geodesic in the homotopy class α . Let $\tilde{\gamma}$ be a lift of γ to \tilde{M} .

Lemma 3.3. $f_\alpha : (\tilde{M}, \tilde{g}) \rightarrow (\tilde{M}, \tilde{g})$ is a translation along $\tilde{\gamma}$.

Proof. Exercise. □

Another lemma that is needed in the proof is

Lemma 3.4. Let (M, g) be a complete simply connected Riemannian manifold of non-positive sectional curvature. Consider the geodesic triangle with vertices $p_1, p_2, p_3 \in M$. Let a, b, c be the lengths of sides and A, B, C be the corresponding opposite angles. Then

- (1) $a^2 + b^2 - 2ab \cos C \leq c^2$.
- (2) $A + B + C \leq \pi$.

Further more, if the sectional curvature is negative, then these inequalities are strict.

Proof. We will prove this later. □

As a consequence of this lemma, we have

Corollary 3.5. Suppose (M, g) has negative sectional curvature, then any translation $f : \tilde{M} \rightarrow \tilde{M}$ fixes only one geodesic.

Proof. Suppose there are two geodesics $\tilde{\gamma}_1$ and $\tilde{\gamma}_2$ in \tilde{M} such that $f(\tilde{\gamma}_i) = \tilde{\gamma}_i$. First we claim that $\tilde{\gamma}_1 \cap \tilde{\gamma}_2 = \emptyset$. Otherwise there are at least two points in $\tilde{\gamma}_1 \cap \tilde{\gamma}_2$ (since f has no fixed point). This contradicts with the fact that $\exp_{\tilde{p}}$ is a diffeomorphism for each $\tilde{p} \in \tilde{M}$.

Now choose $\tilde{p}_i \in \tilde{\gamma}_i$, and let $\tilde{\gamma}_3$ be minimizing geodesic connecting \tilde{p}_1 and \tilde{p}_2 . Consider the “geodesic quadrilateral” with vertices $\tilde{p}_1, \tilde{p}_2, f(\tilde{p}_1), f(\tilde{p}_2)$. Since f is an isometry, one see that the angle at \tilde{p}_1 and the angle at $f(\tilde{p}_1)$ add up to π . Similarly the angle at \tilde{p}_2 and the angle at $f(\tilde{p}_2)$ add up to π . On the other hand, one can split the “geodesic quadrilateral” to two “geodesic triangles” by connecting \tilde{p}_2 and $f(\tilde{p}_1)$. As a consequence, the inner angles of the two “geodesic triangles” add up to at least 2π . [Why “at least”? Think about this!] This contradicts with the lemma above. □

Proof of Preissman’s theorem.

As above we denote by \tilde{M} the universal covering of M , and f_α the deck transformation described above associated to $\alpha \in \pi_1(M)$.

First fix $\alpha \in H$ and let $\tilde{\gamma}$ be the geodesic that is invariant under f_α . Then for any $\beta \in H$, one has $f_{\beta\alpha} = f_{\alpha\beta}$ since H is abelian. So

$$f_\beta(\tilde{\gamma}) = f_\beta(f_\alpha(\tilde{\gamma})) = f_\alpha(f_\beta(\tilde{\gamma})).$$

By the corollary above, one must have

$$f_\beta(\tilde{\gamma}) = \tilde{\gamma}, \quad \forall \beta \in H.$$

As a consequence, $\tilde{\gamma}$ is invariant under all f_α 's for $\alpha \in H$.

Now we denote $\tilde{p}_0 = \tilde{\gamma}(0)$. Since $\tilde{\gamma}$ is invariant under f_β , for each $\beta \in H$, there is a unique $t_\beta \in \mathbb{R}$ so that

$$\tilde{\gamma}(t_\beta) = f_\beta(\tilde{p}_0).$$

Note that this implies

$$\tilde{\gamma}(t_\beta + t) = f_\beta(\tilde{\gamma}(t))$$

for any t , since as t varies, both sides are geodesics with the same initial condition.

Now we define a map $\varphi : H \rightarrow \mathbb{R}$ by

$$\varphi(\beta) = t_\beta$$

Claim 1: φ is a group homomorphism:

For any $\beta_1, \beta_2 \in H$,

$$\tilde{\gamma}(t_{\beta_1} + t_{\beta_2}) = f_{\beta_1} \circ f_{\beta_2}(\tilde{p}_0) = f_{\beta_1\beta_2}(\tilde{p}_0) = \tilde{\gamma}(t_{\beta_1\beta_2}).$$

So we have $\varphi(\beta_1\beta_2) = t_{\beta_1\beta_2} = t_{\beta_1} + t_{\beta_2}$.

Claim 2: φ is injective:

Suppose $\varphi(\beta_1) = \varphi(\beta_2)$, i.e. $t_{\beta_1} = t_{\beta_2}$. Then by definition

$$f_{\beta_1}(\tilde{p}_0) = f_{\beta_2}(\tilde{p}_0).$$

So \tilde{p}_0 is a fixed point of $f_{\beta_1}^{-1} \circ f_{\beta_2} = f_{\beta_1^{-1}\beta_2}$. This can happen only if $\beta_1^{-1}\beta_2 = e$, i.e. $\beta_1 = \beta_2$.

Claim 3: The image of φ is not dense in \mathbb{R} .

Pick a neighborhood U of $p = \pi(\tilde{p}_0)$ so that $\pi^{-1}(U) = \cup_\delta U_\delta$, where each U_δ is diffeomorphic to U under π and they are disjoint. By shrinking U one may assume that U is a normal ball of radius r around p . Denote U_0 be the one so that $\tilde{p}_0 \in U_0$. Then for each $\beta \neq e$, $f_\beta(\tilde{p}_0) \notin U_0$. So we see

$$|t_\beta| = d(\tilde{p}_0, f_\beta(\tilde{p}_0)) \geq r$$

for any $\beta \neq e$.

As a consequence of the first two claims, H is an additive subgroup of \mathbb{R} . But we know that any additive subgroup of \mathbb{R} is either dense or infinite cyclic. So the theorem is proved. \square