## LECTURE 4: PARTITION OF UNITY

## 1. Existence of P.O.U.

We will prove the following fundamental theorem:

**Theorem 1.1** (Existence of P.O.U.). Let M be a smooth manifold, and  $\{U_{\alpha}\}$  an open cover of M. Then there exists a P.O.U. subordinate to  $\{U_{\alpha}\}$ .

In other words, we need to find a family  $\{\rho_{\alpha}\}\$  of smooth functions so that

- (1)  $0 \le \rho_{\alpha} \le 1$  for all  $\alpha$ .
- (2) supp $(\rho_{\alpha}) \subset U_{\alpha}$  for all  $\alpha$ .
- (3) each point  $p \in M$  has a neighborhood which intersects supp $(\rho_{\alpha})$  for only finitely many  $\alpha$ .
- (4)  $\sum_{\alpha} \rho_{\alpha}(p) = 1$  for all  $p \in M$ .

The proof depends on the following technical lemma.

**Lemma 1.2.** Let M be any topological manifold. For any open cover  $\mathcal{U} = \{U_{\alpha}\}$  of M, one can find two countable family of open covers  $\mathcal{V} = \{V_j\}$  and  $\mathcal{W} = \{W_j\}$  of M so that

- For each j,  $\overline{V}_j$  is compact and  $\overline{V}_j \subset W_j$ .
- W is a refinement of U: For each j, there is an  $\alpha = \alpha(j)$  so that  $W_j \subset U_\alpha$ .
- W is a locally finite cover: Any  $p \in M$  has a neighborhood W such that  $W \cap W_i \neq \emptyset$  for only finitely many  $W_i$ 's.

Remark. A topological space X is called paracompact if every open cover admits a locally finite open refinement.

We will first prove Theorem 1.1, then prove Lemma 1.2.

Proof of Theorem 1.1. [Please compare the first paragraph of this proof with the proof of Theorem 1.2 in Lecture 3.] Since  $\overline{V}_j$  is compact and  $\overline{V}_j \subset W_j$ , according to Theorem 1.2 in Lecture 3 we can find nonnegative functions  $\varphi_j \in C_0^{\infty}(M)$  so that  $0 \leq \varphi_j \leq 1$ ,  $\varphi_j \equiv 1$  on  $\overline{V}_j$  and  $\sup(\varphi_j) \subset W_j$ . Since  $\mathcal{W}$  is a locally finite cover, the function

$$\varphi = \sum_{j} \varphi_{j}$$

is a well-defined smooth function on M. Since each  $\varphi_j$  is nonnegative, and  $\mathcal{V}$  is a cover of M,  $\varphi$  is strictly positive on M. It follows that the functions

$$\psi_j = \frac{\varphi_j}{\varphi}$$

are smooth and satisfy  $0 \le \psi_j \le 1$  and  $\sum_j \psi_j = 1$ .

Next let's re-index the family  $\{\psi_j\}$  to get the demanded P.O.U. For each j, we fix an index  $\alpha(j)$  so that  $W_j \subset U_{\alpha(j)}$ , and define

$$\rho_{\alpha} = \sum_{\alpha(j)=\alpha} \psi_j.$$

Note that the right hand side is a finite sum near each point, so it does define a smooth function. According to Problem Set 1 part 2 problem 4,

$$\operatorname{supp} \rho_{\alpha} = \overline{\bigcup_{\alpha(j)=\alpha}} \operatorname{supp} \psi_j = \bigcup_{\alpha(j)=\alpha} \overline{\operatorname{supp} \psi_j} \subset U_{\alpha}.$$

Clearly the family  $\{\rho_{\alpha}\}$  is a P.O.U. subordinate to  $\{U_{\alpha}\}$ .

It remains to prove Lemma 1.2. In particular, we want to prove the existence of locally finite open refinement. The proof is quite geometric:

First we prove

**Lemma 1.3.** For any topological manifold M, there exists a countable collection of open sets  $\{X_i\}$  so that

- (1) For each j, the closure  $\overline{X}_j$  is compact.
- (2) For each j,  $\overline{X}_i \subset X_{i+1}$ .
- (3)  $M = \bigcup_j X_j$ .

*Proof.* Since M is second countable, there is a countable basis of the topology of M. Out of this countable collection of open sets, we pick those that have compact closures, and denote them by  $Y_1, Y_2, \cdots$ . Since M is locally Euclidean, it is easy to see that  $\mathcal{Y} = \{Y_j\}$  is an open cover of M.

We let  $X_1 = Y_1$ . Since  $\mathcal{Y}$  is an open cover of  $\overline{X}_1$  which is compact, there exist finitely many open sets  $Y_{i_1}, \dots, Y_{i_k}$  so that

$$\overline{X}_1 \subset Y_{i_1} \cup \cdots \cup Y_{i_k}$$
.

Let

$$X_2 = Y_2 \cup Y_{i_1} \cup \cdots \cup Y_{i_k}.$$

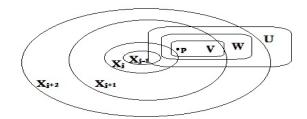
Obviously  $\overline{X}_2$  is compact. Repeat this procedure again and again, we could get a sequence of open sets  $X_1, X_2, X_3, \cdots$ . Obviously the sequence satisfies (1) and (2). It satisfies (3) since  $X_k \supset \bigcup_{i=1}^k Y_i$ 

Remark. Such a collection of subsets is called an exhaustion of M.

Proof of Lemma 1.2. For each  $p \in M$ , there is an j and an  $\alpha(p)$  so that  $p \in \overline{X}_{j+1} \setminus X_j$  and  $p \in U_{\alpha(p)}$ . Since M is locally Euclidean, one can always choose open neighborhoods  $V_p, W_p$  of p so that  $\overline{V}_p$  is compact and

$$\overline{V}_p \subset W_p \subset U_{\alpha(p)} \cap (X_{j+2} \setminus \overline{X}_{j-1}).$$

Now for each j, since the "stripe"  $\overline{X}_{j+1} \setminus X_j$  is compact, one can choose finitely many points  $p_1^j, \dots, p_{k_j}^j$  so that  $V_{p_1^j}, \dots, V_{p_{k_j}^j}$  is an open cover of  $\overline{X}_{j+1} \setminus X_j$ . Denote all



these  $V_{p_k^j}$ 's by  $V_1, V_2, \dots$ , and the corresponding  $W_{p_k^j}$ 's by  $W_1, W_2, \dots$ . Then  $\mathcal{V} = \{V_k\}$  and  $\mathcal{W} = \{W_k\}$  are open covers of M that satisfies all the conditions in Lemma 1.2. For example, the local finiteness property of  $\mathcal{W}$  follows from the fact that there are only finitely many  $W_k$ 's (that correspond to j and j-1 above) intersect  $X_{j+1} \setminus \overline{X}_{j-1}$ .  $\square$ 

We end with two questions:

- Where did we use the second countable condition in proving P.O.U.?
- Where did we use the Hausdorff condition in proving P.O.U.?

## 2. An application: Whitney Approximation Theorem

As another application of P.O.U., we prove the following

**Theorem 2.1** (Whitney Approximation Theorem). Let M be a smooth manifold. Then for any continuous function  $g: M \to \mathbb{R}$  and any positive continuous function  $\delta: M \to \mathbb{R}_{>0}$ , there exists a smooth function  $f: M \to \mathbb{R}$  so that  $|f(p) - g(p)| < \delta(p)$  holds for all  $p \in M$ .

In fact we will prove a stronger version of this theorem. Let  $A \subset M$  be any closed set. We say a function  $g: M \to \mathbb{R}$  is *smooth on* A if there exists an open set  $U \supset A$  and a smooth function  $g_0$  defined on U so that  $g_0 = g$  on A. [As a consequence, any function g is smooth on any single point set  $\{p\}$ , although it may not be smooth at g.]

**Theorem 2.2** (Whitney Approximation Theorem). Let M be a smooth manifold, and  $A \subset M$  a closed subset. Then for any continuous function  $g: M \to \mathbb{R}$  which is smooth on A and any positive continuous function  $\delta: M \to \mathbb{R}_{>0}$ , there exists  $f \in C^{\infty}(M)$  so that

$$f(p) = g(p), \quad \forall p \in A$$

and

$$|f(p) - g(p)| < \delta(p), \quad \forall p \in M.$$

By taking  $A = \emptyset$  we see that Theorem 2.2 implies Theorem 2.1

*Proof.* [The idea: approximate g by  $g_0$  near A, and approximate g by constant functions elsewhere.] By definition, there exists an open set  $U \supset A$  and a smooth function  $g_0$  defined on U so that  $g_0 = g$  on A. Let

$$U_0 = \{ p \in U : |g_0(p) - g(p)| < \delta(p) \}.$$

Then  $U_0$  is open in M and  $U_0 \supset A$ .

Next we construct a (nice) open cover of  $M \setminus A$ . For any  $q \in M \setminus A$ , we let

$$U_q = \{ p \in M \setminus A : |g(p) - g(q)| < \delta(p) \}.$$

Then  $\{U_q \mid q \in M \setminus A\}$  is an open covering of  $M \setminus A$ .

Now let  $\{\rho_0, \rho_q : q \in M\}$  be P.O.U. subordinate to the open cover  $\{U_0, U_q : q \in M\}$  of M, and define a function on M via

$$f(p) = \rho_0(p)g_0(p) + \sum_{q \in M} \rho_q(p)g(q).$$

Since the summation is locally finite, f is smooth. Also by definition,  $f = g_0 = g$  on A. Moreover, for any  $g \in M$  one has

$$|f(p) - g(p)| = \left| \rho_0(p)g_0(p) + \sum_q \rho_q(p)g(q) - \rho_0(p)g(p) - \sum_q \rho_q(p)g(p) \right|$$

$$\leq \rho_0(p)|g_0(p) - g(p)| + \sum_q \rho_q(p)|g(q) - g(p)|$$

$$< \rho_0(p)\delta(p) + \sum_q \rho_q(p)\delta(p)$$

$$= \delta(p),$$

where in the last inequality, the fact  $\rho_0(p)|g_0(p) - g(p)| < \rho_0(p)\delta(p)$  follows from the facts that if  $p \in U_0$ , then by definition  $|g_0(p) - g(p)| < \delta(p)$ , while if  $p \notin U_0$ , then  $\rho_0(p)=0$ ; the fact  $\rho_q(p)|g(q) - g(p)| < \rho_q(p)\delta(p)$  follows from a similar argument.  $\square$