

## LECTURE 25: THE DE RHAM COHOMOLOGY

### 1. THE DE RHAM COHOMOLOGY

#### ¶ Closed and exact forms.

We start with the following definition:

**Definition 1.1.** Let  $M$  be a smooth manifold, and  $\omega \in \Omega^k(M)$  is a  $k$ -form.

- (1) We say  $\omega$  is *closed* if  $d\omega = 0$ .
- (2) We say  $\omega$  is *exact* if there exists a  $(k-1)$ -form  $\eta \in \Omega^{k-1}(M)$  such that  $\omega = d\eta$ .

Denote the set of closed  $k$ -forms by  $Z^k(M)$ , and the set of exact  $k$ -forms by  $B^k(M)$ :

$$Z^k(M) = \text{the set of closed } k\text{-forms} = \ker(d : \Omega^k(M) \rightarrow \Omega^{k+1}(M)),$$

$$B^k(M) = \text{the set of exact } k\text{-forms} = \text{Im}(d : \Omega^{k-1}(M) \rightarrow \Omega^k(M)).$$

As we have seen, the exterior derivative  $d : \Omega^k(M) \rightarrow \Omega^{k+1}(M)$  is a linear map so that for any  $k$  and any  $\omega \in \Omega^k(M)$ ,

$$d^2\omega = d(d\omega) = 0.$$

So we have the following inclusion relation (as vector spaces and as additive groups)

$$B^k(M) \subset Z^k(M) \subset \Omega^k(M).$$

*Remark.* Suppose  $\dim M = m$ . Then by definition we have

- For  $k > m$ :  $B^k(M) = Z^k(M) = \{0\}$ .
- For  $k = 0$ :  $B^0(M) = \{0\}$ , and

$$Z^0(M) = \{f \in C^\infty(M) \mid df = 0\} \simeq \mathbb{R}^K.$$

where  $K$  is the number of connected components of  $M$ .

- For  $k = m$ :  $Z^m(M) = \Omega^m(M)$ .

*Example.* Consider  $M = \mathbb{R}$ . We have

$$B^0(\mathbb{R}) = \{0\}, \quad Z^0(\mathbb{R}) \simeq \mathbb{R} \quad \text{and} \quad \Omega^0(\mathbb{R}) = C^\infty(\mathbb{R}).$$

For any 1-form  $g(t)dt$  on  $\mathbb{R}$ , we have

$$\omega = g(t)dt \iff \omega = dG, \text{ where } G(t) = \int_0^t g(\tau)d\tau.$$

It follows that  $\Omega^1(\mathbb{R}) = B^1(\mathbb{R}) = Z^1(\mathbb{R})$ .

¶ **The De Rham cohomology groups.**

Since  $d^2 = 0$ , we get the following *de Rham cochain complex*

$$0 \xrightarrow{d} \Omega^0(M) \xrightarrow{d} \Omega^1(M) \xrightarrow{d} \cdots \xrightarrow{d} \Omega^m(M) \xrightarrow{d} 0.$$

(Such a sequence of vector spaces [could be an infinite sequence] connected by a sequence of linear maps, such that the composition of any two consecutive maps is the zero map, is called a *chain complex* or a *cochain complex*, depending on the “direction” of the maps.)

**Definition 1.2.** The quotient group (vector space)

$$H_{dR}^k(M) := Z^k(M)/B^k(M)$$

is called the  $k^{\text{th}}$  *de Rham cohomology group* of  $M$ .

*Example.* For  $M = \mathbb{R}$ , we easily see  $H_{dR}^0(\mathbb{R}) \simeq \mathbb{R}$  and  $H_{dR}^k(\mathbb{R}) = \{0\}$  for  $k \geq 1$ .

Given any  $\omega \in Z^k(M)$ , we will denote by  $[\omega]$  the corresponding *cohomology class*.

*Remark.* Suppose  $\dim M = m$ . According to the above remark, we get

$$H_{dR}^k(M) = \{0\}, \quad \forall k > m$$

and (we still denote by  $K$  the number of connected components of  $M$ )

$$H_{dR}^0(M) \simeq \mathbb{R}^K.$$

By definition,  $H_{dR}^k(M)$  is a vector space. We will see that for many smooth manifolds (including all compact manifolds),

$$\dim H_{dR}^k(M) < \infty$$

for all  $k$ . On the other hand, we have  $\dim H_{dR}^0(\mathbb{Z}) = \infty$ . (As another example: it is not hard to prove  $\dim H_{dR}^1(\mathbb{R}^2 \setminus \mathbb{Z}^2) = +\infty$ .)

**Definition 1.3.** In the case  $\dim H_{dR}^k(M) < \infty$  for each  $k$ , we will call the number

$$b_k(M) = \dim H_{dR}^k(M)$$

the  $k^{\text{th}}$  *Betti number* of  $M$ , and the number

$$\chi(M) = \sum_{k=0}^m (-1)^k b_k(M)$$

the *Euler characteristic* of  $M$ .

¶ **The De Rham cohomology groups of  $S^1$ .**

Consider  $M = S^1$ . As we have seen,

$$H_{dR}^0(S^1) \simeq \mathbb{R} \quad \text{and} \quad H_{dR}^k(S^1) = 0 \quad \text{for } k \geq 2.$$

To calculate  $H_{dR}^1(S^1)$ , we argue as in the previous example. Note that on  $S^1 = \mathbb{R}/2\pi\mathbb{Z}$ , the “angle” variable  $\theta$  is not a globally defined smooth function on  $S^1$ , but the translation invariance of  $d$  on  $\mathbb{R}$  implies that the differential form  $d\theta$  is a globally defined 1-form on  $S^1$ . (As a consequence, the 1-form  $d\theta$  is a closed 1-form on  $S^1$ , but

is NOT an exact 1-form on  $S^1$ . However, it is an exact 1-form on any proper subset of  $S^1$ .) So we can write

$$\begin{aligned} Z^1(S^1) &= \Omega^1(S^1) = \{f d\theta \mid f \in C^\infty(S^1)\} \\ &\simeq \{f \in C^\infty(\mathbb{R}) \mid f \text{ is periodic with period } 2\pi\}. \end{aligned}$$

On the other hand, by the fundamental theorem of calculus,

$\omega$  is an exact 1-form

$$\iff \omega = df, \text{ where } f \text{ is periodic with period } 2\pi$$

$$\iff \omega = g(\theta)d\theta, \text{ where } g \text{ is periodic with period } 2\pi \text{ and } \int_0^{2\pi} g(\theta)d\theta = 0.$$

So we conclude

$$H_{dR}^1(S^1) \simeq \frac{\{f \in C^\infty(\mathbb{R}) \mid f \text{ is periodic with period } 2\pi\}}{\{g \in C^\infty(\mathbb{R}) \mid g \text{ is periodic with period } 2\pi, \text{ and } \int_0^{2\pi} g(\theta)d\theta = 0\}}.$$

This implies that

$$H_{dR}^1(S^1) \simeq \mathbb{R},$$

since the linear map

$$\varphi : H_{dR}^1(S^1) \rightarrow \mathbb{R}, \quad [f] \mapsto \int_0^{2\pi} f(\theta)d\theta.$$

is an linear isomorphism:

- $\varphi$  is well-defined:

$$[f_1] = [f] \implies f_1 - f \in B^1(S^1) \implies \int_0^{2\pi} f_1(\theta)d\theta = \int_0^{2\pi} f(\theta)d\theta.$$

- $\varphi$  is injective:

$$[f_1] \neq [f] \implies f_1 - f \notin B^1(S^1) \implies \int_0^{2\pi} f_1(\theta)d\theta \neq \int_0^{2\pi} f(\theta)d\theta.$$

- $\varphi$  is surjective: for any  $c \in \mathbb{R}$ ,

$$f(\theta) := c \in Z^1(S^1) \implies \varphi([f]) = \int_0^{2\pi} f(\theta)d\theta = 2\pi c.$$

### ¶ Operations on cohomology classes.

One can extend the wedge product and pull-back operations on differential forms to operations on cohomology classes.

First let  $\omega \in Z^k(M)$  and  $\eta \in Z^l(M)$ , then

$$d(\omega \wedge \eta) = d\omega \wedge \eta + (-1)^k \omega \wedge d\eta = 0,$$

i.e.  $\omega \wedge \eta \in Z^{k+l}(M)$ . Moreover, for any  $\xi_1 \in \Omega^{k-1}(M)$  and  $\xi_2 \in \Omega^{l-1}(M)$ ,

$$(\omega + d\xi_1) \wedge (\eta + d\xi_2) = \omega \wedge \eta + d[(-1)^k \omega \wedge \xi_2 + (-1)^{k-1} \xi_1 \wedge \eta + (-1)^{k-1} \xi_1 \wedge d\xi_2].$$

In other words,  $[\omega \wedge \eta]$  is independent of the choice of  $\omega$  and  $\eta$  in  $[\omega]$  and  $[\eta]$ . So we can define

**Definition 1.4.** The *cup product* between  $[\omega] \in H_{dR}^k(M)$  and  $[\eta] \in H_{dR}^l(M)$  is

$$[\omega] \cup [\eta] := [\omega \wedge \eta] \in H_{dR}^{k+l}(M).$$

Similarly suppose  $\varphi : M \rightarrow N$  is smooth. Then the fact  $d\varphi^* = \varphi^*d$  implies

$$\varphi^*(Z^k(N)) \subset Z^k(M) \quad \text{and} \quad \varphi^*(B^k(N)) \subset B^k(M).$$

It follows that  $\varphi^* : \Omega^k(N) \rightarrow \Omega^k(M)$  descends to a pull-back  $\varphi^* : H_{dR}^k(N) \rightarrow H_{dR}^k(M)$ :

$$\varphi^*([\omega]) := [\varphi^*\omega].$$

Obviously  $\varphi^*$  is a group homomorphism. It is easy to check

- $(\psi \circ \varphi)^* = \varphi^* \circ \psi^*$ .
- $\text{Id}^* = \text{Id}$ .

As an immediate consequence, we see that the de Rham cohomology groups are invariant under diffeomorphisms:

**Corollary 1.5** (Diffeomorphism Invariance). *If  $\varphi : M \rightarrow N$  is a diffeomorphism, then*

$$\varphi^* : H_{dR}^k(N) \rightarrow H_{dR}^k(M)$$

*is a linear isomorphism for all  $k$ . In particular,*

$$b_k(N) = b_k(M)$$

*for all  $k$ , and*

$$\chi(N) = \chi(M).$$

*Remark.* For any smooth map  $\varphi : M \rightarrow N$ , The cup product makes

$$H_{dR}^*(M) = \bigoplus_{k=0}^m H_{dR}^k(M)$$

a graded ring, and the induced map  $\varphi^*$  is in fact a ring homomorphism

$$\varphi^* : H_{dR}^*(N) \rightarrow H_{dR}^*(M),$$

since

$$\varphi^*(\alpha \wedge \beta) = \varphi^*\alpha \wedge \varphi^*\beta.$$

Moreover, if  $\varphi$  is a diffeomorphism, then  $\varphi^* : H_{dR}^*(N) \rightarrow H_{dR}^*(M)$  is a ring isomorphism.

## 2. HOMOTOPIC INVARIANCE

### ¶ Homotopic Invariance of de Rham cohomology.

In this section we shall prove a much stronger result: if two manifolds are homotopy equivalent, then they have the same de Rham cohomology groups. We first recall

**Definition 2.1.** Two topological spaces  $M$  and  $N$  are said to be *homotopy equivalent* if there exist continuous maps  $\varphi : M \rightarrow N$  and  $\psi : N \rightarrow M$  so that  $\varphi \circ \psi$  is homotopic to  $\text{Id}_N$  and  $\psi \circ \varphi$  is homotopic to  $\text{Id}_M$ .

In Lecture 11 we have shown

- any continuous map between smooth manifolds is homotopic to some smooth map.
- any two homotopic smooth maps are smoothly homotopic (i.e., the homotopy  $F$  can be chosen to be smooth if both  $f_0$  and  $f_1$  are smooth).

Homotopy equivalence is a much weaker equivalence relation than homeomorphism or diffeomorphism. For example (check details if you are not familiar with this)

- $S^{n-1}$  is homotopy equivalent to  $\mathbb{R}^n \setminus \{0\}$ .
- any star-shaped region is homotopy equivalent to a single point set  $\{x_0\}$ .

We would like to prove

**Theorem 2.2** (Homotopy Invariance). *Let  $M, N$  be smooth manifolds. If  $M$  and  $N$  are homotopy equivalent, then*

$$H_{dR}^k(M) \simeq H_{dR}^k(N), \quad \forall k.$$

Obviously the homotopy invariance implies the topological Invariance of de Rham cohomology groups:

If  $M$  is homeomorphic to  $N$ , then  $H_{dR}^k(M) \simeq H_{dR}^k(N)$  for all  $k$ .

*Remark.* Although in defining  $H_{dR}^k(M)$ , we need to use the smooth structure on  $M$  (to define the operator  $d$  and the space  $\Omega^k(M)$  etc), the topological invariance tells us that  $H_{dR}^k(M)$  only depends on the topology of  $M$ , and is independent of the smooth structure! In fact, for any topological space  $X$ , one can define its *singular cohomology groups*  $H_{sing}^k(X, \mathbb{R})$  which depends only on the topology (and in fact depends only on the homotopy class) of  $X$ . The famous theorem of de Rham claims

**Theorem 2.3** (The de Rham theorem).  $H_{dR}^k(M) = H_{sing}^k(M, \mathbb{R})$  for all  $k$ .

We will not prove the theorem in this course.

Another immediate consequence of the homotopy invariance is

**Corollary 2.4** (Poincaré's lemma). *If  $U$  is a star-shaped region in  $\mathbb{R}^m$ , then for any  $k \geq 1$ ,  $H_{dR}^k(U) = 0$ . In particular,*

$$H_{dR}^k(\mathbb{R}^m) = 0, \quad \forall k \geq 1.$$

Since any point in a manifold has a neighborhood that is homeomorphic to a star-like region in  $\mathbb{R}^n$ , we conclude that any closed form is locally exact:

**Corollary 2.5.** *Suppose  $k \geq 1$ . Then for any closed  $k$ -form  $\omega \in Z^k(M)$  and any  $p \in M$ , there is a neighborhood  $U$  of  $p$  and an  $(k-1)$ -form  $\eta \in \Omega^{k-1}(U)$  so that*

$$\omega = d\eta$$

on  $U$ .

¶ **Homotopic invariance of de Rham cohomology: The proof.**

The homotopy invariance is a consequence of

**Theorem 2.6.** *Let  $f, g \in C^\infty(M, N)$  be homotopic, then*

$$f^* = g^* : H_{dR}^k(N) \rightarrow H_{dR}^k(M).$$

*Proof of Theorem 2.2 assuming Theorem 2.6.* Let  $\varphi : M \rightarrow N$  and  $\psi : N \rightarrow M$  be continuous maps so that  $\varphi \circ \psi \sim \text{Id}_N$  and  $\psi \circ \varphi \sim \text{Id}_M$ . Then one can find  $\varphi_1 \in C^\infty(M, N)$  and  $\psi_1 \in C^\infty(N, M)$  so that  $\varphi_1 \sim \varphi$  and  $\psi_1 \sim \psi$ . It follows that both  $\varphi_1 \circ \psi_1$  and  $\psi_1 \circ \varphi_1$  are smooth, and  $\varphi_1 \circ \psi_1 \sim \text{Id}_N$ ,  $\psi_1 \circ \varphi_1 \sim \text{Id}_M$ .

Applying Theorem 2.6, we get

$$\varphi_1^* \circ \psi_1^* = \text{Id} : H_{dR}^k(M) \rightarrow H_{dR}^k(M)$$

$$\psi_1^* \circ \varphi_1^* = \text{Id} : H_{dR}^k(N) \rightarrow H_{dR}^k(N).$$

So  $\varphi^*$  and  $\psi^*$  are linear isomorphisms. □

Theorem 2.6 can be proved by constructing a *cochain homotopy*:

$$\begin{array}{ccccccc} \cdots & \xrightarrow{d} & \Omega^{k-1}(N) & \xrightarrow{d} & \Omega^k(N) & \xrightarrow{d} & \Omega^{k+1}(N) & \xrightarrow{d} & \cdots \\ & \nearrow h & \downarrow g^* \parallel f^* & \nwarrow h & \downarrow g^* \parallel f^* & \nwarrow h & \downarrow g^* \parallel f^* & \nwarrow h & \\ \cdots & \xrightarrow{d} & \Omega^{k-1}(M) & \xrightarrow{d} & \Omega^k(M) & \xrightarrow{d} & \Omega^{k+1}(M) & \xrightarrow{d} & \cdots \end{array}$$

**Definition 2.7.** Let  $f, g \in C^\infty(M, N)$  be homotopic. A *cochain homotopy* between  $f^*$  and  $g^*$  is a sequence of maps  $h_k : \Omega^k(N) \rightarrow \Omega^{k-1}(M)$  such that on  $\Omega^k(N)$ ,

$$g^* - f^* = d_M h_k + h_{k+1} d_N.$$

*Proof of Theorem 2.6 assuming the existence of the cochain homotopy*.

Suppose  $[\omega] \in H_{dR}^k(N)$ . Then  $d\omega = 0$  since  $\omega$  is closed. It follows

$$g^*\omega - f^*\omega = (dh + hd)\omega = dh\omega \in B^k(M)$$

Thus  $f^*([\omega]) = [f^*\omega] = [g^*\omega] = g^*([\omega])$ . □

¶ **The existence of cochain homotopy.**

It remains to construct the cochain homotopy. We will use the flow generated by a vector field to complete the construction. Recall that if  $X$  is a complete vector field on  $M$ , then  $X$  generates a flow  $\phi_t : M \rightarrow M$ . We need

**Lemma 2.8.** *Let  $X$  be a complete vector field on  $M$ , and  $\phi_t$  the flow generated by  $X$ . Then there is a linear operator  $Q : \Omega^k(M) \rightarrow \Omega^{k-1}(M)$  so that for any  $\omega \in \Omega^k(M)$ ,*

$$\phi_1^*\omega - \omega = dQ(\omega) + Q(d\omega).$$

*Proof.* If we set  $Q_t(\omega) = \iota_X(\phi_t^*\omega)$ , then  $Q_t : \Omega^k(M) \rightarrow \Omega^{k-1}(M)$  and

$$\begin{aligned} \frac{d}{dt}\phi_t^*\omega &= \frac{d}{ds}\Big|_{s=0} \phi_{t+s}^*\omega = \frac{d}{ds}\Big|_{s=0} \phi_s^*\phi_t^*\omega \\ &= \mathcal{L}_X(\phi_t^*\omega) = d\iota_X(\phi_t^*\omega) + \iota_X d(\phi_t^*\omega) \\ &= d(Q_t\omega) + \iota_X\phi_t^*(d\omega) = d(Q_t\omega) + Q_t(d\omega). \end{aligned}$$

So if we denote  $Q(\omega) = \int_0^1 Q_t(\omega)dt$ , then  $Q : \Omega^k(M) \rightarrow \Omega^{k-1}(M)$  and

$$\phi_1^*\omega - \omega = \int_0^1 \left( \frac{d}{dt}\phi_t^*\omega \right) dt = dQ(\omega) + Q(d\omega). \quad \square$$

*Construction of the cochain homotopy  $h_k : \Omega^k(N) \rightarrow \Omega^{k-1}(M)$ .*

Let  $W = M \times \mathbb{R}$ , then  $X = \frac{\partial}{\partial t}$  is a complete vector field on  $W$  whose flow is

$$\phi_t(p, a) = (p, a + t).$$

By Lemma 2.8, there is a linear operator  $Q : \Omega^k(W) \rightarrow \Omega^{k-1}(W)$  so that

$$\phi_1^*\omega - \omega = dQ(\omega) + Q(d\omega).$$

Let  $F : W \rightarrow N$  is a smooth homotopy between  $f$  and  $g$ , and let  $\iota : M \hookrightarrow W$  be the inclusion map  $\iota(p) = (p, 0)$ , then

$$f = F \circ \iota \quad \text{and} \quad g = F \circ \phi_1 \circ \iota,$$

It follows that for any  $\omega \in \Omega^k(N)$ ,

$$g^*\omega - f^*\omega = \iota^*\phi_1^*F^*\omega - \iota^*F^*\omega = \iota^*(dQ + Qd)F^*\omega = (d\iota^*QF^* + \iota^*QF^*d)\omega.$$

So if we denote  $h = \iota^*QF^*$ , then  $h : \Omega^k(N) \rightarrow \Omega^{k-1}(M)$  satisfies

$$g^*\omega - f^*\omega = (dh + hd)\omega,$$

i.e.  $h$  is the cochain homotopy we are looking for. □