Classical Problems of Synchronization Monitors Synchronization Examples 小生和作业

操作系统原理与设计

第6章 Processe Synchronization2(进程同步2)

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提纲

- Classical Problems of Synchronization
- 2 Monitors
- Synchronization Examples
- 4 小结和作业

Outline

- Classical Problems of Synchronization
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Classical Problems of Synchronization

- Use semaphores to solve
 - Bounded-Buffer Problem, 生产者-消费者问题(PC Problem)
 - Readers and Writers Problem, 读者-写者问题
 - Dining-Philosophers Problem ,哲学家就餐问题

Solution to Bounded-Buffer Problem 1

- N buffers, each can hold one item
- Semaphore mutex initialized to the value 1
- Semaphore full initialized to the value 0
- Semaphore empty initialized to the value N.
- The structure of the consumer process
 while (true) {
 wait (full);
 wait (mutex);
 // remove an item from buffer signal (mutex);
 signal (empty);
 // consume the removed item
 }

Sulotion to Readers-Writers Problem 1

- A data set is shared among a number of concurrent processes
 - Readers only read the data set; they do not perform any updates
 - Writers can both read and write.
- Problem allow multiple readers to read at the same time.
 Only one single writer can access the shared data at the same time.
- Shared Data
 - Data set
 - Semaphore mutex initialized to 1.
 - Semaphore wrt initialized to 1.
 - Integer readcount initialized to 0.



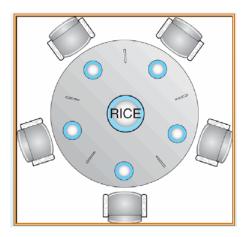
Sulotion to Readers-Writers Problem II

The structure of a writer process while (true) {
 wait(wrt);
 // writing is performed
 signal(wrt);

```
    The structure of a reader

  process
  while (true) {
     wait(mutex);
     readcount ++:
     if (readcount == 1) wait(wrt);
     signal(mutex)
        // reading is performed
     wait(mutex);
     readcount - -:
     if (readcount == 0) signal(wrt);
     signal (mutex);
```

Dining-Philosophers Problem 1



Dining-Philosophers Problem

- Shared data
 - Bowl of rice (data set)
 - Semaphore chopstick [5] initialized to 1

```
• The structure of Philosopher i:
While (true) {
    wait ( chopstick[i] );
    wait ( chopStick[ (i + 1) % 5] );
    // eat
    signal ( chopstick[i] );
    signal (chopstick[ (i + 1) % 5] );
    // think
}
```

• This solution may cause a deadlock.

Dining-Philosophers Problem III

- Several possible remedies
 - Allow at most 4 philosophers to be sitting simultaneously at the table.
 - Allow a philosopher to pick up her chopsticks only if both chopsticks are available
 - Odd philosophers pick up first her left chopstick and then her right chopstick, while even philosophers pick up first her right chopstick and then her left chopstick.
- 注: deadlock-free & starvation-free

Problems with Semaphores

• Incorrect use of semaphore operations:

```
signal (mutex) ···. wait (mutex)
```

 the mutual-exclusion requirement is violated, processes may in their CS simultaneously

```
wait (mutex) ··· wait (mutex)
```

a deadlock will occur.

```
Omitting of wait (mutex) or signal (mutex) (or both)
```

 either mutual-exclusion requirement is violated, or a deadlock will occur



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Monitors I

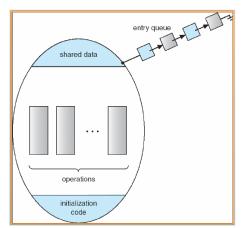
- A high-level abstraction that provides a convenient and effective mechanism for process synchronization
- Only one process may be active within the monitor at a time

```
Syntax of a monitor

monitor monitor-name
{
    // shared variable declarations
    procedure P1 (...) {...}
    ...
    procedure Pn (...) {...}
    Initialization code (....) {...}
}
```

Monitors II

Schematic view of a Monitor



Condition Variables 1

• the monitor construct is not sufficiently powerful for modeling some synchronization scheme.

```
condition x, y;
```

Two operations on a condition variable:

```
x.wait()
```

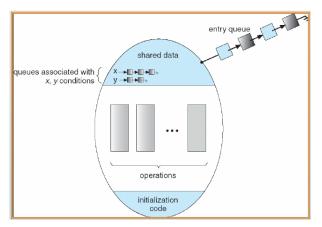
• a process that invokes the operation is suspended.

```
x.signal()
```

• resumes one of processes (if any) that invoked x.wait ()

Condition Variables II

Monitor with Condition Variables



Condition Variables III

- Problem with x.signal()
 - process P invokes x.signal, and a suspended process Q is allowed to resume its execution, then?
 - signal and wait
 - signal and continue
 - in the language Concurrent Pascal, a compromise was adopted
 - when P executes the signal operation, it immediately leaves the monitor, hence, Q is immediately resumed.

A deadlock-free solution to Dining Philosophers I

the monitor monitor DP enum { THINKING; HUNGRY, EATING} state[5]; condition self [5]; void pickup (int i) { state[i] = HUNGRY;test(i); if (state[i] != EATING) self[i].wait; void putdown (int i) { state[i] = THINKING;test((i + 4) % 5); test((i + 1) % 5);

A deadlock-free solution to Dining Philosophers II

```
void test (int i) {
   if ( (state[(i + 4) % 5] != EATING) &&
       (state[i] == HUNGRY) &&
       (state[(i + 1) \% 5] != EATING))
           state[i] = EATING;
           self[i].signal();
initialization_code() {
   for (int i = 0; i < 5; i++)
       state[i] = THINKING;
```

A deadlock-free solution to Dining Philosophers III

 Each philosopher i invokes the operations pickup() and putdown() in the following sequence:

```
dp.pickup (i)
EAT
dp.putdown (i)
```

not starvation-free

Monitor Implementation Using Semaphores 1

Variables

```
semaphore mutex; // (initially = 1) , for enter and exit monitor semaphore next; // (initially = 0) int next-count = 0;
```

Monitor Implementation Using Semaphores II

Each external procedure F will be replaced by

```
wait(mutex);
     body of F;
if (\text{next-count} > 0)
  signal(next)
else
  signal(mutex);
```

• Mutual exclusion within a monitor is ensured.

Monitor Implementation I

• For each condition variable x, we have:

```
semaphore x-sem; // (initially = \frac{0}{0})
int x-count = 0;
```

The operation x.wait can be implemented as:

Monitor Implementation II

```
x-count++;
if (next-count > 0)
    signal(next);
else
    signal(mutex);
wait(x-sem);
x-count-;
```

Monitor Implementation III

• The operation x.signal can be implemented as:

```
if (x-count > 0) {
  next-count++;
  signal(x-sem);
  wait(next);
  next-count-;
}
```

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Synchronization Examples

- Solaris
- Windows XP
- Linux
- Pthreads

Solaris Synchronization

- Implements a variety of locks to support multitasking, multithreading (including real-time threads), and multiprocessing
- Uses adaptive mutexes for efficiency when protecting data from short code segments
- Uses condition variables and readers-writers locks when longer sections of code need access to data
- Uses turnstiles to order the list of threads waiting to acquire either an adaptive mutex or reader-writer lock

Windows XP Synchronization

- Uses interrupt masks to protect access to global resources on uniprocessor systems
- Uses spinlocks on multiprocessor systems
- Also provides dispatcher objects which may act as either mutexes and semaphores
- Dispatcher objects may also provide events
 - An event acts much like a condition variable

Linux Synchronization

- before 2.6, nonpreemptive kernel
- now, fully preemptive
- Linux:
 - disables interrupts to implement short critical sections
- Linux provides:
 - semaphores
 - spin locks

Pthreads Synchronization

- Pthreads API is OS-independent
- It provides:
 - mutex locks
 - condition variables
- Non-portable extensions include:
 - read-write locks
 - spin locks

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小结

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作业

- 华夏班: 6.3, 6.11, 6.13
- 非华夏班:
 - 临界区问题的解答必须满足的三个要求是什么?
 - 7.1, 7.8

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谢谢!