

操作系统原理与设计

第 3 章 Processes (进程) 1

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提纲

多道程序技术和程序并发执行的条件

多道程序技术的难点

Serial execution of programs (程序的顺序执行)

Concurrent execution of programs (程序的并发执行)

Process Concept

the Processes

Process State

Process Control Block (PCB)

小结和作业

Outline

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Multiprogramming(多道程序) techniques

- ▶ From Simple Batch system → Multiprogramming system
 - ▶ Memory must be **shared** by multiple programs
 - ▶ CPU must be **multiplexing(复用)** by multiple programs
 - ▶ 4 basic components:
 - ▶ Process management
 - ▶ Memory management
 - ▶ I/O system management
 - ▶ file management

some easily confused terms

- ▶ In our course:
 - ▶ **Program**(程序): passive entity, usually a file containing a list of instructions stored on disk (often called an **executable file**).
 - ▶ **Tasks**(任务): a general reference
 - ▶ **Jobs**(作业): in batch system, user programs (and data) waiting to be loaded and executed
 - ▶ **Processes**(进程): a program in execution
- ▶ Usually, the term **job** and **process** are used **interchangeably**.

Difficulties of multiprogramming techniques

- ▶ 与单道相比，在多道系统中，进程之间的运行随着调度的发生而具有无序性，那么
 - ▶ **How to ensure correct concurrent?**
- ▶ Related theory:
 - ▶ **Conditions of the concurrent execution of program**
 - ▶ **Theoretical model: Precedence graph (前趋图)**
 - ▶ Analysis on the **serial** execution of programs based on precedence graph
 - ▶ Analysis on the **current** execution of programs based on precedence graph

Precedence Graph (前驱图) I

- ▶ **Goal:**

准确的描述语句、程序段、进程之间的执行次序

Definition

Precedence graph (前趋图) is a **Directed Acyclic Graph (有向无环图, DAG)**.

- ▶ **Node(结点):**

一个执行单元 (如一条语句、一个程序段或进程)

- ▶ **Edge(边, directed edge(有向边)):**

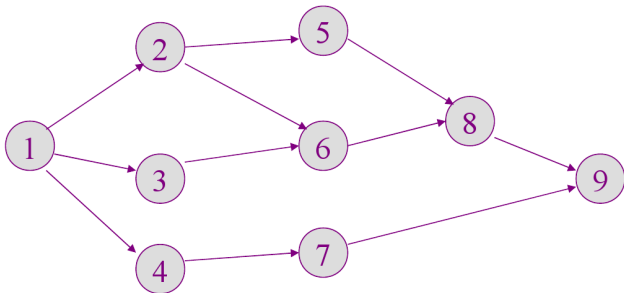
The precedence relation (前驱关系) “ \rightarrow ”,
 $\rightarrow = \{(P_i, P_j) \mid P_i \text{ 必须在 } P_j \text{ 开始执行前执行完}\}$

- ▶ If $(P_i, P_j) \in \rightarrow$, then $P_i \rightarrow P_j$

Here, P_i is called the **predecessor(前趋)** of P_j , and P_j the **subsequent(后继)** of P_i

Precedence Graph (前驱图) II

- ▶ 没有前趋的结点称为**初始结点** (initial node)
- ▶ 没有后继的结点称为**终止结点** (final node)
- ▶ 结点上使用一个**权值** (weight) 表示该结点所含的程序量或结点的执行时间
- ▶ Example:



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Serial execution of programs(程序的顺序执行)

- ▶ 一个较大的程序通常包含若干个程序段。程序在执行时，必须按照某种先后顺序逐个执行，仅当前一个程序段执行完，后一个程序段才能执行。

例如



- ▶ 其中
 - ▶ I 代表用户程序和数据的输入;
 - ▶ C 代表计算;
 - ▶ P 代表输出结果

Serial execution of programs(程序的顺序执行)

- ▶ 在一个程序段中，多条语句也存在执行顺序的问题。在下面的例子中，S1 和 S2 必须在 S3 执行前执行完。类似的，S4 必须在 S3 执行完才能执行。

- ▶ S1: $a = x + 3$

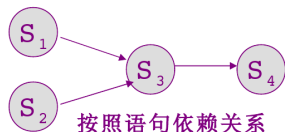
- ▶ S2: $b = y + 4$

- ▶ S3: $c = a + b$

- ▶ S4: $d = a + c$



若按指令地址顺序执行



按照语句依赖关系

程序顺序执行时的特征

1 顺序性

- ▶ 严格按照程序规定的顺序执行

2 封闭性

- ▶ 程序是在封闭的环境下运行的。独占全机资源。一旦开始运行，结果不受外界因素的影响。

3 可再现性

- ▶ 只要程序执行时的环境和初始条件相同，都将获得相同的结果。

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the Processes

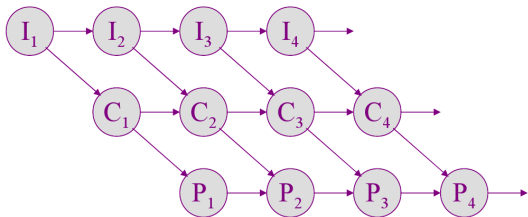
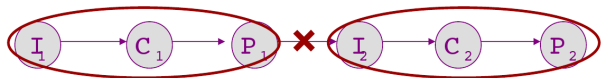
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小结和作业

Concurrent execution of programs (程序的并发执行)

- ▶ P_i 与 I_{i+1} 之间不存在内在的前趋关系



程序并发执行时的前趋图

程序并发执行时的特征

▶ 间断性

- ▶ 并发程序“执行 - - 暂停执行 - - 执行”

▶ 失去封闭性

- ▶ 由于资源共享，程序之间可能出现相互影响的现象

▶ 不可再现性

- ▶ 原因同上。
- ▶ 举例：变量 N 的共享，设某时刻 $N = n$ ，则若执行顺序为：

1. $N := N + 1; \text{print}(N); N := 0;$ N 的值依次为 $n + 1; n + 1; 0$
2. $\text{print}(N); N := 0; N := N + 1;$ N 的值依次为 $n; 0; 1$
3. $\text{print}(N); N := N + 1; N := 0;$ N 的值依次为 $n; n + 1; 0$

程序并发执行的条件 (Bernstein's conditions)

- ▶ 在上述 3 个特性中，必须防止“不可再现性”。
- ▶ 为使并发程序的执行保持“可再现性”，引入并发执行的条件。
 - ▶ **思路**：分析程序或语句的输入信息和输出信息，考察它们的相关性
 - ▶ Definitions, notation and terminology:
 - ▶ **读集** $R(p_i)$ ，表示程序 p_i 在执行时需要参考的所有变量的集合
 - ▶ **写集** $W(p_i)$ ，表示程序 p_i 在执行期间要改变的所有变量的集合
 - ▶ 1966, Bernstein: if programs p_1 and p_2 meet the following conditions, they can be executed **concurrently**, and have **reproducibility (可再现性)**
 1. If process p_i writes to a memory cell M_i , then no process p_j can read the cell M_i .
 2. If process p_i read from a memory cell M_i , then no process p_j can write to the cell M_i .
 3. If process p_i writes to a memory cell M_i , then no process p_j can write to the cell M_i .

$$R(p_1) \cap W(p_2) \cup R(p_2) \cap W(p_1) \cup W(p_1) \cap W(p_2) = \emptyset$$

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the Processes

Process State

Process Control Block (PCB)

小结和作业

the processes

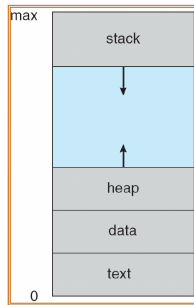
- ▶ 进程需要使用某种方法加以描述，原因
 - ▶ 进程运行的间断性，要求在进程暂停运行时记录该程序的现场，以便下次能正确的继续运行
 - ▶ 资源的共享，要求能够记录进程对资源的共享情况
 - ▶ 为保证程序“正确”的并发执行，必须将进程看成某种对象，对其进行描述并加以控制

Process Concept I

- ▶ An OS executes a variety of programs:
 - ▶ Batch system - **jobs**
 - ▶ Time-shared systems - **user programs or tasks**
 - ▶ PC - **several programs**: a word processor, a web browser, etc.
- ▶ we call all of them **process**
 - ▶ a program in execution;
 - ▶ process execution must progress in sequential fashion

A process includes:

- ▶ **text section** \leftarrow program code
- ▶ **program counter + other registers** \leftarrow current activity
- ▶ **stack** \leftarrow temporary data
- ▶ **data section** \leftarrow global variables
- ▶ **heap**



Process Concept II

COMPARE: Program vs. Process?

- ▶ Program: a passive entity (静态的)
- ▶ Process: a active entity (活动的)

进程的五大特征 I

1. 动态性

“它由创建而产生，由调度而执行，因得不到资源而暂停执行，以及由撤销而消亡”

- ▶ 具有生命期
- ▶ **最基本的特性**

2. 并发性

- ▶ 多道
- ▶ 既是进程也是 OS 的重要特征

3. 独立性

- ▶ 进程是一个能独立运行的基本单位，也是系统中独立获得资源和独立调度的基本单位。

4. 异步性

- ▶ 进程按各自独立的、不可预知的速度向前推进。
- ▶ 导致“不可再现性”
- ▶ OS 必须采取某种措施来保证各程序之间能协调运行。

5. 结构特征

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- ▶ As a process executes, it changes **state**.

State Models (状态模型)

- ▶ 最基本的“三状态”模型
- ▶ 引入“新”和“终止”态的“五状态”模型
- ▶ 引入“挂起”状态的“七状态”模型

“三状态”模型

- ▶ 三种最基本的状态

- ▶ **ready** (就绪): “万事具备, 只欠 CPU”

- ▶ ready queue

- ▶ **running** (执行)

- ▶ **waiting** (等待, also blocked(阻塞), sleeping(睡眠))

The process is waiting for some event to occur:

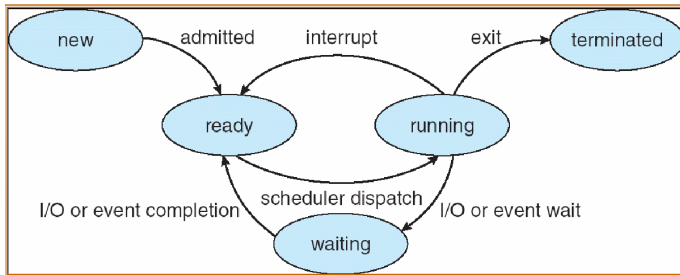
1. I/O completion
2. reception of a signal
3. resource allocation
4. etc.

- ▶ waiting queue

“五状态”模型

- ▶ Two more states is added to the “three state” model.
 - ▶ **new** (新状态): The process is being created
 - ▶ initialization, resource preallocation, etc.
 - ▶ **terminated** (终止状态): The process has finished execution, normally or abnormally.
 - ▶ removed from ready queue, but still not destroyed.
 - ▶ other process may gather some information from the terminated processes

Diagram of Process State

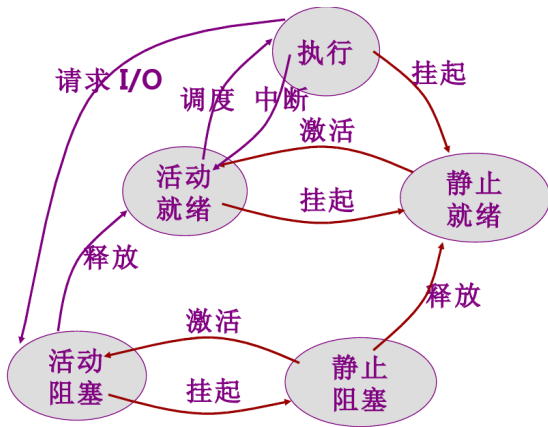


6 types of state transferring

“Seven state” model I

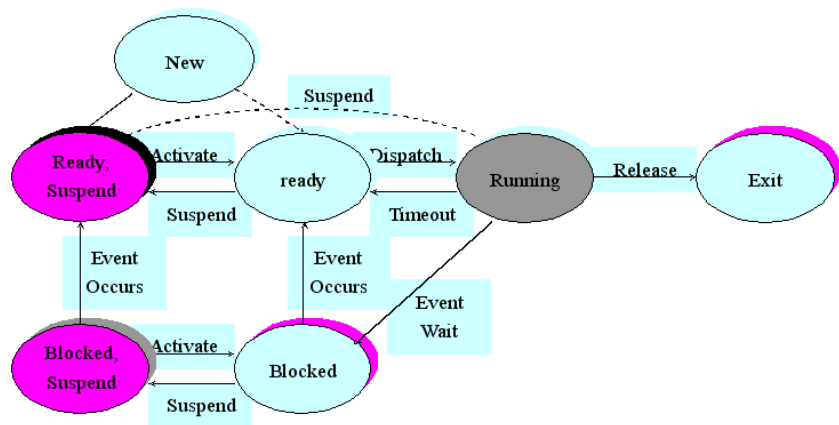
- ▶ 进程因自身内部的一些原因，无法继续运行时，暂时进入“等待”状态，当等待的原因消除后，就可以返回就绪状态；
- ▶ 但有时候会因为进程外部的一些原因，使得进程暂时不能继续运行。外部原因主要有
 - ▶ 终端用户的需要
 - ▶ 父进程的需求
 - ▶ 操作系统的需要
 - ▶ 对换的需要
 - ▶ 负载调节的需要
- ▶ 引入“挂起”状态
- ▶ “挂起”状态不是一种状态，而是**一类状态**
 - ▶ 挂起后处于静止状态：**静止就绪，静止阻塞**
 - ▶ 非挂起的活动状态：**活动就绪，活动阻塞**，还包括**执行态**
- ▶ 在状态转换中，增加了从活动状态与静止状态之间，以及静止状态内部之间的状态转换

“Seven state” model II



新增 6 种状态转换

“Seven state” model III



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the Processes

Process State

Process Control Block (PCB)

小结和作业

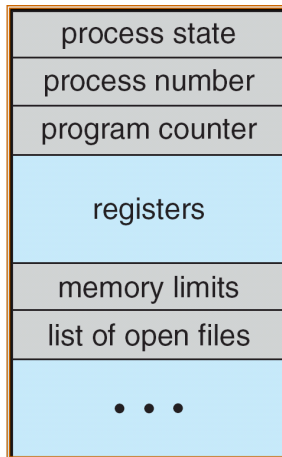
Process Control Block (进程控制块, PCB)

- ▶ Each process is represented in the OS by a PCB also called Task Control Block, TCB
是操作系统中的一种关键数据结构
 - ▶ 由操作系统进程管理模块维护
 - ▶ 常驻内存
- ▶ 操作系统根据 PCB 来控制和管理并发执行的进程

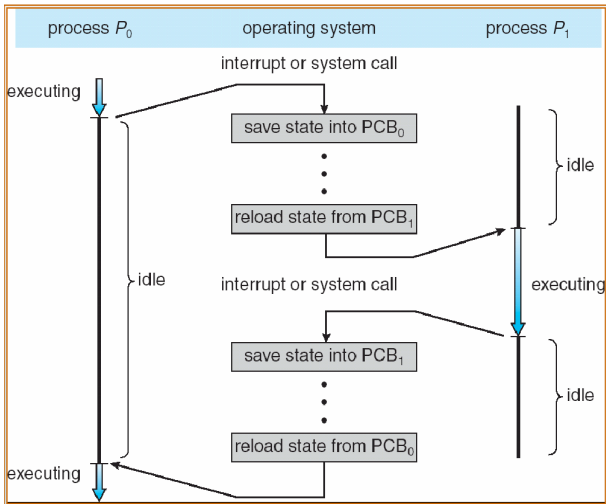
PCB 是进程存在的唯一标志

Process Control Block (进程控制块, PCB)

- ▶ Information associated with each process
 - ▶ Process **state** (...)
 - ▶ **Program counter**
 - ▶ CPU **registers**
 - ▶ CPU-scheduling information
 - ▶ Memory-management information
 - ▶ Accounting information: time used, time limit, ...
 - ▶ I/O status information



CPU Switch From Process to Process



Examples I

- ▶ 观察:
 - ▶ 数据结构
 - ▶ 状态
- ▶ struct task_struct in Linux0.11 & Linux 2.6.26
- ▶ struct OS_TCB in μ C/OS-II

```
typedef struct os_tcb {
    OS_STK *OSTCBStkPtr; /* Pointer to current top of stack */
#ifdef OS_TASK_CREATE_EXT_EN > 0
    void *OSTCBExtPtr; /* Pointer to user definable data for TCB extension */
    OS_STK *OSTCBStkBottom; /* Pointer to bottom of stack */
    INT32U OSTCBStkSize; /* Size of task stack (in number of stack elements) */
    INT16U OSTCBOpt; /* Task options as passed by OSTaskCreateExt() */
    INT16U OSTCBId; /* Task ID (0..65535) */
#endif
    struct os_tcb *OSTCBNext; /* Pointer to next TCB in the TCB list */
    struct os_tcb *OSTCBPrev; /* Pointer to previous TCB in the TCB list */
#ifdef ((OS_Q_EN > 0) && (OS_MAX_QS > 0)) || (OS_MBOX_EN > 0) ||
(OS_SEM_EN > 0) || (OS_MUTEX_EN > 0)
    OS_EVENT *OSTCBEventPtr; /* Pointer to event control block */
#endif
}
```

Examples II

```
#if ((OS_Q_EN > 0) && (OS_MAX_QS > 0)) || (OS_MBOX_EN > 0)
    void *OSTCBMsg; /* Message received from OSMboxPost() or OSQPost() */
#endif
#if (OS_VERSION >= 251) && (OS_FLAG_EN > 0) && (OS_MAX_FLAGS > 0)
#if OS_TASK_DEL_EN > 0
    OS_FLAG_NODE *OSTCBFlagNode; /* Pointer to event flag node */
#endif
    OS_FLAGS OSTCBFlagsRdy; /* Event flags that made task ready to run */
#endif
    INT16U OSTCBDly; /* Nbr ticks to delay task or, timeout waiting for event */
    INT8U OSTCBStat; /* Task status */
    INT8U OSTCBPrio; /* Task priority (0 == highest, 63 == lowest) */
    INT8U OSTCBX; /* Bit position in group corresponding to task priority (0..7) */
    INT8U OSTCBY; /* Index into ready table corresponding to task priority */
    INT8U OSTCBBitX; /* Bit mask to access bit position in ready table */
    INT8U OSTCBBitY; /* Bit mask to access bit position in ready group */
#if OS_TASK_DEL_EN > 0
    BOOLEAN OSTCBDeReq; /* Indicates whether a task needs to delete itself */
#endif
} OS_TCB;
```

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作业

- ▶ 程序的顺序执行和并发执行有什么异同之处？

- ▶ 什么是 Bernstein 条件？

- ▶ 对于下面的语句：

$S_1: a = 5 - x;$

$S_2: b = a \cdot x;$

$S_3: c = 4 \cdot x;$

$S_4: d = b + c;$

$S_5: e = d + 3$

1. 画出前趋图
 2. 证明 S_2 和 S_3 是可以并发执行的，而 S_3 和 S_4 是不能并发执行的。
- ▶ 阅读至少 2 本操作系统相关书籍，给出这些书中关于进程的定义，要列出出处。
 - ▶ 阅读 linux-0.11 的内核代码，找到其进程数据结构加以分析。说明 linux-0.11 中进程的状态及其转换关系。

谢谢!