

Mutable State

Yu Zhang

Course web site:
<http://staff.ustc.edu.cn/~yuzhang/tpl>

References

- [PFPL](#)
 - Chapter 34 Modernized Algol
 - Chapter 35 Assignable References

Yu Zhang: Mutable State 2

Basic Commands

- Commands
 - Act on *assignables* by retrieving and altering their contents
- *Pure* expressions and *impure* commands
 - Pure: not depend on assignables
 - Impure: depend on assignables
- Syntax of MA

Typ $\tau ::=$ cmd	cmd	command
Exp $e ::=$ cmd(m)	cmd m	encapsulation
Cmd $m ::=$ ret(e)	ret e	return
	bnd($e; x.m$)	bnd $x \leftarrow e; m$ sequence
	dcl($e; a.m$)	dcl $a := e$ in m new assignable
	get[a]	@ a fetch
	set[a](e)	$a := e$ assign

求e的值并封装成命令，执行该命令以作用于m中的可赋值对象，将该值代换m中的x

未求值的命令m

返回e的值而不影响可赋值对象

声明一个可赋值对象

Yu Zhang: Mutable State 3

Basic Commands

- A MA Program

Typ $\tau ::=$ cmd	cmd	command
Exp $e ::=$ cmd(m)	cmd m	encapsulation
Cmd $m ::=$ ret(e)	ret e	return
	bnd($e; x.m$)	bnd $x \leftarrow e; m$ sequence
	dcl($e; a.m$)	dcl $a := e$ in m new assignable
	get[a]	@ a fetch
	set[a](e)	$a := e$ assign

```

proc (x:nat) {
  dcl r := 1 in
  dcl a := x in
  { while ( @ a ) {
    y ← @ r
    ; z ← @ a
    ; r := (x-z+1) × y
    ; a := z-1
  }
  ; x ← @ r
  ; ret x
}
            
```

Yu Zhang: Mutable State 4

Statics of MA

- Judgements: Σ -a finite set of assignables
 - Expression typing: $\Gamma \vdash_{\Sigma} e : \tau$
 - Command formation: $\Gamma \vdash_{\Sigma} m \text{ ok}$
- Rules

$$\frac{\Gamma \vdash_{\Sigma} m \text{ ok}}{\Gamma \vdash_{\Sigma} \text{cmd}(m) : \text{cmd}} \quad \frac{\Gamma \vdash_{\Sigma} e : \text{nat}}{\Gamma \vdash_{\Sigma} \text{ret}(e) \text{ ok}} \quad \frac{\Gamma \vdash_{\Sigma, a} \text{get}[a] \text{ ok}}{\Gamma \vdash_{\Sigma, a} e : \text{nat}} \quad (34.1)$$

$$\frac{\Gamma \vdash_{\Sigma} e : \text{cmd} \quad \Gamma, x : \text{nat} \vdash_{\Sigma} m \text{ ok}}{\Gamma \vdash_{\Sigma} \text{bnd}(e; x.m) \text{ ok}} \quad \frac{\Gamma \vdash_{\Sigma, a} e : \text{nat}}{\Gamma \vdash_{\Sigma, a} \text{set}[a](e) \text{ ok}}$$

$$\frac{\Gamma \vdash_{\Sigma} e : \text{nat} \quad \Gamma \vdash_{\Sigma, a} m \text{ ok}}{\Gamma \vdash_{\Sigma} \text{dcl}(e; a.m) \text{ ok}}$$

Yu Zhang: Mutable State 5

Dynamics of MA

- Judgements
 - $e \text{ val}_{\Sigma}$: e is a value relative to Σ
 - $e \mapsto_{\Sigma} e'$: e steps to e'
 - $m \parallel \mu \text{ final}_{\Sigma}$: the state $m \parallel \mu$ is complete
 - μ : a memory mapping assignables to values
 - $m \parallel \mu \mapsto_{\Sigma} m' \parallel \mu'$: $m \parallel \mu$ steps to $m' \parallel \mu'$
- Rules

$$\frac{e \text{ val}_{\Sigma}}{\text{ret}(e) \parallel \mu \text{ final}_{\Sigma}} \quad \frac{e \mapsto_{\Sigma} e'}{\text{ret}(e) \parallel \mu \mapsto_{\Sigma} \text{ret}(e') \parallel \mu}$$

Yu Zhang: Mutable State 6

Dynamics of MA

Rules

$$\frac{e \mapsto_{\Sigma, a} e'}{\text{set}[a](e) \parallel \mu \mapsto_{\Sigma, a} \text{set}[a](e') \parallel \mu}$$

$$\frac{e \mapsto_{\Sigma} e'}{\text{bnd}(e; x.m) \parallel \mu \mapsto_{\Sigma} \text{bnd}(e'; x.m) \parallel \mu}$$

$$\frac{e \text{ val}_{\Sigma, a}}{\text{set}[a](e) \parallel \mu \otimes a \mapsto_{\Sigma, a} \text{ret}(e) \parallel \mu \otimes a \mapsto e}$$

$$\frac{e \text{ val}_{\Sigma}}{\text{bnd}(\text{cmd}(\text{ret}(e)); x.m) \parallel \mu \mapsto_{\Sigma} [e/x]m \parallel \mu}$$

$$\frac{m_1 \parallel \mu \mapsto_{\Sigma} m'_1 \parallel \mu'}{\text{bnd}(\text{cmd}(m_1); x.m_2) \parallel \mu \mapsto_{\Sigma} \text{bnd}(\text{cmd}(m'_1); x.m_2) \parallel \mu'}$$

$$\frac{e \text{ val}_{\Sigma} \quad m \parallel \mu \otimes a \mapsto e \mapsto_{\Sigma} m' \parallel \mu' \otimes a \mapsto e'}{\text{dcl}(e; a.m) \parallel \mu \mapsto_{\Sigma} \text{dcl}(e'; a.m) \parallel \mu'}$$

$$\frac{e \text{ val}_{\Sigma} \quad e' \text{ val}_{\Sigma, a}}{\text{dcl}(e; a.\text{ret}(e')) \parallel \mu \mapsto_{\Sigma} \text{ret}(e') \parallel \mu}$$

define the concept of block structure

Declarations adhere to the stack discipline

Yu Zhang: Mutable State

7

Safety of MA

Judgements

- $m \parallel \mu \text{ ok}_{\Sigma}$ is defined by the rule

$$\frac{\vdash_{\Sigma} m \text{ ok} \quad \mu : \Sigma}{m \parallel \mu \text{ ok}_{\Sigma}} \quad (34.4)$$

Preservation

- If $e \mapsto_{\Sigma} e'$ and $\vdash_{\Sigma} e : \tau$, then $\vdash_{\Sigma} e' : \tau$
- If $m \parallel \mu \mapsto_{\Sigma} m' \parallel \mu'$, with $\vdash_{\Sigma} m \text{ ok}$ and $\mu : \Sigma$, then $\vdash_{\Sigma} m' \text{ ok}$ and $\mu' : \Sigma$
- Progress
- If $\vdash_{\Sigma} e : \tau$, then either $e \text{ val}_{\Sigma}$ or there exists e' such that $e \mapsto_{\Sigma} e'$
- If $\vdash_{\Sigma} m \text{ ok}$ and $\mu : \Sigma$, then either $m \parallel \mu \text{ final}_{\Sigma}$ or $m \parallel \mu \mapsto_{\Sigma} m' \parallel \mu'$ for some μ' and m'

Yu Zhang: Mutable State

8

Assignable References: RMA

- A reference to an assignable a is a value, & a
- Reference types are compatible with
 - a scoped assignable
 - a scope-free allocation of assignable
- Scoped Assignables

Typ	$\tau ::= \text{ref}(\tau)$	$\tau \text{ ref}$	assignable
Exp	$e ::= \text{ref}[a]$	$\&a$	reference
Cmd	$m ::= \text{getref}(e)$	$*e$	contents
	$\text{setref}(e_1; e_2)$	$e_1 * e_2$	update

Yu Zhang: Mutable State

9

Scoped Assignables

Statics

$$\frac{\Gamma \vdash_{\Sigma, a-\tau} \text{ref}[a] : \text{ref}(\tau)}{\Gamma \vdash_{\Sigma} e : \text{ref}(\tau)}$$

$$\frac{\Gamma \vdash_{\Sigma} e : \text{ref}(\tau)}{\Gamma \vdash_{\Sigma} \text{getref}(e) \dot{\sim} \tau}$$

$$\frac{\Gamma \vdash_{\Sigma} e_1 : \text{ref}(\tau) \quad \Gamma \vdash_{\Sigma} e_2 : \tau}{\Gamma \vdash_{\Sigma} \text{setref}(e_1; e_2) \dot{\sim} \tau}$$

$\Gamma \vdash_{\Sigma} m \dot{\sim} \tau$
 m is a well-formed
 command returning a
 value of type τ

Dynamics

$$\frac{\text{ref}[a] \text{ val}_{\Sigma, a-\tau} \quad e \mapsto_{\Sigma} e'}{\text{getref}(e) \parallel \mu \mapsto_{\Sigma, a-\tau} \text{getref}(e') \parallel \mu}$$

$$\frac{\text{getref}(\text{ref}[a]) \parallel \mu \mapsto_{\Sigma, a-\tau} \text{get}[a] \parallel \mu}{e_1 \mapsto_{\Sigma} e'_1}$$

$$\frac{e_1 \mapsto_{\Sigma} e'_1}{\text{setref}(e_1; e_2) \parallel \mu \mapsto_{\Sigma} \text{setref}(e'_1; e_2) \parallel \mu}$$

$$\frac{\text{setref}(\text{ref}[a]; e) \parallel \mu \mapsto_{\Sigma, a-\tau} \text{set}[a](e) \parallel \mu}{\text{setref}(\text{ref}[a]; e) \parallel \mu \mapsto_{\Sigma, a-\tau} \text{set}[a](e) \parallel \mu}$$

Yu Zhang: Mutable State

10

Free Assignables

- Scope-free assignables: Heap allocation
- Dynamics: allocation of assignables **persists across transitions**
 - Transition judgement $v \Sigma \{ m \parallel \mu \} \mapsto v \Sigma' \{ m' \parallel \mu' \}$.
 - command $\text{newref}[\tau](e)$ defined by

$$\text{dcl } a := e \text{ in ret}(\&a). \quad (35.5)$$

$$\frac{\Gamma \vdash_{\Sigma} e : \tau}{\Gamma \vdash_{\Sigma} \text{newref}[\tau](e) \dot{\sim} \text{ref}(\tau)} \quad (35.6)$$

$$\frac{e \mapsto_{\Sigma} e'}{v \Sigma \{ \text{newref}[\tau](e) \parallel \mu \} \mapsto v \Sigma \{ \text{newref}[\tau](e') \parallel \mu \}} \quad (35.7a)$$

$$\frac{e \text{ val}_{\Sigma}}{v \Sigma \{ \text{newref}[\tau](e) \parallel \mu \} \mapsto v \Sigma, a-\tau \{ \text{ret}(\text{ref}[a]) \parallel \mu \otimes a \mapsto e \}} \quad (35.7b)$$

Yu Zhang: Mutable State

11