

Statics and Dynamics: $E(L^{num, str})$

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References

- [PFPL](#)
 - Chapters: $E(L^{num, str})$
 - 4 Statics, 5 Dynamics
 - 6 Type Safety
 - 7 Evaluation Dynamics
- [TAPL](#)
- [The algebra \(and calculus!\) of algebraic data types](#)

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Outline

- Syntax
- Statics
- Dynamics
- Type Safety
- Evaluation Dynamics

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Syntax

- Abstract syntax vs. concrete syntax

Typ $\tau ::=$	num str	num str	numbers strings
Exp $e ::=$	x num[n] str[s] plus($e_1; e_2$) times($e_1; e_2$) cat($e_1; e_2$) len(e) let($e_1; x.e_2$)	x n "s" $e_1 + e_2$ $e_1 * e_2$ $e_1 \sim e_2$ e let x be e_1 in e_2	variable numeral literal addition multiplication concatenation length definition

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Semantics

- Semantics: **judgements, rules**
- **Statics** (Type System)
 - Generic hypothetical judgements $\vec{x} \mid \Gamma \vdash e : \tau$
 - Rules

variables typing context: $x : \tau$

Introduction form of num type
(引入num类型的值)

$$\frac{}{\Gamma \vdash num[n] : num}$$

Elimination form of num type
(操作num类型的值)

$$\frac{\Gamma \vdash e_1 : num \quad \Gamma \vdash e_2 : num}{\Gamma \vdash plus(e_1; e_2) : num}$$

$$\frac{\Gamma \vdash e_1 : num \quad \Gamma \vdash e_2 : num}{\Gamma \vdash times(e_1; e_2) : num}$$

Typ $\tau ::=$ num
str

Exp $e ::=$ x
num[n]
str[s]
plus($e_1; e_2$)
times($e_1; e_2$)
cat($e_1; e_2$)
len(e)
let($e_1; x.e_2$)

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Semantics

- Type system

variable x is not declared in Γ

$$\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma, x : \tau_1 \vdash e_2 : \tau_2}{\Gamma \vdash let(e_1; x.e_2) : \tau_2}$$

- Unicity(唯一性): $\Gamma \vdash e : \tau$, at most one type for each exp
- Inversion for typing(定型反转)
 - If $\Gamma \vdash e : \tau$, $e = plus(e_1; e_2)$, then $\tau = num$, $\Gamma \vdash e_1 : num$, and $\Gamma \vdash \Gamma \vdash plus(e_1; e_2) : num$
- Weakening(弱化)
 - If $\Gamma \vdash e' : \tau'$, then $\Gamma, x : \tau \vdash e' : \tau'$ for any $x \notin dom(\Gamma)$ and any type τ
- Substitution(代换)
 - If $\Gamma, x : \tau \vdash e' : \tau'$ and $\Gamma \vdash e : \tau$, then $\Gamma \vdash [e/x]e' : \tau'$
- Decomposition(分解)
 - If $\Gamma \vdash [e/x]e' : \tau'$, then for each type τ such that $\Gamma \vdash e : \tau$, we have $\Gamma, x : \tau \vdash e' : \tau'$

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Dynamics: Transition Systems

• Structural dynamics (step-by-step, small step)

- Judgements

- s state, 断言s是转换系统的一个状态。
- s final, 对s state, 断言s是一个终结状态。
- s initial, 对s state, 断言s是一个初始状态。
- $s \mapsto s'$, 对s state, s' state, 断言状态s可以转换到状态 s' 。
- $s \mapsto^* s'$

$$\frac{}{s \mapsto^* s} \quad (5.1a)$$

$$\frac{s \mapsto s' \quad s' \mapsto^* s''}{s \mapsto^* s''} \quad (5.1b)$$

Dynamics: Transition Systems

- Values: $e \text{ val}$

$$\frac{}{\text{num}[n] \text{ val}}$$

$$\frac{}{\text{str}[s] \text{ val}}$$

- Transition judgment $e \mapsto e'$

$$\frac{n_1 + n_2 = n}{\text{plus}(\text{num}[n_1], \text{num}[n_2]) \mapsto \text{num}[n]} \quad \frac{s_1, s_2 = s \text{ str}}{\text{cat}(\text{str}[s_1], \text{str}[s_2]) \mapsto \text{str}[s]}$$

$$\frac{e_1 \mapsto e'_1}{\text{plus}(e_1; e_2) \mapsto \text{plus}(e'_1; e_2)} \quad \frac{e_1 \mapsto e'_1}{\text{cat}(e_1; e_2) \mapsto \text{cat}(e'_1; e_2)}$$

$$\frac{e_1 \text{ val} \quad e_2 \mapsto e'_2}{\text{plus}(e_1; e_2) \mapsto \text{plus}(e_1; e'_2)} \quad \frac{e_1 \text{ val} \quad e_2 \mapsto e'_2}{\text{cat}(e_1; e_2) \mapsto \text{cat}(e_1; e'_2)}$$

Search transitions
决定指令执行次序
Instruction transitions
基础的求值步

Included for
call-by-value,
Omitted for
call-by-name

$$\frac{e_1 \mapsto e'_1}{\text{let}(e_1; x.e_2) \mapsto \text{let}(e'_1; x.e_2)}$$

$$\frac{[e_1 \text{ val}]}{\text{let}(e_1; x.e_2) \mapsto [e_1/x]e_2}$$

Dynamics: Transition Systems

- Examples

```
let(plus(num[1]; num[2]); x.plus(plus(x; num[3]); num[4]))
  ↳ let(num[3]; x.plus(plus(x; num[3]); num[4]))
  ↳ plus(plus(num[3]; num[3]); num[4])
  ↳ plus(num[6]; num[4])
  ↳ num[10]
```

- Finality of values

- For no e , we have both $e \text{ val}$ and $e \mapsto e'$

- Determinacy

- If $e \mapsto e'$ and $e \mapsto e''$, then e' and e'' are α -equivalent

Contextual Dynamics

• Contextual Dynamics

- Judgement $\mathcal{E} \text{ ectxt}$

- The position of the next instruction step is specified by a "hole"

- Judgement $e' = \mathcal{E}\{e\}$

- filling the hole in the evaluation context \mathcal{E} with the exp. e

$$\frac{e = \mathcal{O}\{e\}}{\text{plus}(e_1; e_2) = \text{plus}(\mathcal{E}_1\{e\}; e_2)[e]}$$

Contextual Dynamics

$$\frac{e = \mathcal{E}\{e_0\} \quad e_0 \mapsto e'_0 \quad e' = \mathcal{E}\{e'_0\}}{e \mapsto e'}$$

$$\frac{\mathcal{O} \text{ ectxt}}{\mathcal{E}_1 \text{ ectxt} \quad \text{plus}(\mathcal{E}_1; e_2) \text{ ectxt}}$$

$$\frac{e_1 \text{ val} \quad \mathcal{E}_2 \text{ ectxt}}{\text{plus}(e_1; \mathcal{E}_2) \text{ ectxt}}$$

Type Safety

• A language is *safe/sound* if satisfying two theorems

- Preservation

- If $e : \tau$ and $e \mapsto e'$, then $e' : \tau$

- Progress

- If $e : \tau$, then either $e \text{ val}$, or there exists e' such that $e \mapsto e'$

Prove the theorem by *induction* on the *typing rules*

interpreter.ml

Run-time Errors

• Zero divisor

$$\frac{e_1 : \text{num} \quad e_2 : \text{num}}{\text{div}(e_1; e_2) : \text{num}}$$

- Well-typed, yet stuck!

- How to correct

- Enhance the type system ☹
- Add dynamic checks ☺

Statics $\Gamma \vdash \text{error} : \tau$

Dynamics $\frac{}{\text{error err}}$

Progress with error

$\frac{e_1 \text{ val} \quad e_2 \text{ err}}{\text{div}(e_1; e_2) \text{ err}}$

$\frac{e_1 \text{ err}}{\text{div}(e_1; e_2) \text{ err}}$

$\frac{e_1 \text{ val} \quad e_2 \text{ err}}{\text{div}(e_1; e_2) \text{ err}}$

If $e : \tau$, then either $e \text{ val}$, or $e \text{ err}$, or there exists e' such that $e \mapsto e'$

Evaluation Dynamics

- Evaluation Dynamics (big step)

- Evaluation judgment: $e \Downarrow v$

- Rules

$$\frac{}{\text{num}[n] \Downarrow \text{num}[n]} \quad \frac{}{\text{str}[s] \Downarrow \text{str}[s]}$$

$$\frac{e_1 \Downarrow \text{num}[n_1] \quad e_2 \Downarrow \text{num}[n_2] \quad n_1 + n_2 \text{ is } n \text{ nat}}{\text{plus}(e_1; e_2) \Downarrow \text{num}[n]} \quad \frac{e_1 \Downarrow \text{str}[s_1] \quad e_2 \Downarrow \text{str}[s_2] \quad s_1 \wedge s_2 = s \text{ str}}{\text{cat}(e_1; e_2) \Downarrow \text{str}[s]}$$

$$\frac{e \Downarrow \text{str}[s] \quad |s| = n \text{ nat}}{\text{len}(e) \Downarrow \text{num}[n]} \quad \frac{[e_1/x]e_2 \Downarrow v_2}{\text{let}(e_1; x. e_2) \Downarrow v_2} \quad \frac{e_1 \Downarrow v_1 \quad [v_1/x]e_2 \Downarrow v_2}{\text{let}(e_1; x. e_2) \Downarrow v_2}$$

by-name interpretation

by-value interpretation

- If $e \Downarrow v$, then $v \text{ val}$

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Structural vs. Evaluation Dynamics

- For all closed expressions (闭式) e and values v , $e \mapsto^* v$ iff $e \Downarrow v$.

- If $e \Downarrow v$, then $e \mapsto^* v$

- If $e \mapsto e'$ and $e' \Downarrow v$, then $e \Downarrow v$

- Type safety

- Cannot be proved if using evaluation dynamics

- Have an analog of the preservation property, but **no clear analog** of the **progress** property

- **Progress**: If $e: \tau$, then $e \Downarrow v$ for some v requires that **every expression evaluate to a value!**

- If E were extended to admit non-terminating expressions or operations that may cause an error, the progress would fail.

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Cost Dynamics

- Time complexity for programs

- Structural dynamics: the number of steps

- Evaluation dynamics: does not provide

- Cost dynamics

- Evaluation judgment $e \Downarrow^k v$

- Rules

$$\frac{}{\text{num}[n] \Downarrow^0 \text{num}[n]} \quad \frac{e_1 \Downarrow^{k_1} \text{num}[n_1] \quad e_2 \Downarrow^{k_2} \text{num}[n_2]}{\text{plus}(e_1; e_2) \Downarrow^{k_1+k_2+1} \text{num}[n_1+n_2]}$$

$$\frac{}{\text{str}[s] \Downarrow^0 \text{str}[s]} \quad \frac{e_1 \Downarrow^{k_1} s_1 \quad e_2 \Downarrow^{k_2} s_2}{\text{cat}(e_1; e_2) \Downarrow^{k_1+k_2+1} \text{str}[s_1 \wedge s_2]}$$

$$\frac{[e_1/x]e_2 \Downarrow^{k_2} v_2}{\text{let}(e_1; x. e_2) \Downarrow^{k_2+1} v_2} \quad \frac{e_1 \Downarrow^{k_1} v_1 \quad [v_1/x]e_2 \Downarrow^{k_2} v_2}{\text{let}(e_1; x. e_2) \Downarrow^{k_1+k_2+1} v_2}$$

by-name interpretation

by-value interpretation

- For all closed expressions e and values v , $e \Downarrow^k v$ iff $e \mapsto^k v$.

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