

## System T of Higher-Order Recursion

Yu Zhang

<http://staff.ustc.edu.cn/~yuzhang/tp/>  
yuzhang@ustc.edu.cn

## Recap

- $E(L^{\text{num, str}})$ 
  - Terms: introduction and elimination forms of a type
  - Statics: introduction and elimination rules
  - Dynamics: values, structural small-step semantics
  - Type safety: progress and preservation
- [Algebraic Data Types](#)  $L^{\times, +, \rightarrow}$ 
  - void (0), unit (1), bool (1+1), Maybe a (a+1), Either a or b (a+b), (a,b) (axb), a->b (b<sup>a</sup>)
- Useful sum types: enumerate, option<sub>r</sub>
  - Why using option<sub>r</sub>?

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2

## Recap

- Reduction strategies  $(\lambda u. \lambda v. v)((\lambda x. x x)(\lambda x. x x))$ 
  - Normal-order reduction: left-most, outer-most redex first
  - Applicative-order reduction: left-most, **inner-most** redex first

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3

## Recap

- Reduction strategies  $(\lambda u. \lambda v. v)((\lambda x. x x)(\lambda x. x x))$ 
  - Normal-order reduction: left-most, outer-most redex first
 
$$(\lambda u. \lambda v. v)((\lambda x. x x)(\lambda x. x x))$$

$$\rightarrow \lambda v. v$$
  - Applicative-order reduction: left-most, **inner-most** redex first
 
$$(\lambda u. \lambda v. v)((\lambda x. x x)(\lambda x. x x))$$

$$\rightarrow (\lambda u. \lambda v. v)((\lambda x. x x)(\lambda x. x x))$$

$$\rightarrow \dots$$

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4

## Recap

- Reduction strategies similar to (but subtly different from) **evaluation strategies** in language theories
  - **Call-by-name** (like normal-order)
    - ALGOL 60
    - arguments are not evaluated, but directly substituted into function body
  - **Call-by-need** ("memorized version" of call-by-name)
    - Haskell, R, ...
    - called "lazy evaluation", avoids repeated evaluations
  - **Call-by-value** (like applicative-order)
    - C, ...
    - called "eager evaluation"
  - ...

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5

## References

- [PFPL](#)
  - Chapters:
    - 8 Function Definitions and Values
    - 9 System T of Higher-order Recursion
- [TAPL](#)

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6

### System T: Gödel's T

- $E: L_{\text{num, str}}; T: L_{\text{nat}, \rightarrow}$  (primitive recursion)
- Syntax
 

Typ $\tau ::=$	<code>nat</code>	<code>nat</code>	<code>naturals</code>	自然数类型
	<code>arr(<math>\tau_1; \tau_2</math>)</code>	<code><math>\tau_1 \rightarrow \tau_2</math></code>	<code>function</code>	函数类型
Exp $e ::=$	<code>x</code>	<code>x</code>	<code>variable</code>	变量
introduction	<code>z</code>	<code>z</code>	<code>zero</code>	零
	<code>s(e)</code>	<code>s(e)</code>	<code>successor</code>	后继
elimination	<code>rec{<math>e_0; x.y.e_1</math>}(e)</code>	<code>rec e {z <math>\rightarrow e_0</math>; s(x) with y <math>\rightarrow e_1</math>}</code>	<code>recursion</code>	递归式
	<code>lam(<math>\tau</math>)(x.e)</code>	<code><math>\lambda (x : \tau) e</math></code>	<code>abstraction</code>	抽象
	<code>ap(<math>e_1; e_2</math>)</code>	<code><math>e_1(e_2)</math></code>	<code>application</code>	应用
- Recursor:  $\text{rec}\{e_0; x.y.e_1\}(e)$ 
  - $e$ -fold iteration of the transformation  $x.y.e_1$  starting from  $e_0$
  - $x$ : predecessor;  $y$ : result of the  $x$ -fold iteration;  $e_1$ : result of recursive call

### System T

- Recursor vs. Iterator 迭代式  $\text{iter}\{e_0; y.e_1\}(e)$ 
  - $y$ : result of the recursive call, no binding for the predecessor
- Derivability vs. Admissibility
  - Derivability (可导性)  $\Gamma \vdash_R K$ 
    - $K$  is derivable from rules  $R \cup \Gamma$
  - Admissibility (可纳性、可容许性)  $\Gamma \vDash_R J$ 
    - $\vdash_R \Gamma$  implies  $\vdash_R J$
    - if any of the hypotheses  $\Gamma$  are *not* derivable relative to  $R$ , then  $J$  is *vacuously true*
- If  $\Gamma \vdash_R J$ , then  $\Gamma \vDash_R J$ ; but the converse fails
 

$\text{succ}(\text{zero}) \text{ even} \not\vdash_{(2.8)} \text{zero odd},$	$\frac{\text{zero even}}{\text{succ}(b) \text{ even}} \quad (2.8)$
$\text{succ}(\text{zero}) \text{ even} \vdash_{(2.8)} \text{zero odd}$ valid, because the hypothesis is false	$\frac{a \text{ even}}{\text{succ}(a) \text{ odd}}$

### System T

- Statics of T
 

$\frac{\Gamma, x: \tau \vdash x: \tau}{\Gamma \vdash z: \text{nat}}$	$\frac{\Gamma, x: \tau \vdash x: \tau}{\Gamma \vdash s(e): \text{nat}}$	$\frac{\Gamma \vdash e: \text{nat} \quad \Gamma \vdash e_0: \tau \quad \Gamma, x: \text{nat}, y: \tau \vdash e_1: \tau}{\Gamma \vdash \text{rec}\{e_0; x.y.e_1\}(e): \tau}$
$\frac{\Gamma, x: \tau_1 \vdash e: \tau_2}{\Gamma \vdash \text{lam}\{\tau\}(x.e): \text{arr}(\tau_1; \tau_2)}$	$\frac{\Gamma \vdash e_1: \text{arr}(\tau_2; \tau) \quad \Gamma \vdash e_2: \tau_2}{\Gamma \vdash \text{ap}(e_1; e_2): \tau}$	
- Substitution (Admissibility)
 

If  $\Gamma \vdash e: \tau$  and  $\Gamma, x: \tau \vdash e': \tau'$ , then  $\Gamma \vdash [e/x]e': \tau'$
- Dynamics ( [...] omitted for lazy dynamics)
  - Value
 

$\frac{}{z \text{ val}}$	$\frac{[e \text{ val}]}{s(e) \text{ val}}$	$\frac{}{\text{lam}\{\tau\}(x.e) \text{ val}}$	Search transitions 决定指令执行次序 Instruction transitions 基础的求值步
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  - Transition
 

$\frac{[e_2 \text{ val}]}{\text{ap}(\text{lam}\{\tau\}(x.e); e_2) \mapsto [e_2/x]e}$	$\frac{e_1 \mapsto e'_1}{\text{ap}(e_1; e_2) \mapsto \text{ap}(e'_1; e_2)}$	$\frac{[e_1 \text{ val} \ e_2 \mapsto e'_2]}{\text{ap}(e_1; e_2) \mapsto \text{ap}(e_1; e'_2)}$
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### System T

- Dynamics ( [...] omitted for lazy dynamics)
  - Transition
 

$\frac{e \mapsto e'}{\text{rec}\{e_0; x.y.e_1\}(e) \mapsto \text{rec}\{e_0; x.y.e_1\}(e')}$
$\frac{s(e) \text{ val}}{\text{rec}\{e_0; x.y.e_1\}(z) \mapsto e_0 \quad \text{rec}\{e_0; x.y.e_1\}(s(e)) \mapsto [e, \text{rec}\{e_0; x.y.e_1\}(e)/x, y]e_1}$
  - Canonical Forms (范式)
    - If  $e: \tau$  and  $e$  val, then
      - If  $\tau = \text{nat}$ , then  $e = z$  or  $e = s(e')$  for some  $e'$
      - If  $\tau = \tau_1 \rightarrow \tau_2$ , then  $e = \lambda(x: \tau_1)e_2$  for some  $e_2$
  - Safety
    - If  $e: \tau$  and  $e \mapsto e'$ , then  $e': \tau$
    - If  $e: \tau$ , then either  $e$  val or  $e \mapsto e'$  for some  $e'$

### Examples for Recursion

- Doubling
 

```
datatype nat = z | s of nat
fun double z = z
  | double (s x) = s (s (double x))
fun double e =
  case e of
  z => z
  | s x => let val y = double x in s (s y) end
 $\lambda(e: \text{nat}) \text{rec}\{z; x.y.s(s(y))\}(e)$ 
double s(z)  $\mapsto \text{rec}\{z; x.y.s(s(y))\}(s(z))$  Application
 $\mapsto [\text{rec}\{z; x.y.s(s(y))\}(z)/y] s(s(y))$  Since s(z) val
 $= s(s(\text{rec}\{z; x.y.s(s(y))\}(z)))$  Substitution
 $\mapsto s(s(z))$  By evaluation rule of s()
```

### Expressiveness of System T

- Function  $f: \mathbb{N} \rightarrow \mathbb{N}$  is **definable** in T, iff there exists  $e_f: \text{nat} \rightarrow \text{nat}$  such that for all  $n \in \mathbb{N}$ ,  $e_f(\bar{n}) \equiv \overline{f(n)}: \text{nat}$
- Definitional equality for T,  $\Gamma \vdash e \equiv e': \tau$ 

$$\frac{\Gamma, x: \tau_1 \vdash e_2: \tau_2 \quad \Gamma \vdash e_1: \tau_1}{\Gamma \vdash \text{ap}(\text{lam}\{\tau_1\}(x.e_2); e_1) \equiv [e_1/x]e_2: \tau_2} \quad \frac{\Gamma \vdash e_0: \tau \quad \Gamma, x: \text{nat}, y: \tau \vdash e_1: \tau}{\Gamma \vdash \text{rec}\{e_0; x.y.e_1\}(z) \equiv e_0: \tau} \quad (9.5)$$

$$\frac{\Gamma \vdash e_0: \tau \quad \Gamma, x: \text{nat}, y: \tau \vdash e_1: \tau}{\Gamma \vdash \text{rec}\{e_0; x.y.e_1\}(s(e)) \equiv [e, \text{rec}\{e_0; x.y.e_1\}(e)/x, y]e_1: \tau}$$
- Doubling function  $d(n) = 2 \times n$  is definable in T by
 
$$e_d: \text{nat} \rightarrow \text{nat} \quad e_d = \lambda(x: \text{nat}) \text{rec}\{z \hookrightarrow z | s(u) \text{ with } v \hookrightarrow s(s(v))\}$$
- Proof:  $e_d(\bar{0}) \equiv \bar{0}: \text{nat}$  (basis)
 
$$\text{Assume } e_d(\bar{n}) \equiv \overline{d(n)}: \text{nat} \quad e_d(\overline{n+1}) \equiv s(s(e_d(\bar{n}))) \equiv s(s(\overline{2 \times n})) = \overline{2 \times (n+1)} = \overline{d(n+1)}$$

## Ackermann

- Well-known Ackermann function
 
$$A(0, n) = n + 1$$

$$A(m + 1, 0) = A(m, 1)$$

$$A(m + 1, n + 1) = A(m, A(m + 1, n))$$
  - not first-order primitive recursive
  - but is higher-order primitive recursive
 is incompatible with the recursor construct  $\text{rec}\{e_0; x. y. e_1\}(e)$ 
  - its argument be *deconstructed* at every step
- Ackermann is definable in T
  - $A(m + 1, n)$  iterates  $n$  times  $A(m, -)$ , starting with  $A(m, 1)$
  - Define it:  $(\text{nat} \rightarrow \text{nat}) \rightarrow \text{nat} \rightarrow \text{nat} \rightarrow \text{nat}$  as
 
$$\lambda(f: \text{nat} \rightarrow \text{nat}) \lambda(n: \text{nat}) \text{rec } n \{z \hookrightarrow \text{id}|s(x) \text{ with } g \hookrightarrow f \circ g\}$$
    - $\text{id} = \lambda(x: \text{nat})x, f \circ g = \lambda(x: \text{nat})f(g(x))$
  - $\text{it}(f)(\bar{n})(\bar{m}) \equiv f^{(n)}(\bar{m}): \text{nat}$

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13

## Ackermann

- Ackermann is definable in T
  - Define it:  $(\text{nat} \rightarrow \text{nat}) \rightarrow \text{nat} \rightarrow \text{nat} \rightarrow \text{nat}$  as
 
$$\lambda(f: \text{nat} \rightarrow \text{nat}) \lambda(n: \text{nat}) \text{rec } n \{z \hookrightarrow \text{id}|s(x) \text{ with } g \hookrightarrow f \circ g\}$$
    - $\text{id} = \lambda(x: \text{nat})x, f \circ g = \lambda(x: \text{nat})f(g(x))$
  - $\text{it}(f)(\bar{n})(\bar{m}) \equiv f^{(n)}(\bar{m}): \text{nat}$
  - Ackermann  $e_a: \text{nat} \rightarrow \text{nat} \rightarrow \text{nat}$  is
 
$$\lambda(m: \text{nat}) \text{rec } m \{z \hookrightarrow s|s(x) \text{ with } f \hookrightarrow \lambda(n: \text{nat}) \text{it}(f)(n)(f(\bar{1}))\}$$
    - $e_a(\bar{0})(\bar{n}) \equiv s(\bar{0})$
    - $e_a(\overline{m+1})(\bar{0}) \equiv e_a(\bar{m})(\bar{1})$
    - $e_a(\overline{m+1})(\overline{n+1}) \equiv e_a(\bar{m})(e_a(s(\bar{m}))(\bar{n}))$
 That is, the Ackermann function is definable in T

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14

## Primitive Mutual Recursion 原始互递归

- Using **products** to simplify primitive recursors in T
  - System T:  $\text{rec}\{e_0; x. y. e_1\}(e)$
  - Using products:  $\text{iter}\{e_0; x. e_1\}(e)$ ,
    - $x$ : the recursive result on the predecessor
    - define  $\text{rec}\{e_0; x. y. e_1\}(e)$  to be  $e' \cdot r$ 

$$e' \triangleq \text{iter}\{z, e_0; x'. \langle s(x'.l), [x'.l, x'.r/x, y]e_1 \rangle\}(e)$$
- Mutual primitive recursion
 
$$e(0) = 1$$

$$o(0) = 0$$

$$e(n + 1) = o(n)$$

$$o(n + 1) = e(n)$$
  - $\lambda(n: \text{nat}) \text{iter } n \{z \hookrightarrow \langle 1, 0 \rangle | s(b) \hookrightarrow \langle b.r, b.l \rangle\}$ 

$$e_{\text{ev}} \triangleq \lambda(n: \text{nat}) e_{\text{e0}}(n) \cdot 1$$

$$e_{\text{od}} \triangleq \lambda(n: \text{nat}) e_{\text{e0}}(n) \cdot r.$$

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15