

# Bounding the Distance between a Loop Subdivision Surface and Its Limit Mesh



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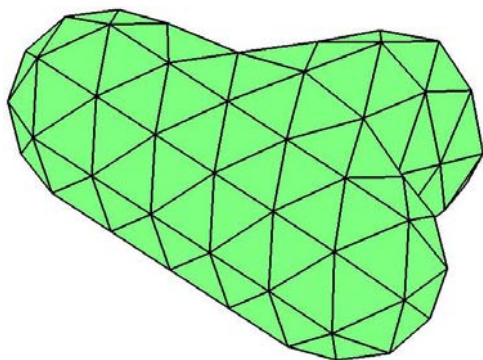
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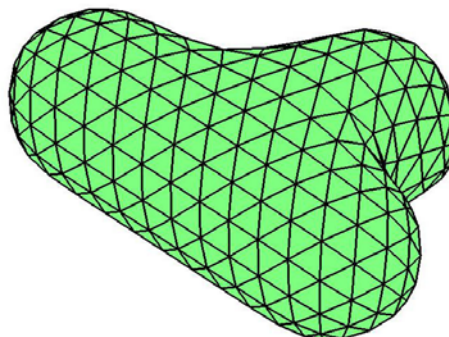
# Loop subdivision surface

## Loop subdivision surface (Loop 1987)

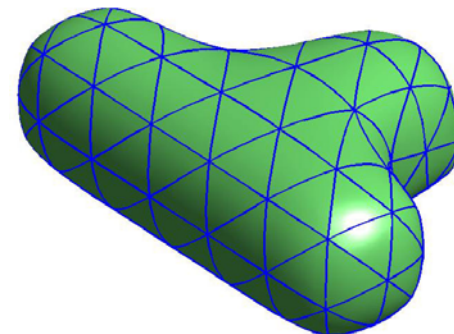
- a generalization of **quartic three-directional box spline surface** to triangular meshes of arbitrary topology
  - $C^2$  continuous except at extraordinary points
- the **limit** of a sequence of recursively refined (triangular) control meshes



initial mesh



step 1



limit surface

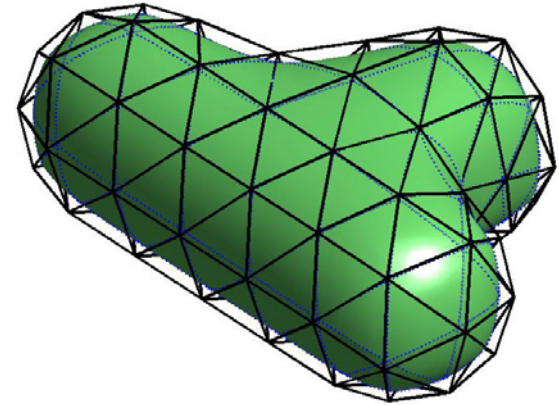


# Linear approximations

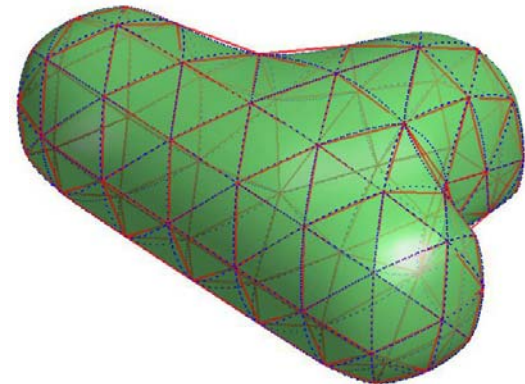
Linear approximations of a Loop surface are used in surface rendering, numerical control tool-path generation, etc

Two linear approximations:

- (refined) **control mesh**
- **limit mesh**: obtained by pushing the control points of a control mesh to their limit positions
  - ▣ It inscribes the limit surface



control mesh



limit mesh

# Problems of limit mesh approx.

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## □ Approximation error

- How to estimate the error (distance) between a Loop surface and its limit mesh?

## □ Subdivision depth estimation

- How many steps of subdivision would be necessary to satisfy a user-specified error tolerance?



# Distance (error)

Each surface patch  $\mathbf{S}$  corresponds to a **limit triangle**  $\bar{\mathbf{F}}$  in its limit mesh

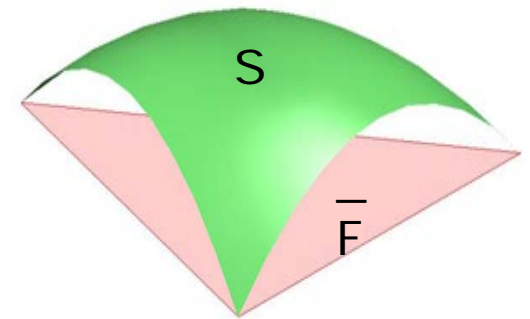
- $\bar{\mathbf{F}}$  is formed by connecting the three corners of  $\mathbf{S}$

**Distance** (error) between a patch  $\mathbf{S}$  and the limit mesh is defined as

$$\max_{(v,w) \in \Omega} \left\| \mathbf{S}(v,w) - \bar{\mathbf{F}}(v,w) \right\|$$

- $\mathbf{S}(v,w)$ : Stam's parameterization of  $\mathbf{S}$
- $\bar{\mathbf{F}}(v,w)$ : linear parameterization of  $\bar{\mathbf{F}}$
- $\Omega$  : the unit triangle

$$\Omega = \{(v,w) \mid v \in [0,1], \omega \in [0,1-v]\}$$





# Control mesh of a Loop patch

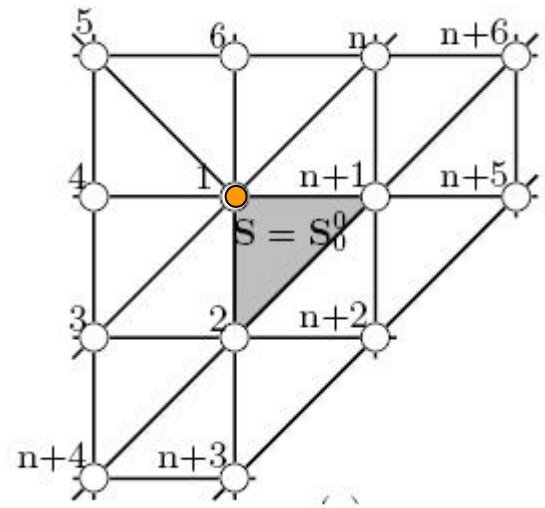
Assume: the initial control mesh has been subdivided at least once

- Each triangle face contains at most one extraordinary point

The control mesh of a Loop patch  $S$  of valence  $n$  consists of  $n+6$  control points

$$\{P_i : i = 1, 2, \dots, n+6\}$$

- $P_1$ : the **only** extraordinary point of valence  $n$



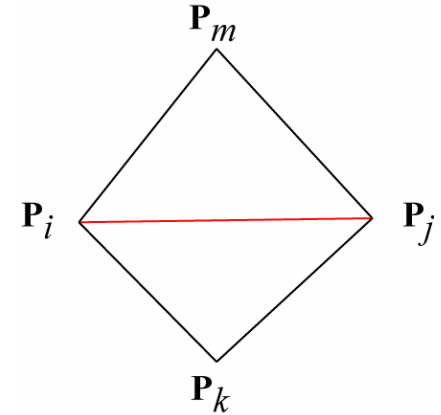
Control mesh of a Loop patch of valence  $n$



# Second order norm

Each interior edge  $\overline{\mathbf{P}_i \mathbf{P}_j}$  in the control mesh can be associated with a **mixed second difference** (MSD):

$$\mathbf{P}_i + \mathbf{P}_j - \mathbf{P}_k - \mathbf{P}_m$$



The **second order norm**  $M$  of the control mesh of Loop patch  $S$  is defined as the maximum norm of  $n+9$  MSDs:

$$\begin{aligned}
 M = \max\{ & \|\mathbf{P}_1 + \mathbf{P}_2 - \mathbf{P}_{n+1} - \mathbf{P}_3\|, \{\|\mathbf{P}_1 + \mathbf{P}_i - \mathbf{P}_{i-1} - \mathbf{P}_{i+1}\| : 3 \leq i \leq n\}, \\
 & \|\mathbf{P}_1 + \mathbf{P}_{n+1} - \mathbf{P}_n - \mathbf{P}_2\|, \|\mathbf{P}_2 + \mathbf{P}_{n+1} - \mathbf{P}_1 - \mathbf{P}_{n+2}\|, \\
 & \|\mathbf{P}_2 + \mathbf{P}_{n+2} - \mathbf{P}_{n+1} - \mathbf{P}_{n+3}\|, \|\mathbf{P}_2 + \mathbf{P}_{n+3} - \mathbf{P}_{n+2} - \mathbf{P}_{n+4}\|, \\
 & \|\mathbf{P}_2 + \mathbf{P}_{n+4} - \mathbf{P}_{n+3} - \mathbf{P}_3\|, \|\mathbf{P}_2 + \mathbf{P}_3 - \mathbf{P}_{n+4} - \mathbf{P}_1\|, \\
 & \|\mathbf{P}_{n+1} + \mathbf{P}_n - \mathbf{P}_1 - \mathbf{P}_{n+6}\|, \|\mathbf{P}_{n+1} + \mathbf{P}_{n+6} - \mathbf{P}_n - \mathbf{P}_{n+5}\|, \\
 & \|\mathbf{P}_{n+1} + \mathbf{P}_{n+5} - \mathbf{P}_{n+6} - \mathbf{P}_{n+2}\|, \|\mathbf{P}_{n+1} + \mathbf{P}_{n+2} - \mathbf{P}_{n+5} - \mathbf{P}_2\| \} \\
 = \max\{ & \|\alpha_i\| : i = 1, \dots, n+9 \} .
 \end{aligned}$$



# Our goal

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To derive a bound on the distance between a Loop patch  $\mathbf{S}(v, w)$  and its limit triangle  $\bar{\mathbf{F}}(v, w)$  as

$$\max_{(v, w) \in \Omega} \left\| \mathbf{S}(v, w) - \bar{\mathbf{F}}(v, w) \right\| \leq \beta(n)M$$

- $M$  : the second order norm of the control mesh of  $\mathbf{S}$
- $\beta(n)$  : a constant **only** depends on valence  $n$



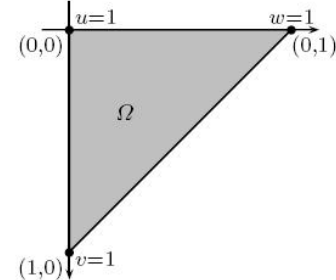
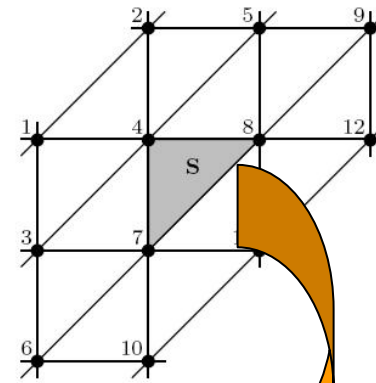


# Regular patch

$\mathbf{S}(v, w)$  is a quartic box spline patch defined by 12 control points:

$$\mathbf{S}(v, w) = \sum_{i=1}^{12} \mathbf{p}_i N_i(v, w), (v, w) \in \Omega$$

- $N_i(v, w)$  : quartic box spline basis functions

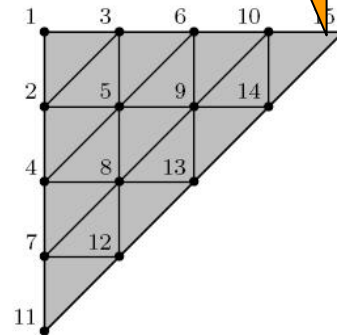


Control points of a quartic box spline patch

$\mathbf{S}(v, w)$  is also a quartic triangular Bézier patch:

$$\mathbf{S}(v, w) = \sum_{i=1}^{15} \mathbf{b}_i B_i(v, w), (v, w) \in \Omega$$

- $B_i(v, w)$  : quartic Bernstein polynomials
- $\mathbf{b}_i$  : Bézier points of  $\mathbf{S}$



$u^4$	$4u^3w$	$6u^2w^2$	$4uw^3$	$w^4$
$4u^3v$	$12u^2vw$	$12uvw^2$	$4vw^3$	
$6u^2v^2$	$12uv^2w$	$6v^2w^2$		
$4uv^3$	$4v^3w$			
$v^4$				

Bézier points of a quartic triangular Bézier patch and Bernstein polynomials



# Regular patch

Limit triangle is  $\bar{\mathbf{F}} = \{\mathbf{b}_1, \mathbf{b}_{11}, \mathbf{b}_{15}\}$ , and its linear parameterization is

$$\bar{\mathbf{F}}(v, w) = u\mathbf{b}_1 + v\mathbf{b}_{11} + w\mathbf{b}_{15}, (v, w) \in \Omega$$

- $(u, v, w)$  : barycentric system of coordinates for the unit triangle,  $u = 1 - v - w$

By the linear precision property of the Bernstein polynomials,  $\bar{\mathbf{F}}(v, w)$  can be expressed into the quartic Bézier form:

$$\bar{\mathbf{F}}(v, w) = \sum_{i=1}^{15} \bar{\mathbf{b}}_i B_i(v, w), (v, w) \in \Omega$$

- Here,

$$\bar{\mathbf{b}}_{\frac{(j+k)(j+k+1)}{2} + k + 1} = \bar{\mathbf{F}}\left(\frac{j}{4}, \frac{k}{4}\right)$$



# Regular patch

For  $(u, v) \in \Omega$ ,

$$\begin{aligned}\|\mathbf{S}(v, w) - \bar{\mathbf{F}}(v, w)\| &= \left\| \sum_{i=1}^{15} (\mathbf{b}_i - \bar{\mathbf{b}}_i) B_i(v, w) \right\| \\ &\leq \sum_{i=1}^{15} \|\mathbf{b}_i - \bar{\mathbf{b}}_i\| B_i(v, w)\end{aligned}$$

By solving some constrained minimization problems,  $\|\mathbf{b}_i - \bar{\mathbf{b}}_i\|$  can be bounded as

$$\|\mathbf{b}_i - \bar{\mathbf{b}}_i\| \leq \delta_i M, 1 \leq i \leq 15$$

- Here,  $M$  is the second order norm of  $\mathbf{S}$ , and

$$\delta_1 = \delta_{11} = \delta_{15} = 0 \quad \delta_2 = \delta_3 = \delta_7 = \delta_{10} = \delta_{12} = \delta_{14} = \frac{1}{4}$$

$$\delta_4 = \delta_6 = \delta_{13} = \frac{1}{3} \quad \delta_5 = \delta_8 = \delta_9 = \frac{5}{12}$$



# Regular patch

Thus,

$$\|\mathbf{S}(v, w) - \bar{\mathbf{F}}(v, w)\| \leq \sum_{i=1}^{15} \delta_i B_i(v, w) M = D(v, w) M$$

Here,  $D(v, w) = \sum_{i=1}^{15} \delta_i B_i(v, w) = v + w - v^2 - vw - w^2$  is called the **distance bound function** of  $\mathbf{S}(v, w)$  with respect to  $\bar{\mathbf{F}}(v, w)$ .

Since  $\max_{(v, w) \in \Omega} D(v, w) = \frac{1}{3} = D(\frac{1}{3}, \frac{1}{3})$ , we have

$$\|\mathbf{S}(v, w) - \bar{\mathbf{F}}(v, w)\| \leq \frac{1}{3} M$$



# Extraordinary patch

$\mathbf{S}$  can be partitioned into an infinite sequence of regular triangular sub-patches:

$$\{\mathbf{S}_m^k : k \geq 1, m = 1, 2, 3\}$$

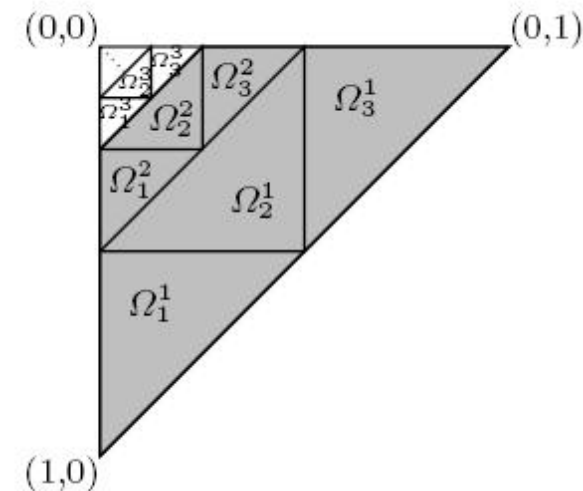
corresponding to tiles  $\Omega_m^k, k \geq 1, m = 1, 2, 3$

$\bar{\mathbf{F}}$  is partitioned into sub-triangles  $\hat{\mathbf{F}}_m^k, k \geq 1, m = 1, 2, 3$  accordingly.

For each subpatch  $\mathbf{S}_m^k$ ,

$$\left\| \mathbf{S}_m^k(v, w) - \hat{\mathbf{F}}_m^k(v, w) \right\| \leq D_m^k(v, w)M \leq \beta_m^k(n)M$$

- $D_m^k(v, w)$  : distance bound function
- $\beta_m^k(n) = \max_{(v,w) \in \Omega} D_m^k(v, w)$

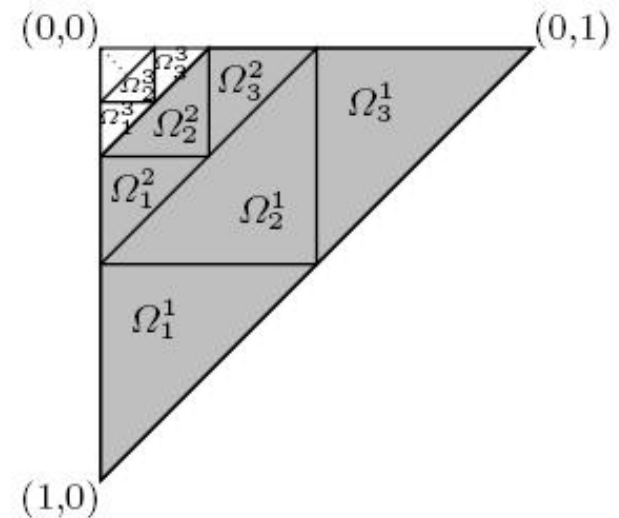




# Extraordinary patch

Let  $\beta(n) = \max_{k \geq 1, m=1,2,3} \beta_m^k(n)$ , we have

$$\max_{(v,w) \in \Omega} \|\mathbf{S}(v,w) - \bar{\mathbf{F}}(v,w)\| \leq \beta(n)M$$



For  $3 \leq n \leq 50$ , the following fact is found:

- Maximum of  $\beta_m^k(n), k \geq 1, m = 1, 2, 3$  appears in the domain

$$\bar{\Omega} = \Omega \cap \{(v,w) \mid v+w \geq \frac{1}{4}\}$$

To compute the values of  $\beta(n)$ , only four subpatches  $\mathbf{S}_1^1, \mathbf{S}_2^1, \mathbf{S}_1^2, \mathbf{S}_2^2$  are needed to be analyzed.



# Subdivision depth estimation

**Theorem** Given an error tolerance  $\varepsilon > 0$ , after

$$k = \min_{0 \leq j \leq \lambda - 1} \lambda^j l_j + j$$

steps of subdivision on the control mesh of a patch  $\mathbf{S}$ , the distance between  $\mathbf{S}$  and its level- $k$  control mesh is smaller than  $\varepsilon$ . Here

$$l_j = \left\lceil \log_{1/r_\lambda(n)} \frac{r_j(n) \max\{\beta(n), \frac{1}{3}\} M}{\varepsilon} \right\rceil, \quad 0 \leq j \leq \lambda - 1, \quad \lambda \geq 1$$

and  $r_j(n)$  is the  $j$ -step convergence rate of second order norm.

For regular Loop patches,  $k = \left\lceil \log_4 \frac{M}{3\varepsilon} \right\rceil$



# Comparison

The distance between a Loop patch  $\mathbf{S}$  and its control mesh can be bounded as:

$$\max_{(u,v) \in \Omega} \|\mathbf{S}(v, w) - \mathbf{F}(v, w)\| \leq C_\lambda(n)M, \lambda \geq 1$$

Comparison results of  $C_3(n)$  and  $\beta(n)$ ,  $3 \leq n \leq 10$

$n$	3	4	5	6	7	8	9	10
$C_3(n)$	0.872850	0.780397	0.858623	0.500000	0.875407	0.866176	0.856245	0.847476
$\beta(n)$	0.358813	0.350722	0.342499	0.333333	0.329252	0.332001	0.333880	0.335299

A limit mesh approximates a Loop surface better than the corresponding control mesh in general.





# Comparison

Set  $M = 1$ , error tolerance  $\varepsilon = 0.0001$ . Comparison results of subdivision depths for control mesh and limit mesh approximations are as follows:

$n$	3	4	5	6	7	8	9	10
control mesh	8	10	14	7	19	21	22	23
limit mesh	7	9	12	6	16	17	18	18

Limit mesh approximation has a 20% improvement over control mesh approximation in most of the cases.



# Conclusion and remark

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- We propose an approach to estimate the bound on the distance between a Loop surface and its limit mesh.
- A subdivision depth estimation formula for limit mesh approximation is derived.
- The upper bounds derived here are optimal for regular patches, but not optimal for extraordinary patches.

Thank you!

